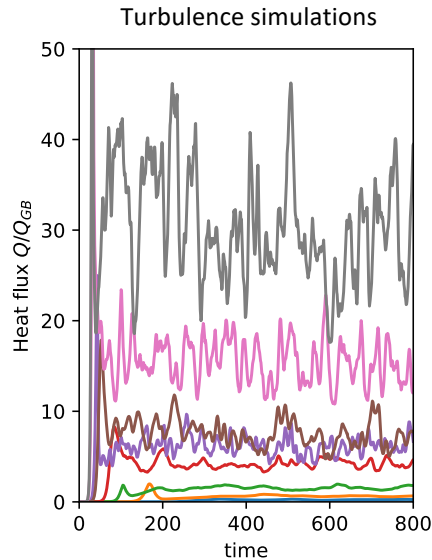
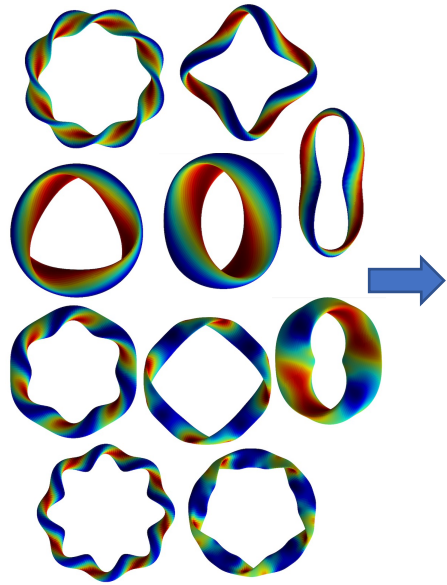
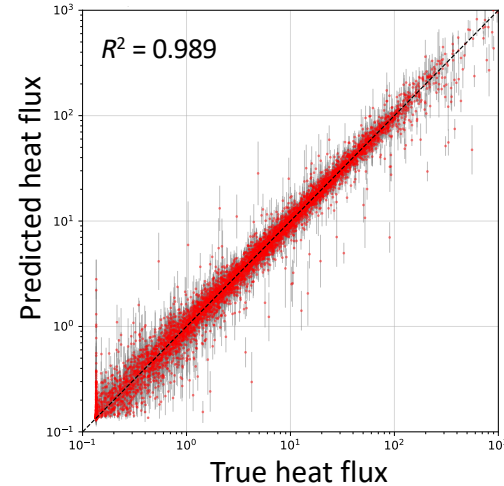


Efficient interpretable regression and classification with translation-invariance



Regression,
classification



Feature
importance

$$\text{mean}([\Theta(\mathbf{B} \times \kappa \cdot \nabla y) + 0.2] |\nabla x|^3 / B)$$

M Landreman, J Y Choi, C Alves, P Balaprakash, R M Churchill, R Conlin, G Roberg-Clark

Journal of Plasma Physics **91**, E120 (2025),

arXiv:2502.11657

Efficient interpretable regression and classification with translation-invariance

- Motivating application: turbulence in fusion plasmas
- Regression/classification method
- Results

Efficient interpretable regression and classification with translation-invariance

- Motivating application: turbulence in fusion plasmas
- Regression/classification method
- Results

Nuclear-Fusion Startup Lands \$1.8 Billion as Investors Chase Star Power



Proxima Fusion

Home Technology About Careers Press & News

Proxima Fusion Raises €130M Series A to Build World's First Stellarator-Based Fusion Power Plant in 2030s

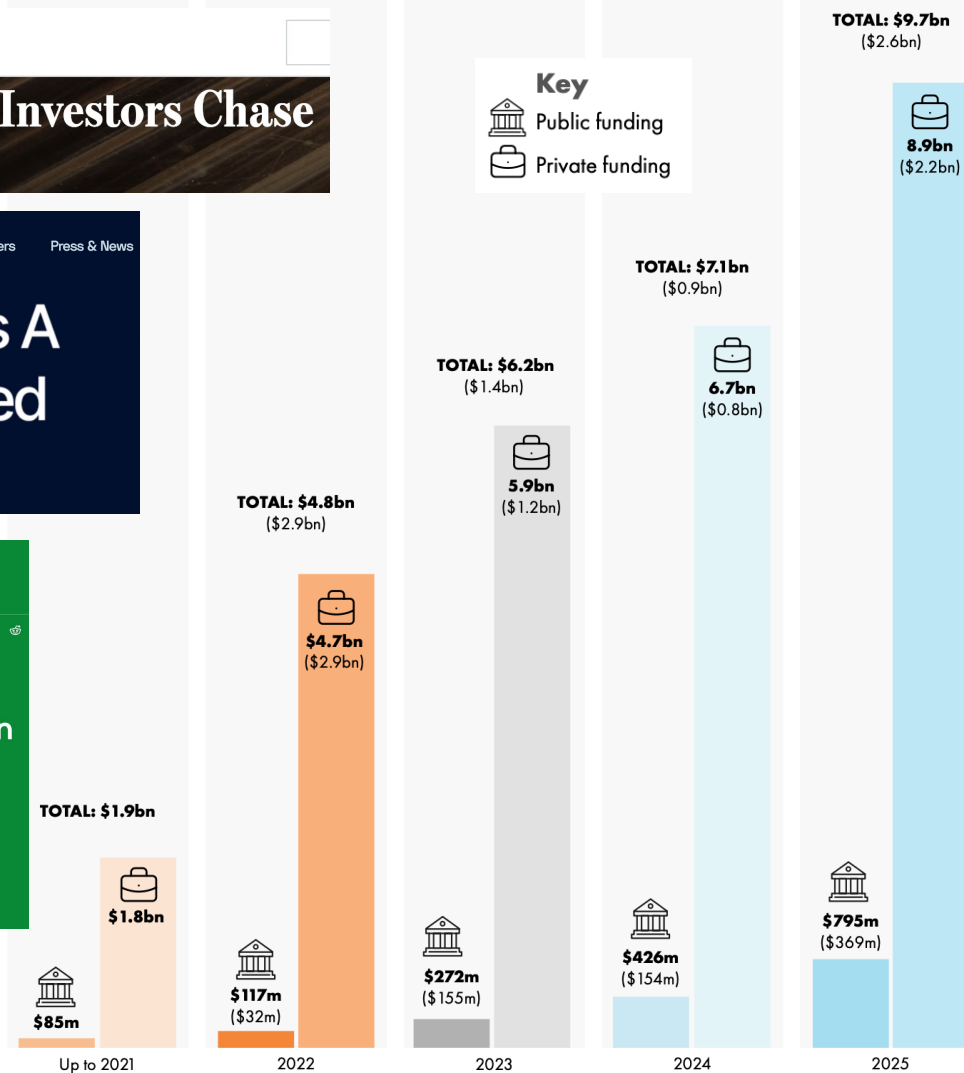


CLIMATE



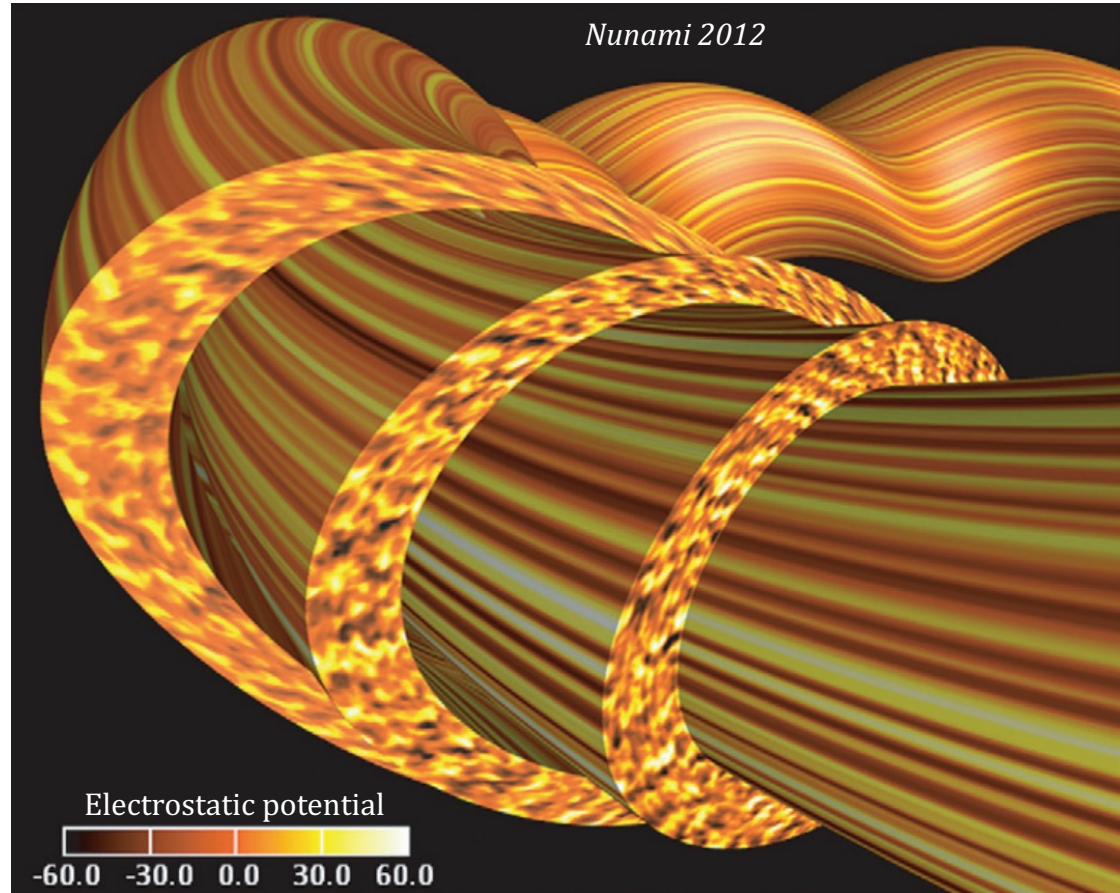
Google inks its first fusion power deal with Commonwealth Fusion Systems

Chart from Fusion Industry Association

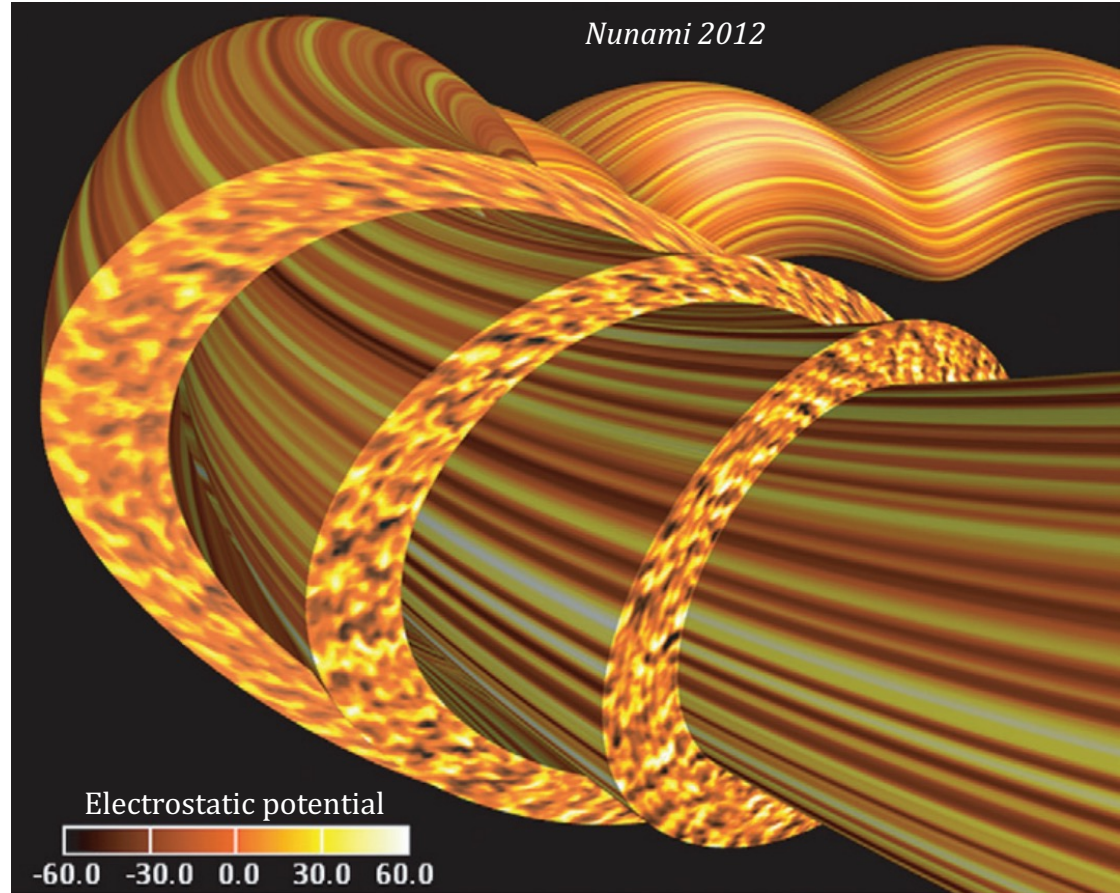
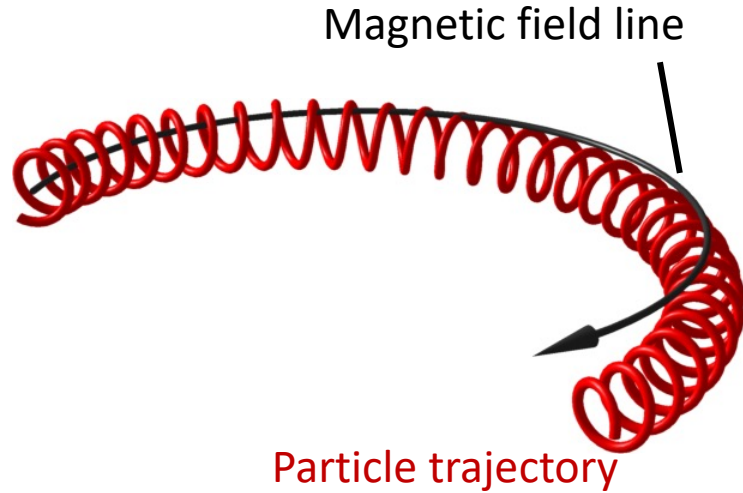


