





$$\mathbf{B}(\mathbf{r}) = \frac{\mu_0}{4\pi} \int d^3 \tilde{r} \frac{\mathbf{J}(\tilde{\mathbf{r}}) \times (\mathbf{r} - \tilde{\mathbf{r}})}{|\mathbf{r} - \tilde{\mathbf{r}}|^3}$$
Hi  
elf-inductance & stored energy: 6D integral  
$$L = \frac{\mu_0}{4\pi I^2} \int d^3 r \int d^3 \tilde{r} \frac{\mathbf{J}(\mathbf{r}) \cdot \mathbf{J}(\tilde{\mathbf{r}})}{|\mathbf{r} - \tilde{\mathbf{r}}|}$$

S Hurwitz, M Landreman, et al, Nucl. Fusion 65, 056044 (2025)

## **Reduced models of self-force, stored energy, & critical current for** design optimization of electromagnets Matt Landreman, Siena Hurwitz, Tom Antonsen

$$\mathbf{r}(u,v,\phi) = \mathbf{r}_{c}(\phi) + \frac{au}{2}\mathbf{p}(\phi) + \frac{bv}{2}\mathbf{q}(\phi)$$

1	$\mathbf{B} = \mathbf{B}_{near} + \mathbf{B}_{far}$
	Far contribution: $ \boldsymbol{r} - \tilde{\boldsymbol{r}}  > d$
	Near contribution: $ r - \tilde{r}  < d$

$$\mathbf{B}_{0} = \frac{\mu_{0}I}{4\pi ab} \sum_{s_{u},s_{v}} s_{u}s_{v} \begin{bmatrix} G(b(v-s_{v}), a(u-s_{u})) \mathbf{q} \\ -G(a(u-s_{u}), b(v-s_{v})) \mathbf{p} \end{bmatrix}$$
$$G(x,y) = y \tan^{-1}\frac{x}{y} + \frac{x}{2} \ln\left(1 + \frac{y^{2}}{x^{2}}\right)$$

# Self-force HSX stellarato CO $L = \frac{\mu_0}{4\pi} \int d\phi \int d\tilde{\phi} \frac{1}{\sqrt{|\mathbf{r}_c - \tilde{\mathbf{r}}_c|^2 + \Delta}} \frac{d\mathbf{r}_c}{d\phi} \cdot \frac{d\tilde{\mathbf{r}}_c}{d\tilde{\phi}}$ $\Delta = a^2/\sqrt{e}$ for circular x-section, $\Delta = ab \exp\left(-\frac{25}{6} + \frac{4b}{3a} \tan^{-1}\frac{a}{b} + \frac{4a}{3b} \tan^{-1}\frac{b}{a}\right)$ **Critical current** depends on **B**, e.g. $j_c(x, y) =$ estimate the global critical current as $I_c = \min$ *x*-*section* Optimization 1.29e+04 1.07e+04 8.57e+03 6.43e+03 4.29e+03 2.14e+03 0.00 Force per length (N/m)

