

# Grad-Shafranov Solver using Physics-Informed Neural Networks

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### **Grad-Shafranov Equation**





### **GS Equation and Hick's Equation**





## **Grad-Shafranov Equation**

$$X\frac{\partial}{\partial X}\left(\frac{1}{X}\frac{\partial\psi}{\partial X}\right) + \frac{\partial^2\psi}{\partial Y^2} = -\mu_0\frac{R_0}{\Psi_0^2}x^2\frac{dp}{d\psi} - \frac{R_0^2}{\Psi_0^2}F\frac{dF}{d\psi}$$

2D MHD equilibrium Two free functions:

- p (Pressure)
- F (Current) -

Function:  

$$\psi = -rA_{\theta}$$
  
 $B = \nabla \times A$ 

Applications(Fusion Reactor):

- **Active Control**
- **Reactor Design**





# **Grad-Shafranov Equation**

J. P. Freidberg, "Ideal MHD" (2014) ISBN: 978-1-107-00625-6 J. Wesson, "Tokamaks" (1997) ISBN: 978-0-19-856293-1

2D MHD equilibriu Two free functions

- p (Pressure)
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e functions:  
Pressure)  
Current)  

$$X \frac{\partial}{\partial X} \left(\frac{1}{X} \frac{\partial \psi}{\partial X}\right) + \frac{\partial^2 \psi}{\partial Y^2} = -\mu_0 \frac{R_0}{\Psi_0^2} X^2 \frac{dp}{d\psi} - \frac{R_0^2}{\Psi_0^2} F \frac{dF}{d\psi}$$

$$\mu_0 \frac{R_0}{\Psi_0^2} X^2 \frac{dp}{d\psi} = -C \quad \frac{R_0^2}{\Psi_0^2} F \frac{dF}{d\psi} = -A \quad \leftarrow \text{ Solov'ev Profile}$$

$$A + C = 1$$

$$X \frac{\partial}{\partial X} \left(\frac{1}{X} \frac{\partial \psi}{\partial X}\right) + \frac{\partial^2 \psi}{\partial Y^2} = CX^2 + A \quad \Rightarrow \quad X \frac{\partial}{\partial X} \left(\frac{1}{X} \frac{\partial \psi}{\partial X}\right) + \frac{\partial^2 \psi}{\partial Y^2} = (1 - A)X^2 + A$$



### **Physics-Informed Neural Network**



 $L_{total} = \lambda_{PDE} \mathcal{L}_{PDE} + \lambda_{BC} \mathcal{L}_{BC} + (\lambda_{Data} \mathcal{L}_{Data})$ 

M. Raissi, P. Perdikaris, G. Karniadakis, J. Comp. Phys. 2019, 378:686–707 (PINN) TensorFlow <u>https://www.tensorflow.org/</u>(ML/AI platform) L. Lu, X. Meng, Z. Mao, G, Karniadakis, SIAM Rev. 2021, 63:208–228 (PINN Wrapper)



### **Data vs. Collocation Points**

#### Data

Ground Truth of the solution from experiments or numerical simulations

$$\mathcal{L}_{Data} = \frac{1}{N_{Data}} \sum_{j=1}^{N_{Data}} \left| \hat{\psi}(X, Y) - \psi_{true} \right|^2 \text{ on Data Points}$$

- **Collocation Points** 
  - Points inside a domain where residual of governing equation is calculated

$$\mathcal{L}_{DE} = \frac{1}{N_{DE}} \sum_{j=1}^{N_{DE}} |\mathcal{R}(in, sol_{nn})|^2 \text{ on } \mathcal{D}$$
$$\mathcal{R}(X, Y, \hat{\psi}) = X \frac{\partial}{\partial X} (\frac{1}{X} \frac{\partial \hat{\psi}}{\partial X}) + \frac{\partial^2 \hat{\psi}}{\partial Y^2} - \alpha - (1 - \alpha) X^2$$



### **Collocation Points**

#### **Collocation Points**



- Collocation points are where the PDE residuals are evaluated
- Possible to add data from numerical simulation or experiment



#### **Boundary Conditions**







# **Up-Down Symmetric Configurations**

#### Using 1024 Points (Dirichlet Boundary Condition)

### **Results – ITER and NSTX**





### **Error**

$$error = (\psi_{PINN} - \psi_{analytic})^2 / \psi_a^2 \text{ where}$$
$$\psi_a = \psi_{PINN} \text{ in magnetic axis}$$



#### **Results – Spheromak and FRC**







# **Shafranov Shift**

#### Using 1024 Points (Dirichlet Boundary Condition)

# NSTX with Different $\beta$





#### NSTX with Different $\beta$







# **Divertor Configuration – X-points**

**Using Cerfon's Boundary Conditions** 

### **Results – NSTX (Double and Single Null)**







# **Hyperparameter Scan**

## **Activation Functions**



#### Activation Function

 Activation functions should be differentiable to solve GS equation with PINN



## **BFGS vs. Adam**





# **Learning Rate**





## **Network Depth**



- Network Architecture
- For Adam, there is no significant improvement after depth=3
- For BFGS, it all converged nicely





# **Future Works**

#### **Future Works**



• Parametric-PINN to expand our input to included A(current/pressure profile) and shape parameters (i.e. eps, kappa, and delta)



# Thank You!



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