Turbulence in fusion plasmas: we want to understand & optimize

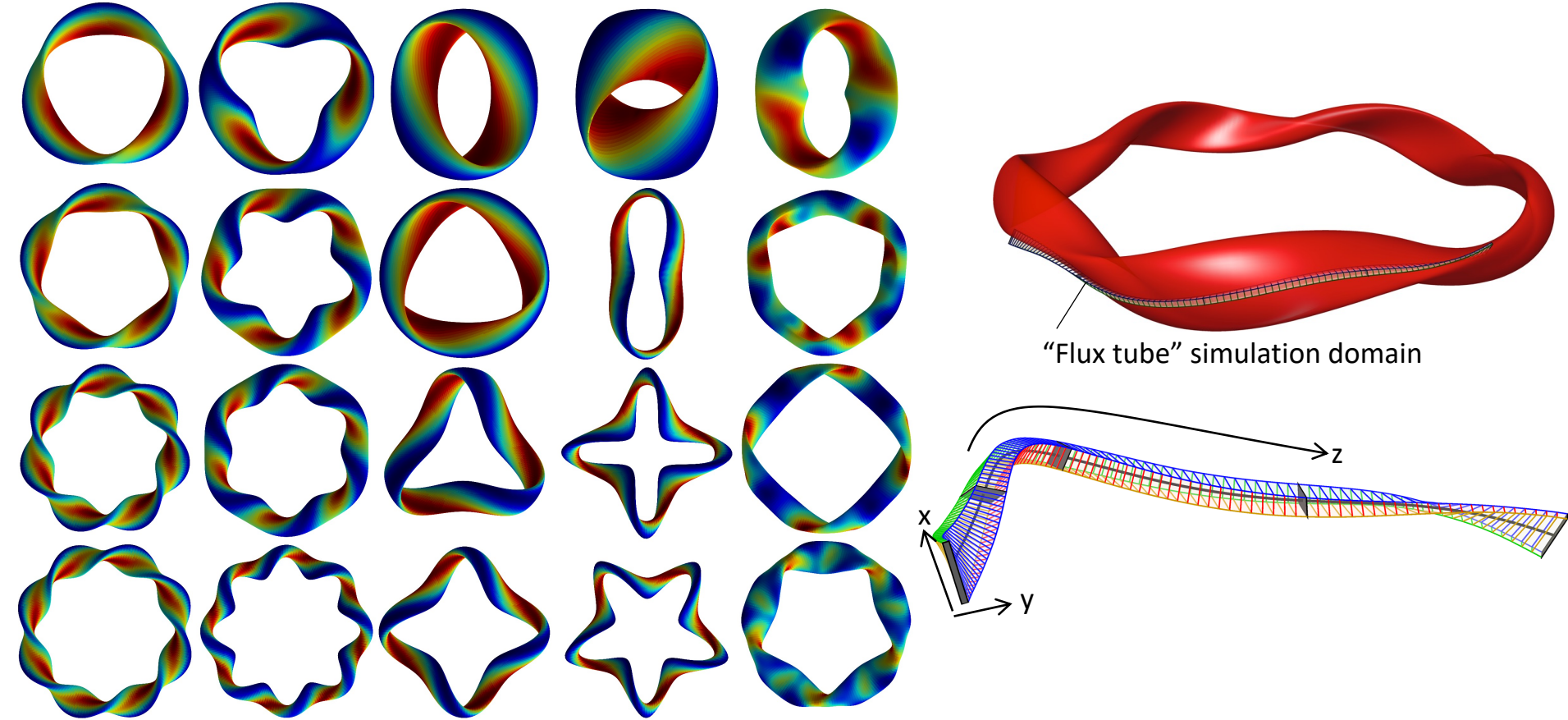
- Gradients of plasma density & temperature cause instabilities & turbulence.
- Causes heat to leak out.
- Known to depend on plasma shape, but how exactly?
- Geometry could be optimized to reduce turbulence
- Turbulence simulations: ~ 10 GPU-min to 10^6 s of CPU-hours.
- 5D + time



Turbulence in fusion plasmas is highly anisotropic due to magnetic field



Approach here: learn how turbulence depends on geometry using data
Start with direct numerical simulations of turbulence in 10^5 geometries



Equations describing the turbulence

Electrostatic potential:
$$\Phi(x, y, z, t) = \sum_{\mathbf{k}} \hat{\Phi}_{\mathbf{k}}(z, t) \exp(ik_x x + ik_y y) \quad \mathbf{k} = (k_x, k_y)$$

Ion distribution function:
$$h(x, y, z, v_{\parallel}, \mu, t) = \sum_{\mathbf{k}} \hat{h}_{\mathbf{k}}(z, v_{\parallel}, \mu, t) \exp(ik_x x + ik_y y) \quad \mu = \frac{v_{\perp}^2}{2B}$$

Gyrokinetic equation:
$$\frac{\partial \hat{h}_{\mathbf{k}}}{\partial t} + v_{\parallel} \frac{\partial \hat{h}_{\mathbf{k}}}{\partial z} - \mu \frac{\partial B}{\partial z} \frac{\partial \hat{h}_{\mathbf{k}}}{\partial v_{\parallel}} + \mathbf{v}_d \cdot \nabla \hat{h}_{\mathbf{k}} + \mathcal{N}_{\mathbf{k}} = \frac{eJ_{0,\mathbf{k}}}{T} \left(\frac{\partial \hat{\Phi}_{\mathbf{k}}}{\partial t} + i\omega_*^T \hat{\Phi}_{\mathbf{k}} \right)$$

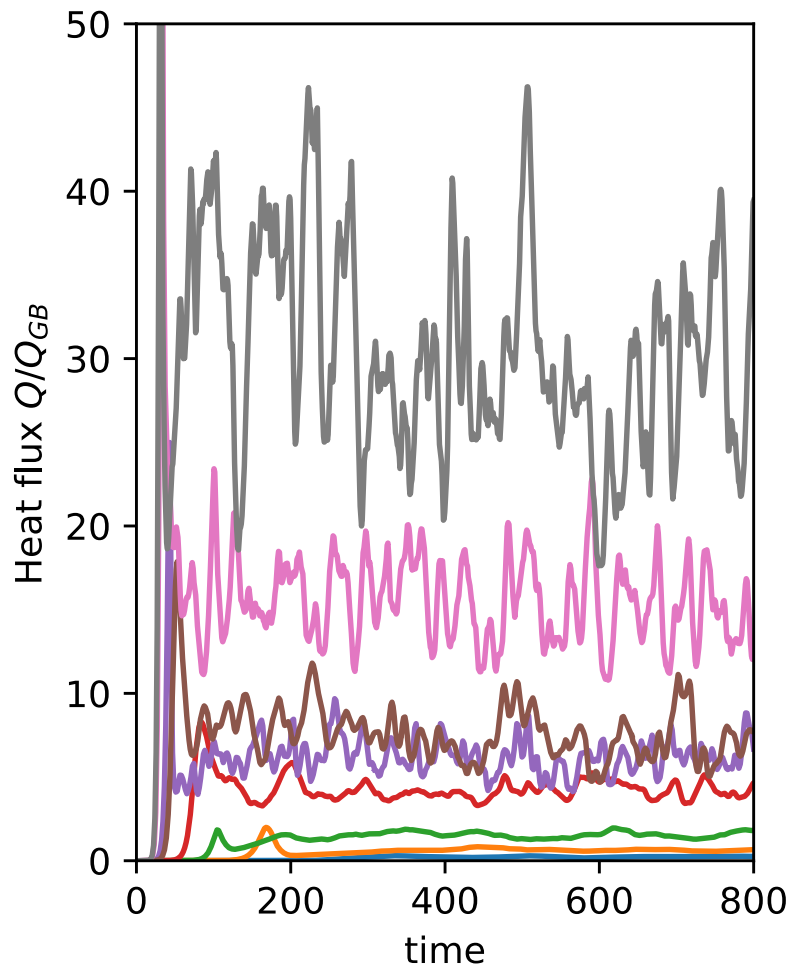
$$\mathbf{v}_d = \frac{mv_{\perp}^2}{2eB^3} \mathbf{B} \times \nabla B + \frac{mv_{\parallel}^2}{eB^2} \mathbf{B} \times (\mathbf{b} \cdot \nabla \mathbf{b}) \quad \mathbf{b} = \frac{1}{B} \mathbf{B} \quad \mathcal{N}_{\mathbf{k}} = \sum_{\mathbf{k}'} \frac{J_{0,\mathbf{k}'} \hat{\Phi}_{\mathbf{k}'} \hat{h}_{\mathbf{k}''}}{B_{\text{ref}}} (k'_y k''_x - k'_x k''_y) \quad \mathbf{k}'' = \mathbf{k} - \mathbf{k}'$$

$$J_{0,\mathbf{k}} = J_0 \left(\frac{v_{\perp} m}{eB} \sqrt{k_x^2 |\nabla x|^2 + 2k_x k_y \nabla x \cdot \nabla y + k_y^2 |\nabla y|^2} \right) \quad \omega_*^T = \frac{k_y T}{eB_{\text{ref}}} \left[\frac{1}{n} \frac{dn}{dx} + \frac{1}{T} \frac{dT}{dx} \left(\frac{mv^2}{2T} - \frac{3}{2} \right) \right]$$

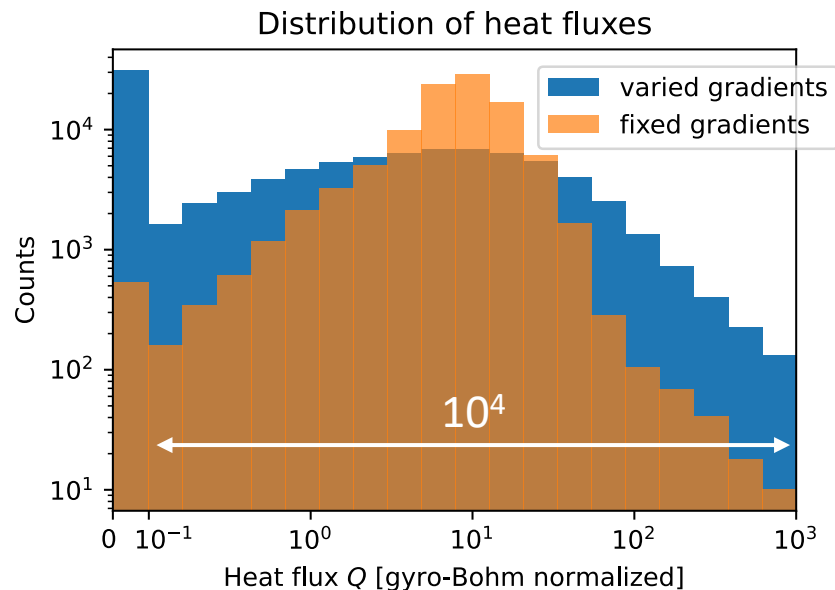
Quasineutrality:
$$\hat{\Phi}_{\mathbf{k}} \left(1 + \frac{T}{T_e} \right) - \langle \hat{\Phi}_{\mathbf{k}} \rangle \left(\frac{T}{T_e} \right) = \frac{T}{ne} \int d^3 v J_{0,\mathbf{k}} \hat{h}_{\mathbf{k}} \quad \langle \dots \rangle = \frac{\int \frac{dz}{B} (\dots)}{\int \frac{dz}{B}}$$

Heat flux:
$$Q = \sum_{\mathbf{k}} \left\langle \int d^3 v \frac{m_i v^2}{2} i k_y J_{0,\mathbf{k}} \hat{h}_{\mathbf{k}} \hat{\Phi}_{-\mathbf{k}} \right\rangle$$

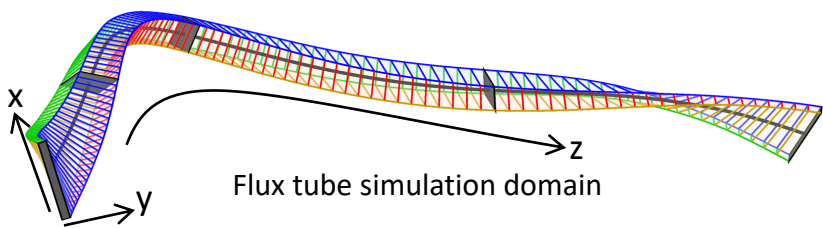
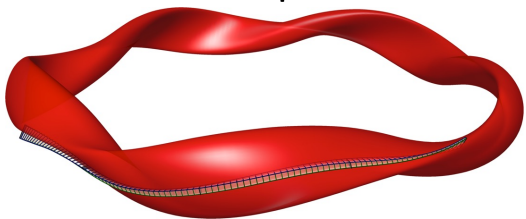
Nonlinear turbulence simulations were run in 10^5 geometries



- 1 simulation in each tube with random dT/dx and dn/dx .
- 1 simulation in each tube with $(a/T) dT/dx = 3$, $(a/n) dn/dx = 0.9$
- 8 minutes to get heat flux on 1 GPU
- 2×10^5 nonlinear simulations took < 7000 node-hours



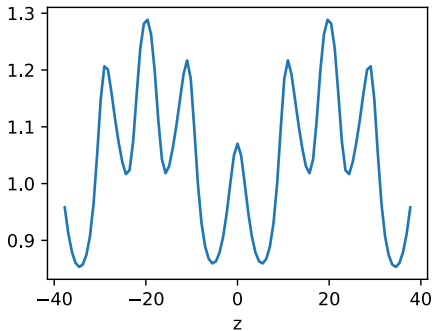
Raw feature space: 7x 1D functions that enter the turbulence simulations



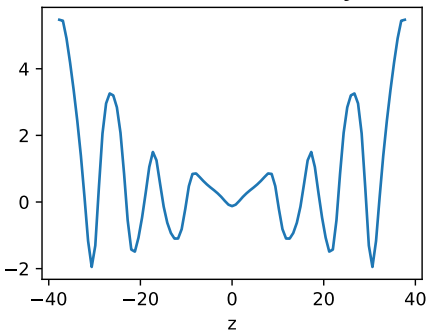
$$\mathbf{B} = B_{ref} \nabla x \times \nabla y$$

$$x = a \sqrt{\psi / \psi_{edge}}$$

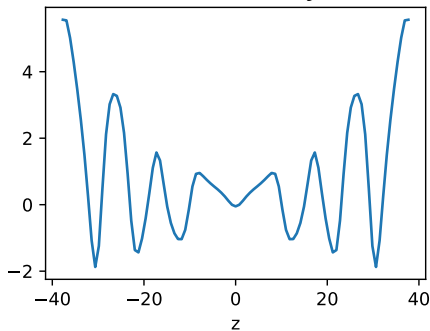
$$|B|$$



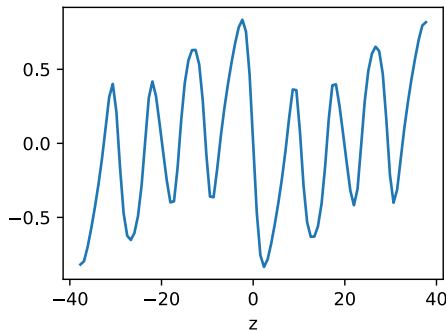
$$|B|^{-3} \mathbf{B} \times \nabla |B| \cdot \nabla y$$



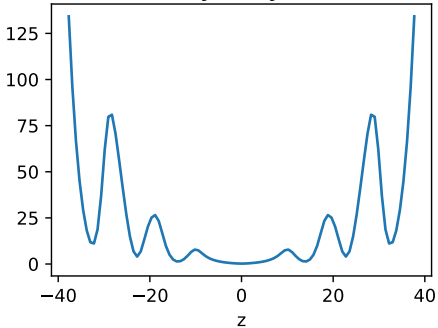
$$|B|^{-2} \mathbf{B} \times \boldsymbol{\kappa} \cdot \nabla y$$



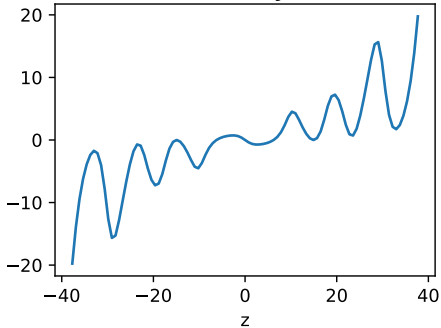
$$|B|^{-3} \mathbf{B} \times \nabla |B| \cdot \nabla x$$



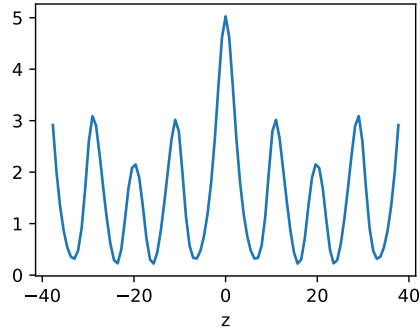
$$\nabla y \cdot \nabla y$$



$$\nabla x \cdot \nabla y$$

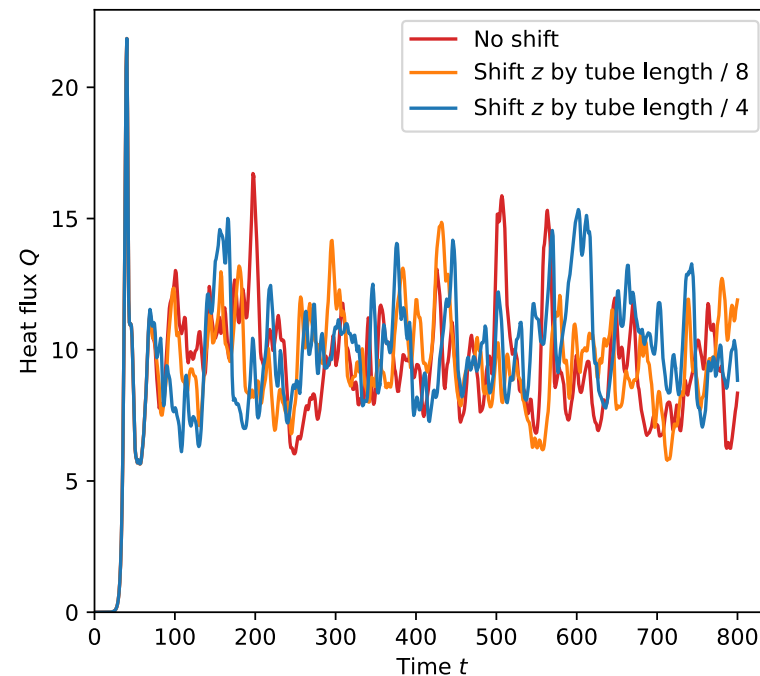
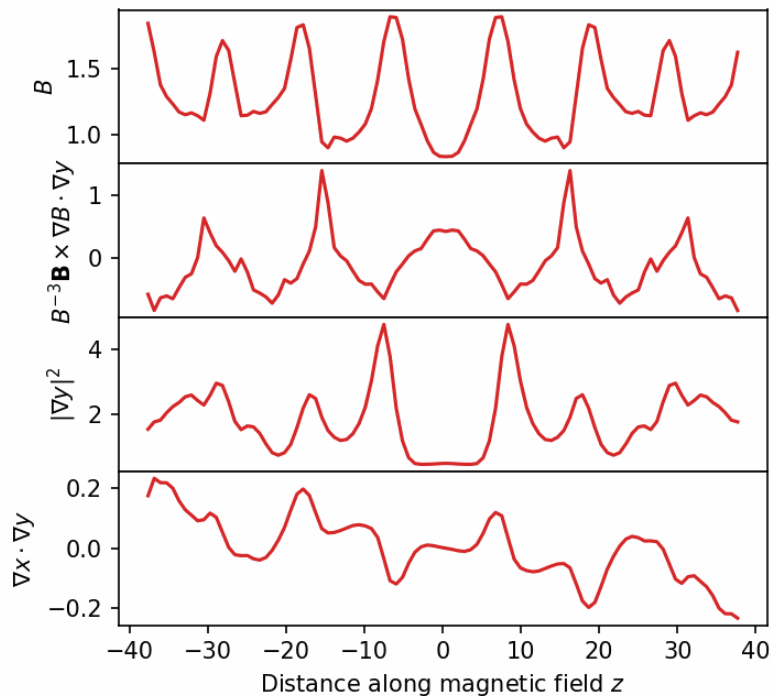


$$\nabla x \cdot \nabla x$$



Raw features should *not* be directly fed to classical regression or fully-connected neural network, since model should be translation-invariant

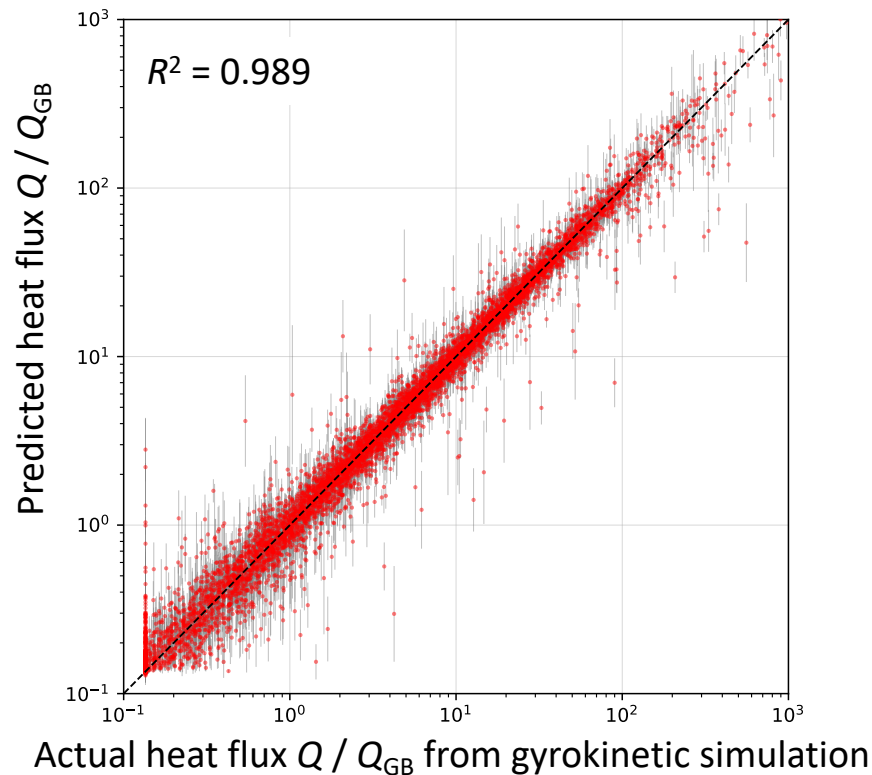
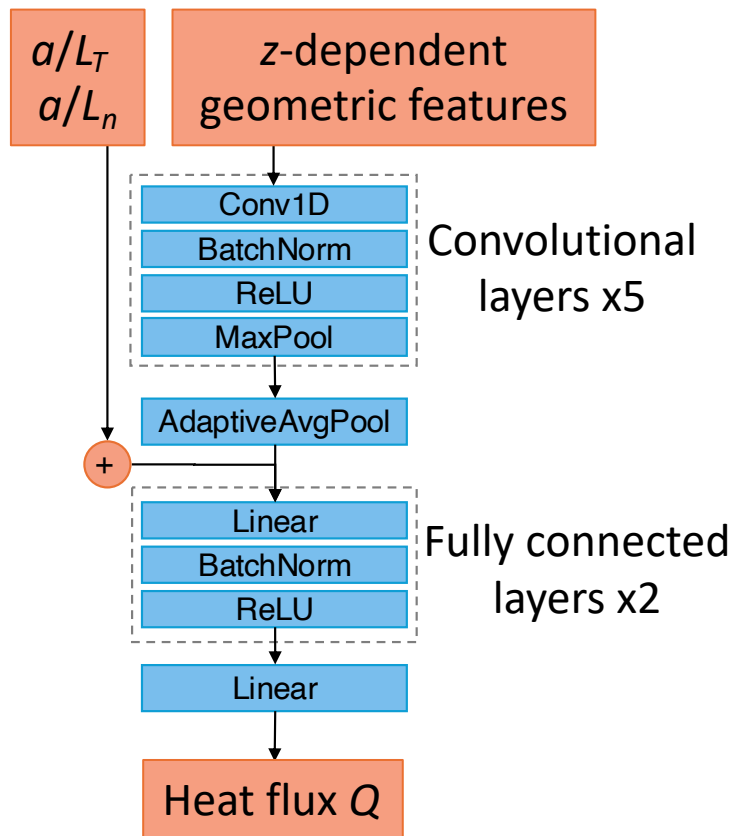
- Gyrokinetic equation, hence heat flux, is invariant under periodic translation of the raw features in z .
- Similar to computer vision, where convolutional neural networks give approximate translation-invariance.



Efficient interpretable regression and classification with translation-invariance

- Motivating application: turbulence in fusion plasmas
- Regression/classification method
- Results

Convolutional neural networks give accurate prediction of the turbulence, but lack interpretability

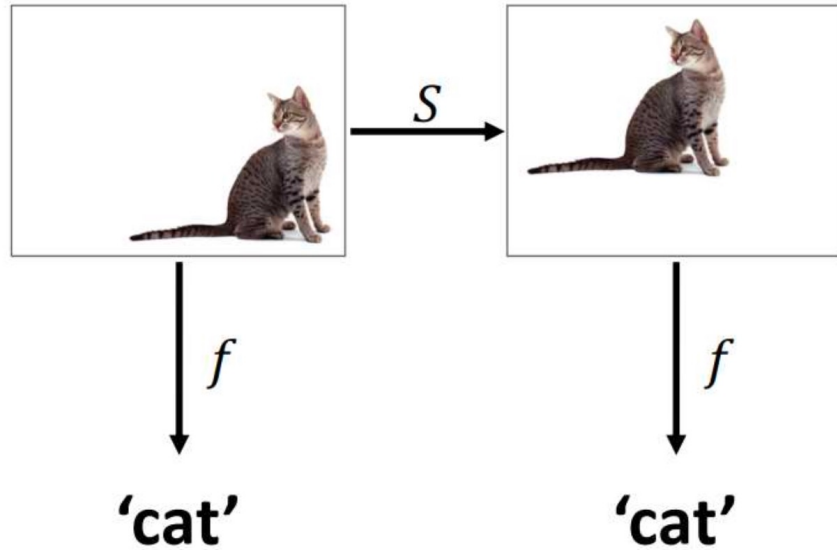


Regression/classification method to achieve invariance & interpretability

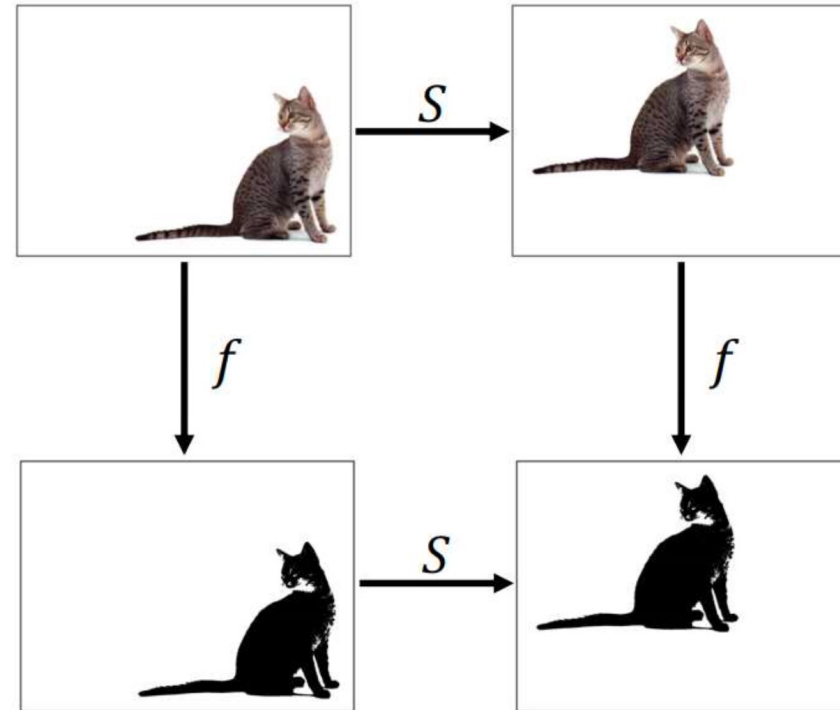
1. Define library of candidate features which are all translation-invariant. (Akin to SINDy).
 2. Apply a fast regression/classification method like decision trees to these features.
 3. Use forward sequential feature selection to pick out only the most important features.
- Guarantees that model will respect the invariance.
 - Each feature is an analytic expression $\Rightarrow$ partially interpretable.
 - Step 2 allows extra nonlinearity beyond functions in the library.
 - Method in step 2 must be fast to fit because we will fit millions of models.

To create library of candidate features, apply any translation-invariant reduction to translation-equivariant operations

Invariance



Equivariance



To create library of candidate features, apply any translation-invariant reduction to translation-equivariant operations

Start with inputs to the gyrokinetic equation:

$$F = \{B, B^{-3}\mathbf{B} \times \nabla B \cdot \nabla \mathbf{y}, B^{-2}\mathbf{B} \times \mathbf{k} \cdot \nabla \mathbf{y}, B^{-3}\mathbf{B} \times \nabla B \cdot \nabla \mathbf{x}, |\nabla \mathbf{x}|^2, \nabla \mathbf{x} \cdot \nabla \mathbf{y}, |\nabla \mathbf{y}|^2\}.$$

U = unary operations on $f(z)$: identity, df/dz , Heaviside(f), Heaviside($-f$), $\text{ReLU}(f)$, $\text{ReLU}(-f)$, $1/f$, f^2 , f/B (Jacobian), $f*B$

$C(U(F)) = U(F)$ and all pairwise products of functions in $U(F)$

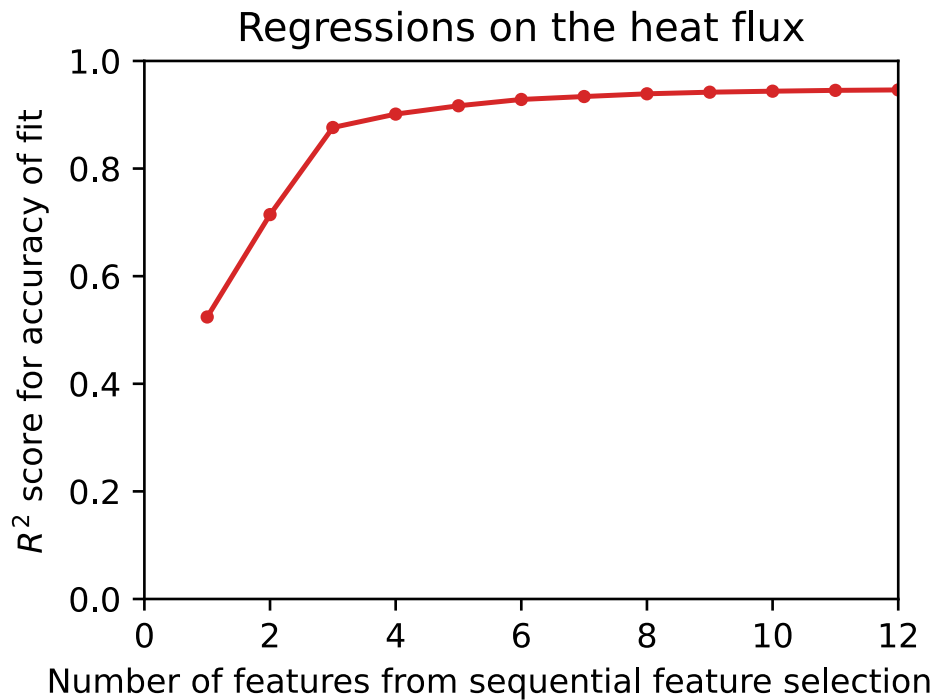
Reductions: $R = \{\text{min}, \text{max}, \text{max-min}, \text{mean}, \text{median}, \text{mean square}, \text{variance}, \text{skewness}, L_1 \text{ norm}, \text{quantiles } 0.1, 0.25, 0.75, \text{ or } 0.9, \text{abs of fft coefficients } 1-3, k_{||} \text{ with largest amplitude, expected } k_{||}, \text{count above } [-2, -1, 0, 1, 2]\}$

Features: $R(U(C(U(F)))) \Rightarrow > 1 \text{ million combinations}$

Efficient interpretable regression and classification with translation-invariance

- Motivating application: turbulence in fusion plasmas
- Regression/classification method
- Results

Forward sequential feature selection



Using decision trees (XGBoost library), varied-gradient dataset

Most important features from sequential feature selection

Regression on heat flux

Feature

R^2

a/L_T 0.524

a/L_n 0.714

$\text{mean}(\Theta(\mathbf{B} \times \kappa \cdot \nabla u) |\nabla x|^4 / B^2)$ 0.876

$\text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 |\nabla x|^8 / B^8)$ 0.901

$\text{absFFTCoeff1}(\text{ReLU}(\mathbf{B} \times \nabla B \cdot \nabla x) / B^5)$ 0.917

Classification (stability vs instability)

Feature

log-loss

a/L_T 0.361

a/L_n 0.189

$\text{mean}(\Theta(\mathbf{B} \times \nabla B \cdot \nabla u) |\nabla x|^2 / B)$ 0.122

$\text{mean}(\Theta(-\mathbf{B} \times \nabla B \cdot \nabla x) |\nabla x|^2 B)$ 0.105

$\text{mean}((\mathbf{B} \times \kappa \cdot \nabla y) / B)$ 0.094

Most important geometric feature:

The gradients are more important than any geometric feature

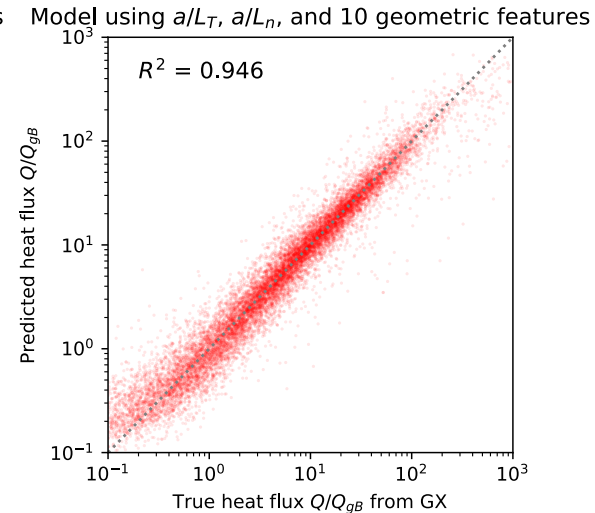
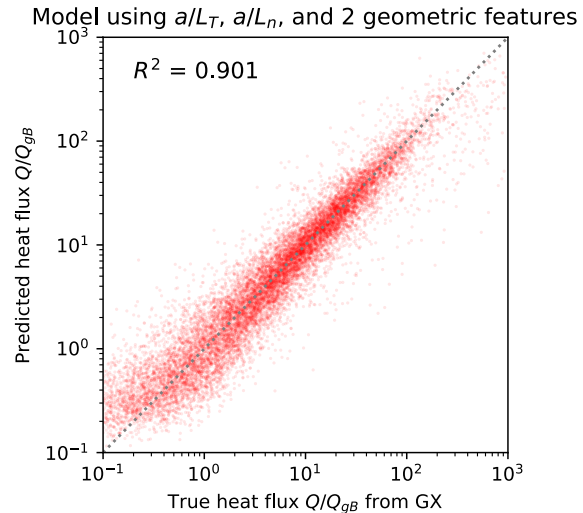
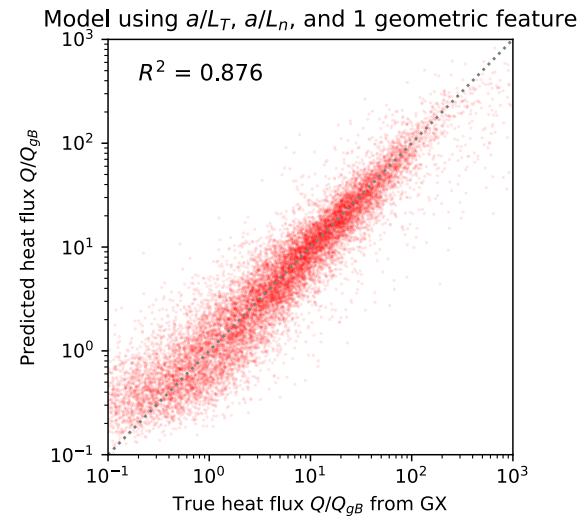
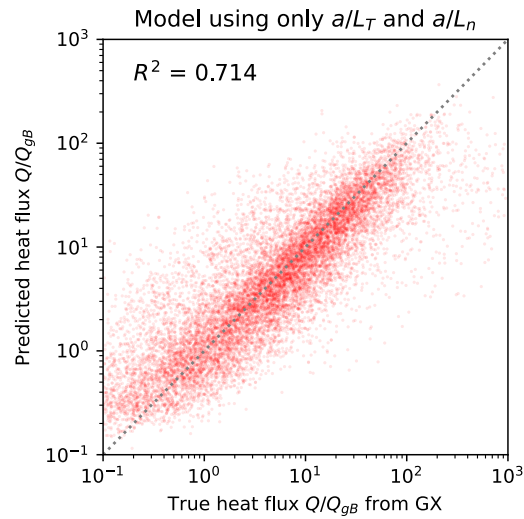
Local temperature gradient in real space $|\nabla T| = (dT/dx) |\nabla x|$, where there is bad curvature.

Similar to proposed physics inspired surrogates

larger geometric curvature (→ red drift) ⇒ Stronger damping of zonal flows ⇒ higher heat flux

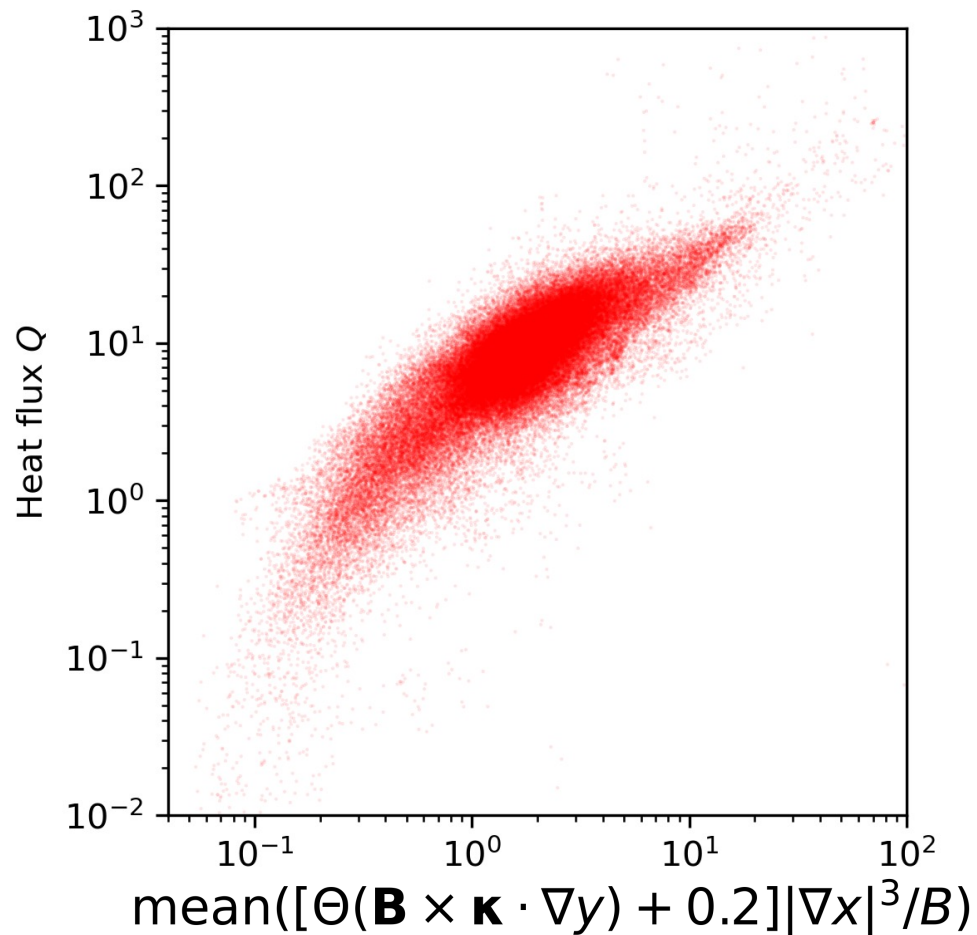
[Myrick (2010), Xanthopoulos (2014), Strohriech (2022), Goodman (2024)]

Sequential feature selection allows closer fit to the data as more geometric features are included



Performance shown on 20% held-out test data

The first geometric feature can be fine-tuned for even better fit



Summary

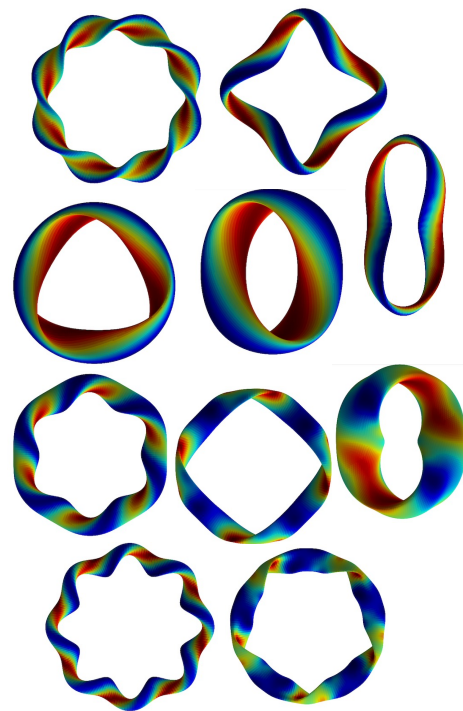
- Interpretable regression/classification guaranteeing translation-invariance.
- Library of candidate invariant features + decision trees + feature selection.
- Most important features align with recent physics-motivated surrogates.

Future work

- Use model for optimizing geometry & predicting temperature.
- Compare to saliency maps for the neural networks.
- Include physics-motivated features (e.g. linear growth rates).
- Generate data with higher physics fidelity, repeat analysis.
- Other suggestions for methods to try?



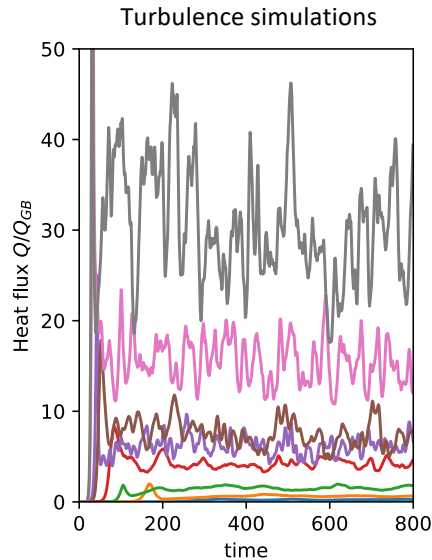
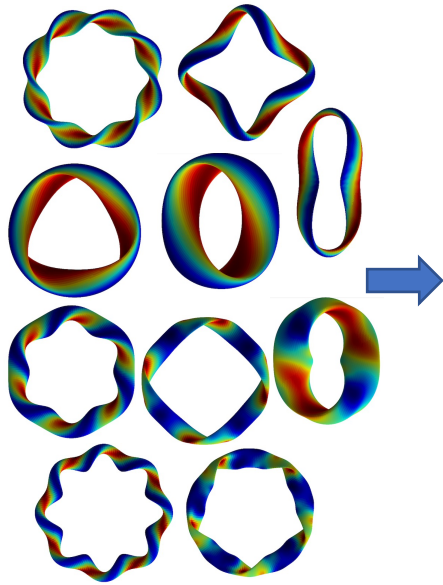
Journal of Plasma Physics 91, E120 (2025)
arXiv:2502.11657



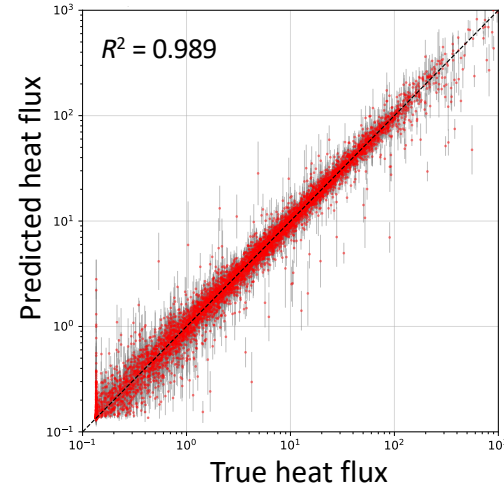
Extra slides

How does magnetic geometry affect ITG turbulence?

Insights from data & machine learning



Regression



Feature importance

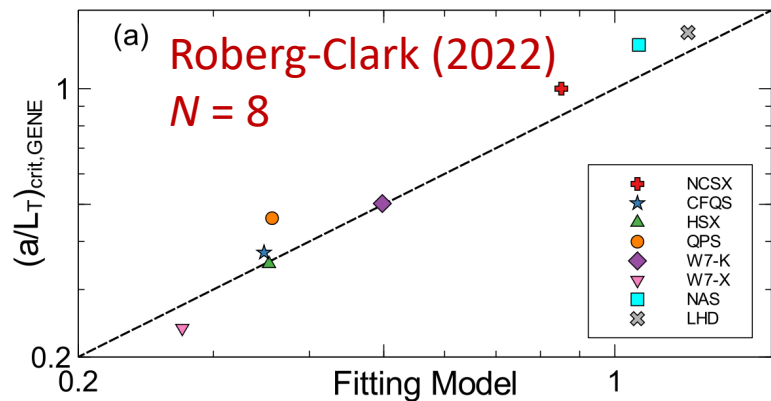
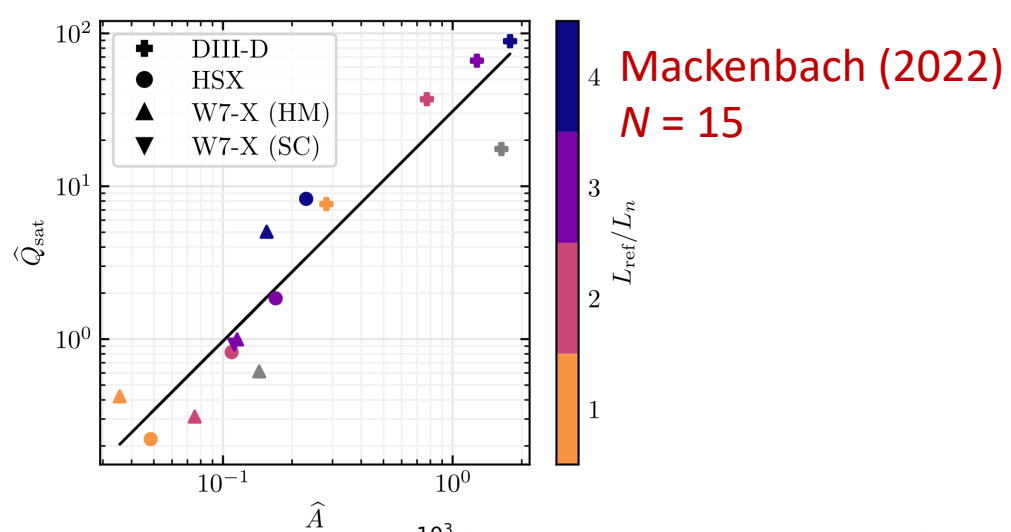
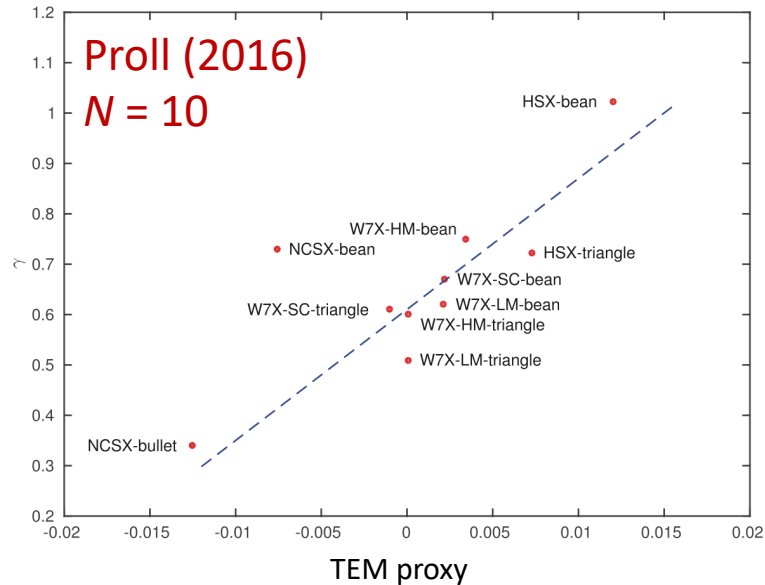
$$\begin{aligned} & \text{mean}([\Theta(\mathbf{B} \times \kappa \cdot \nabla y) + 0.2] |\nabla x|^3 / B) \\ & \text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 |\nabla x|^8 / B^8) \end{aligned}$$

M Landreman, J Y Choi, C Alves, P Balaprakash, R M Churchill, R Conlin, G Roberg-Clark

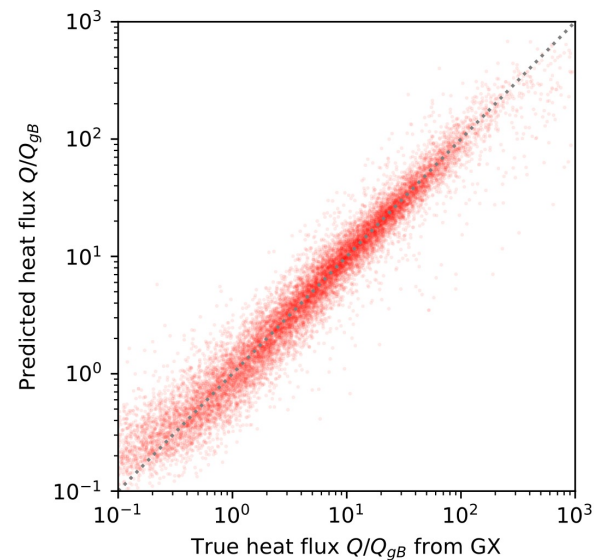
arXiv:2502.11657

Thanks to many others who gave suggestions

Supported by the US DOE StellFoundry SciDAC



This work:
 $N = 100,705$

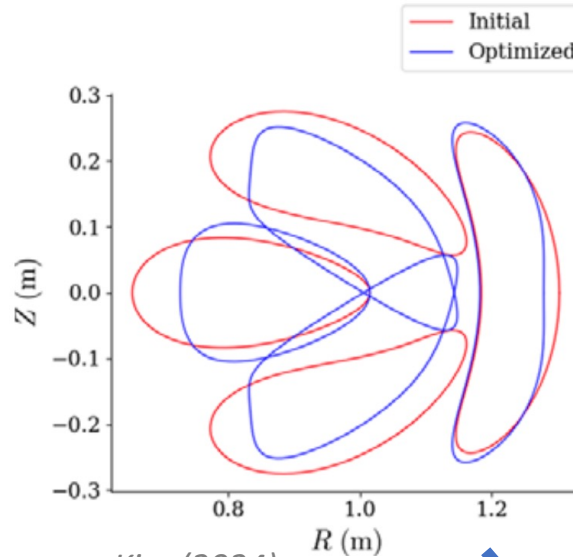


Motivations

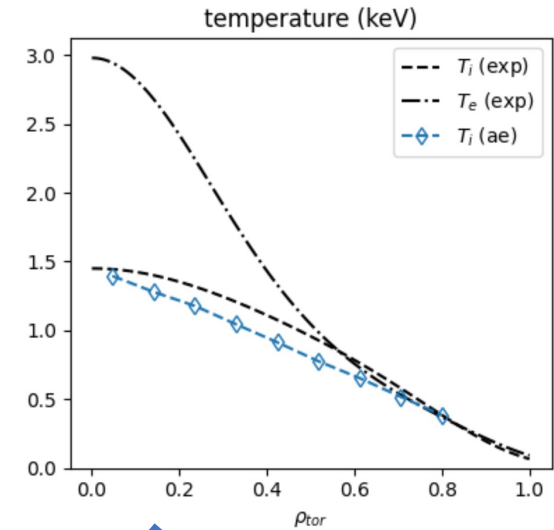
Understanding



Optimization



Profile prediction



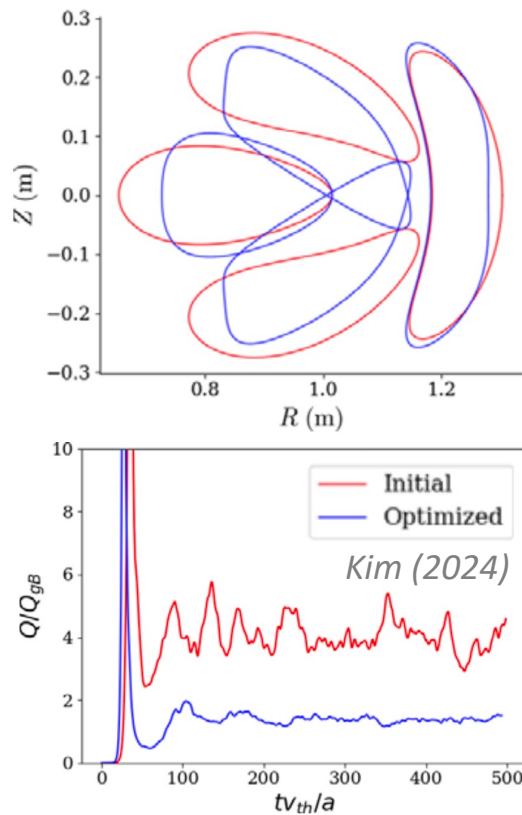
Optimize geometry for maximum fusion power

Motivations

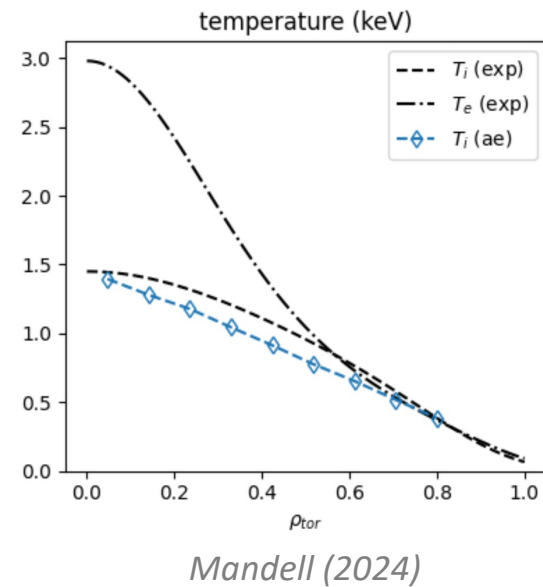
Understanding

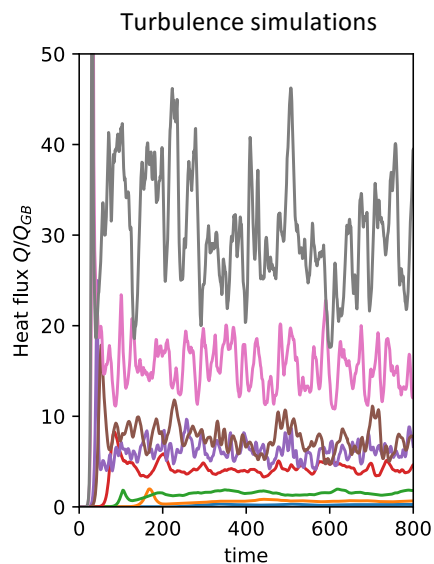
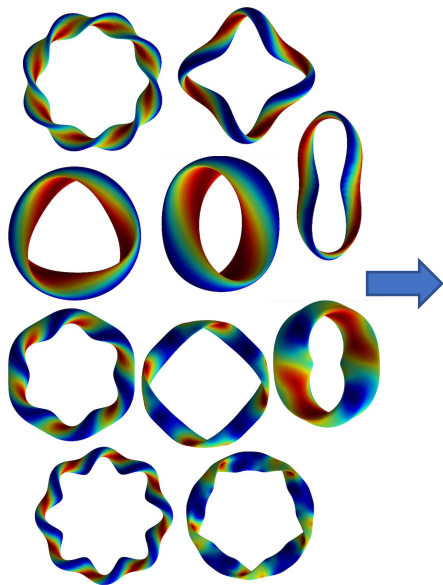


Optimization

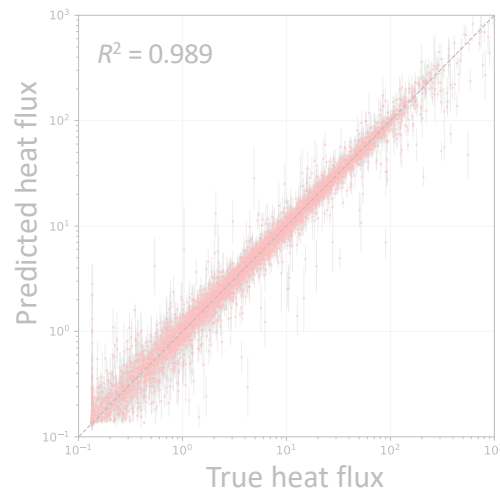


Profile prediction





Regression

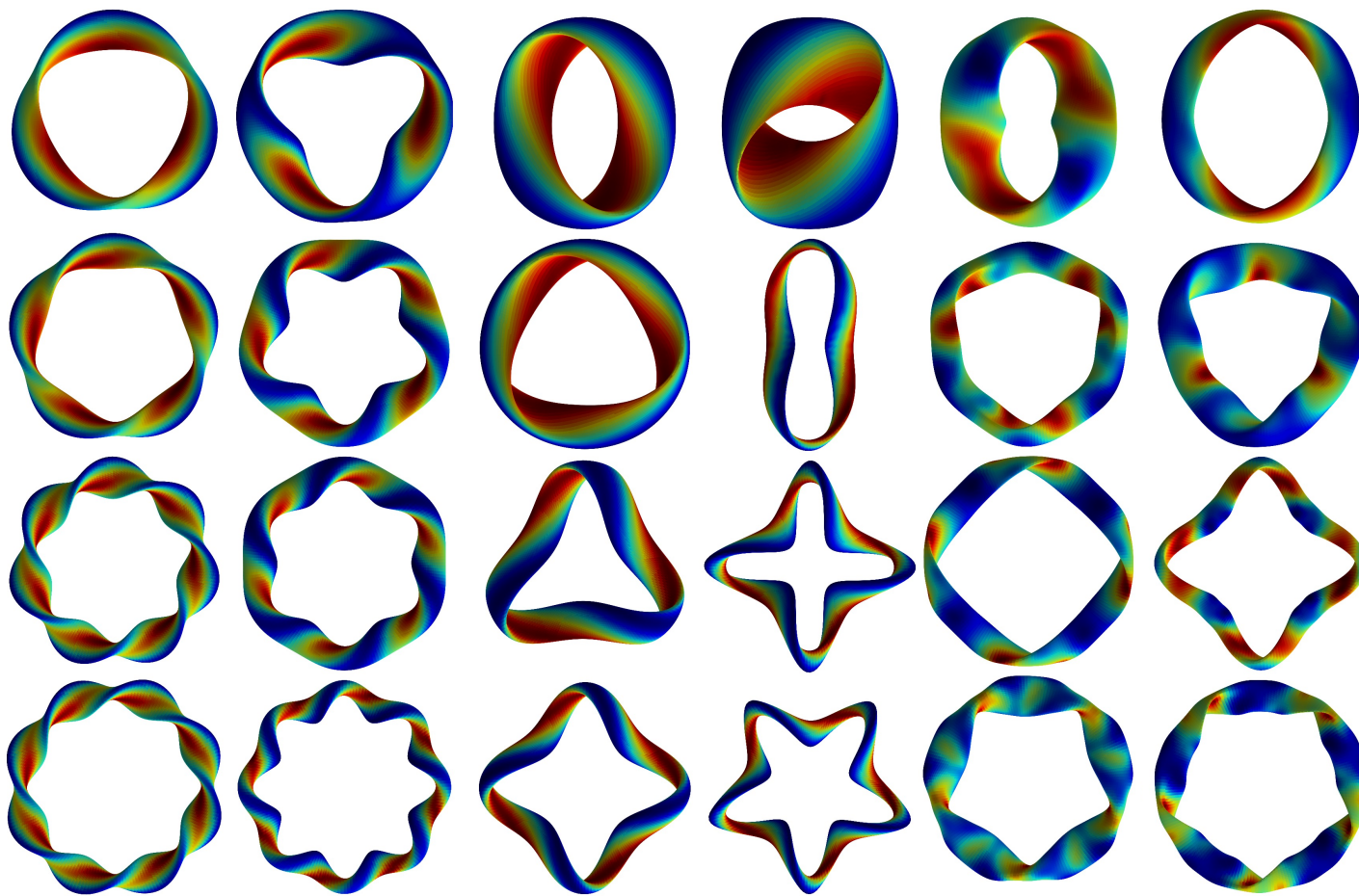


Feature importance

$$\text{mean}([\Theta(\mathbf{B} \times \kappa \cdot \nabla y) + 0.2] |\nabla x|^3 / B)$$

$$\text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 |\nabla x|^8 / B^8)$$

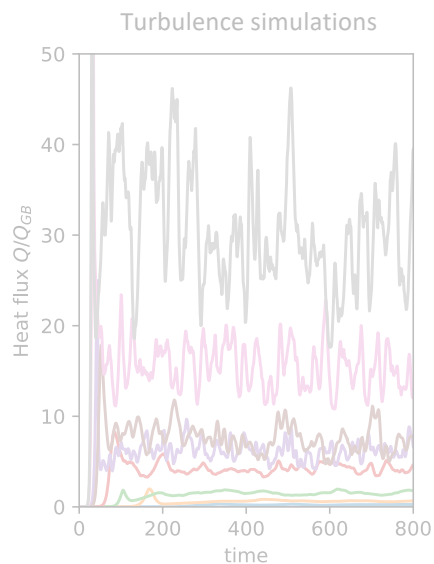
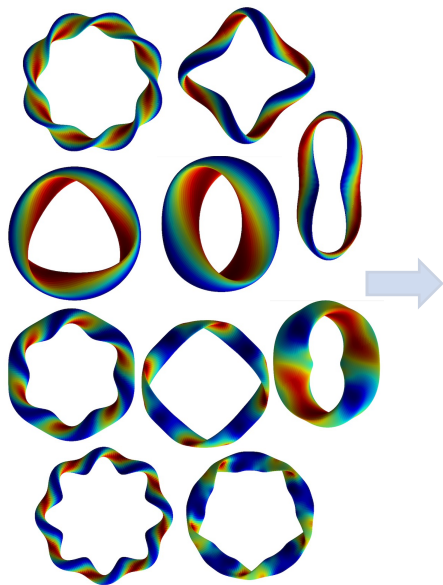
Equilibria include rotating ellipses, quasi-symmetric, and random shapes



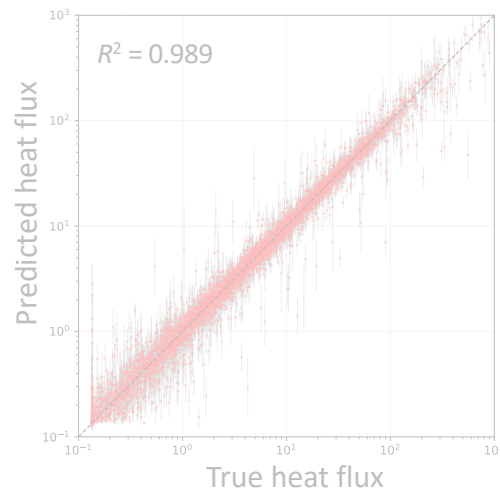
Aspect ratio,
elongation, $q = 1 / \iota$,
 β , and number of field
periods are all varied.

All configurations
scaled to have same
gyroBohm
normalizations

(Tokamak generation
underway by Ralf
Mackenbach)



Regression

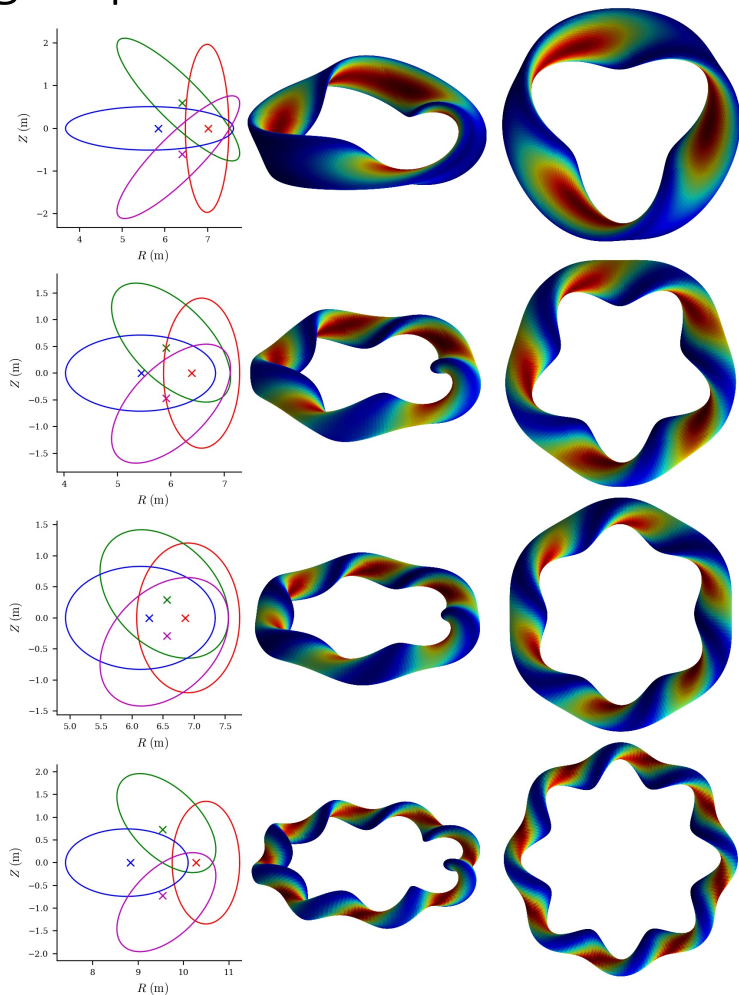
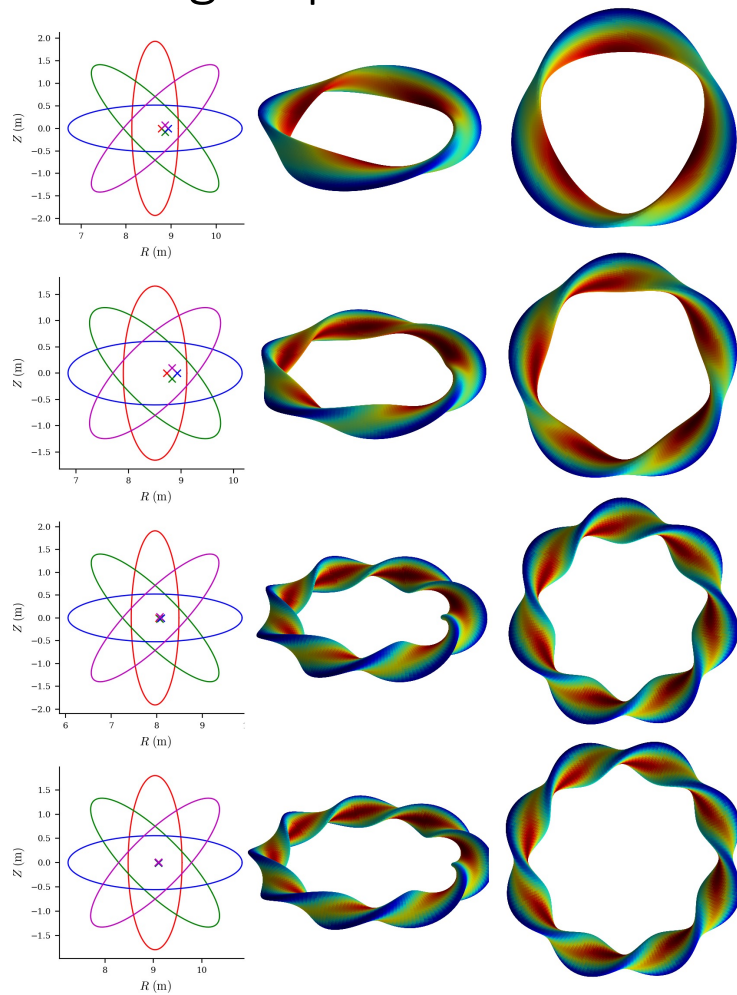


Feature importance

$$\text{mean}([\Theta(\mathbf{B} \times \kappa \cdot \nabla y) + 0.2] |\nabla x|^3 / B)$$

$$\text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 |\nabla x|^8 / B^8)$$

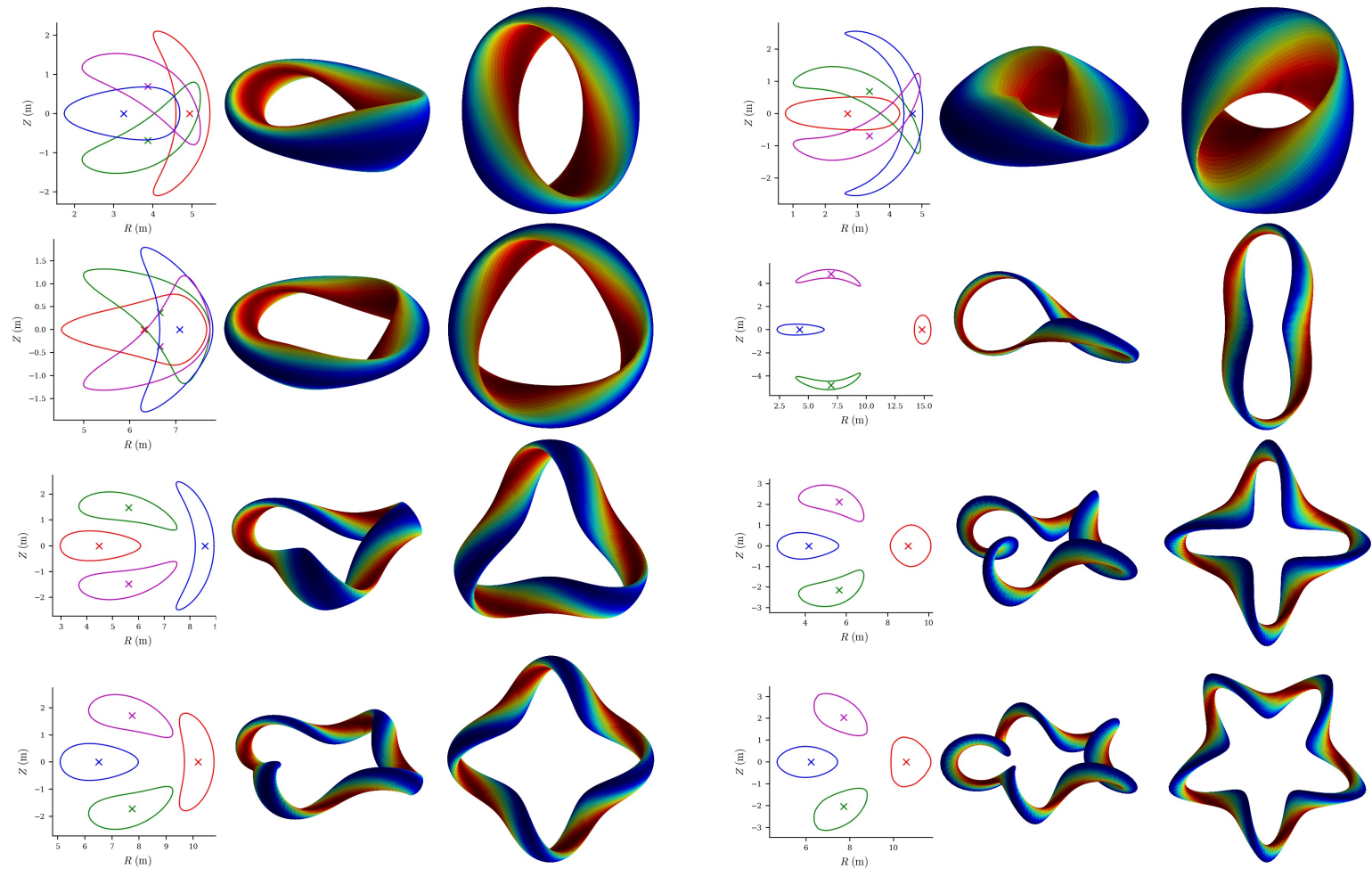
Equilibria group 1: random rotating ellipses



N_{fp} ,
aspect ratio,
elongation,
axis torsion,
and beta are
all random.

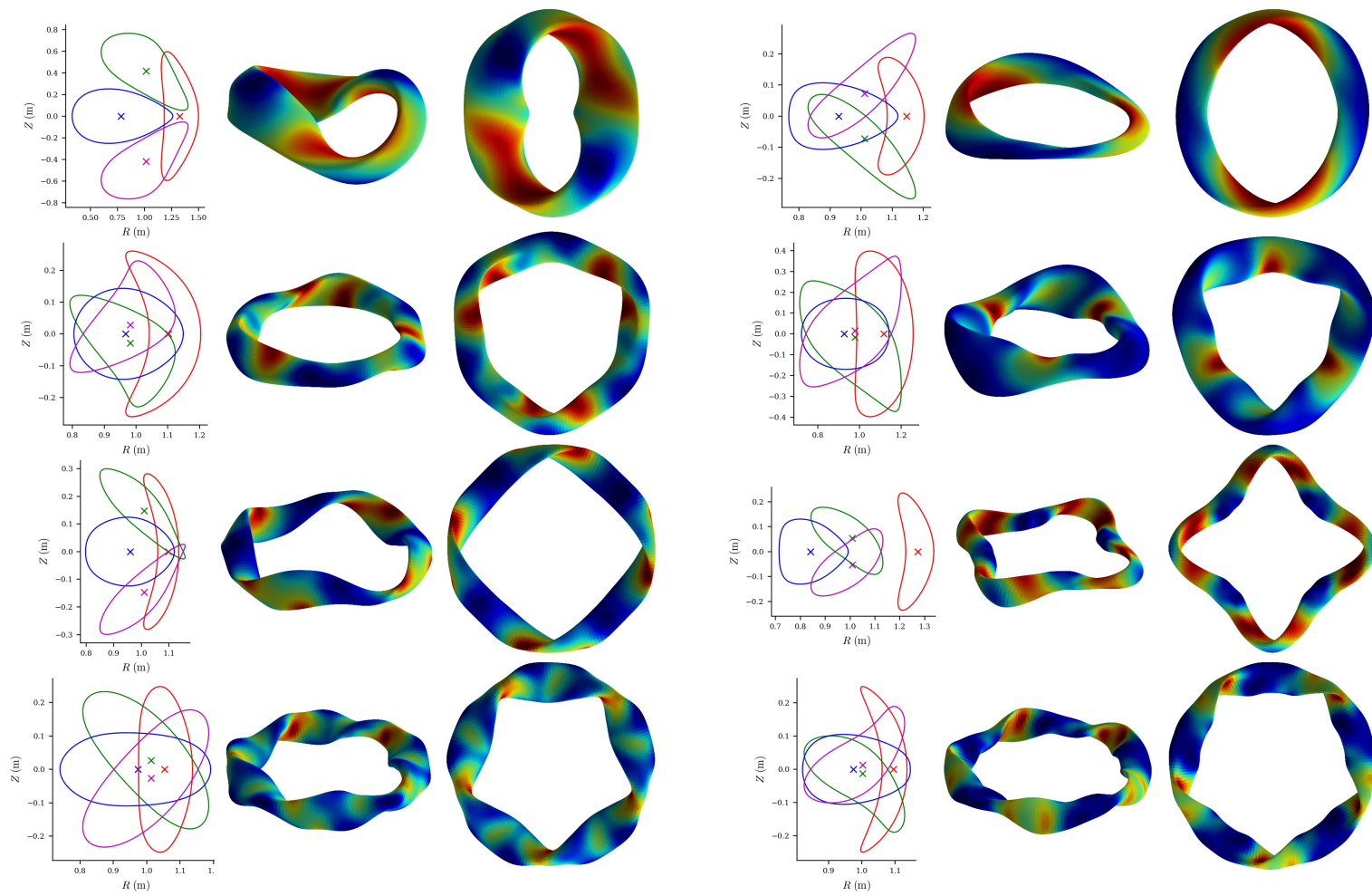
All
configurations
have same
minor radius &
toroidal flux,
so same
gyroBohm
normalization

Equilibria group 2: QUASR QA & QH (Giuliani 2024)

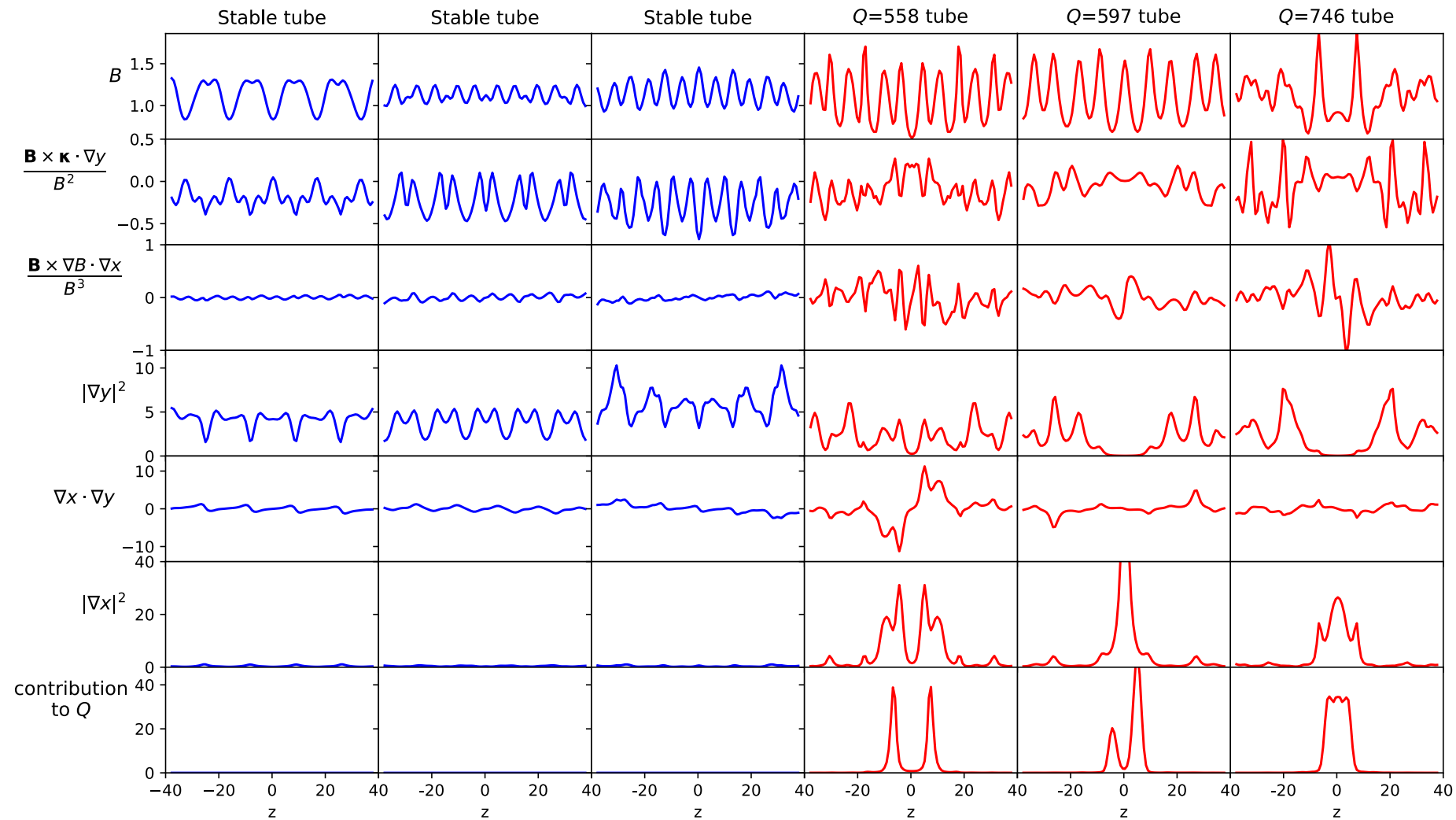


Random
pressure
added for
even more
diversity

Equilibria group 3: random boundary modes



RBC and ZBS
boundary
Fourier modes
sampled from
normal
distributions,
fit to 44 “real”
stellarators



Our interpretable models use a large library of candidate features, all translation-invariant

Start with inputs to the gyrokinetic equation & local shear:

$$F = \{B, B^{-3}\mathbf{B} \times \nabla B \cdot \nabla \mathbf{y}, B^{-2}\mathbf{B} \times \mathbf{\kappa} \cdot \nabla \mathbf{y}, B^{-3}\mathbf{B} \times \nabla B \cdot \nabla \mathbf{x}, |\nabla \mathbf{x}|^2, \nabla \mathbf{x} \cdot \nabla \mathbf{y}, |\nabla \mathbf{y}|^2, d/dz(\nabla \mathbf{x} \cdot \nabla \mathbf{y} / |\nabla \mathbf{x}|^2)\}.$$

U = unary operations on $f(z)$: identity, df/dz , Heaviside(f), Heaviside($-f$), $\text{ReLU}(f)$, $\text{ReLU}(-f)$, $1/f$, f^2 , f/B (Jacobian), $f*B$

$C(U(F)) = U(F)$ and all pairwise products of functions in $U(F)$

Reductions: $R = \{\text{min}, \text{max}, \text{max-min}, \text{mean}, \text{median}, \text{mean square}, \text{variance}, \text{skewness}, L_1 \text{ norm}, \text{quantiles } 0.1, 0.25, 0.75, \text{ or } 0.9, \text{abs of fft coefficients } 1-3, k_{||} \text{ with largest amplitude, expected } k_{||}, \text{count above } [-2, -1, 0, 1, 2]\}$

Features: $R(U(C(U(F)))) \Rightarrow > 1 \text{ million combinations}$

Spearman correlation is a quick tool to find the most important feature

- Spearman correlation is the regular Pearson correlation of the the sorted rank of the target with the sorted rank of the feature.
- Its magnitude is invariant to any monotonic nonlinear function, e.g. $\text{corr}(x, \exp(x)) = 1$
- No regression model required.
- Features with highest correlation to heat flux Q at fixed dT/dx & dn/dx :

Feature	Correlation
$\text{variance}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^2 / B)$	0.775
$\text{mean}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^8 / B^2)$	0.774
$\text{mean}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^4 / B)$	0.772
$\text{variance}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^4 / B)$	0.769
$\text{mean}(\underbrace{\Theta(\mathbf{B} \times \kappa \cdot \nabla y)}_{\text{Heaviside function: Where there is bad curvature,}} \nabla x ^4 / B^2)$	0.769

Heaviside function: Where there is bad curvature, local temperature gradient in real space (to various powers) Jacobian (maybe squared) |∇T| = (dT/dx) |∇x|

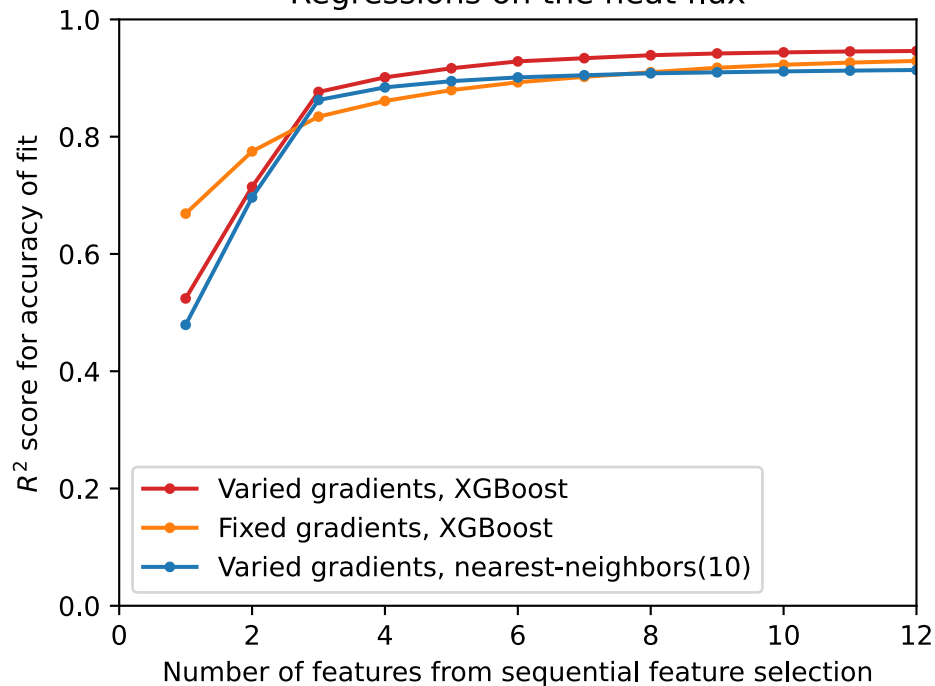
Extremely similar to Mynick (2010), Xanthopoulos (2014), Stroteich (2022), Goodman (2024)!

Forward sequential feature selection: ~ 3 features can be almost as predictive as all features

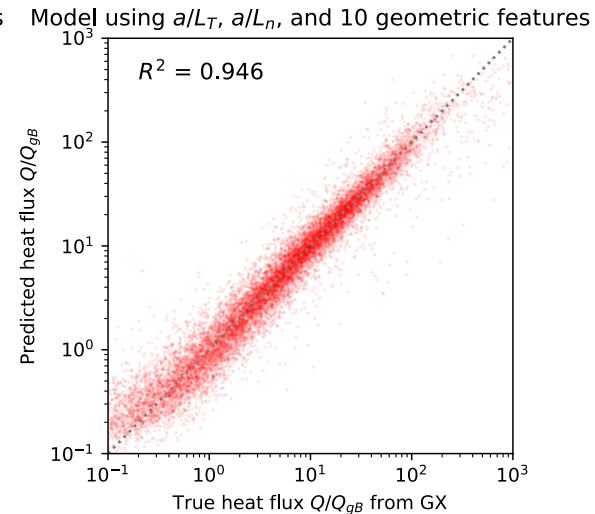
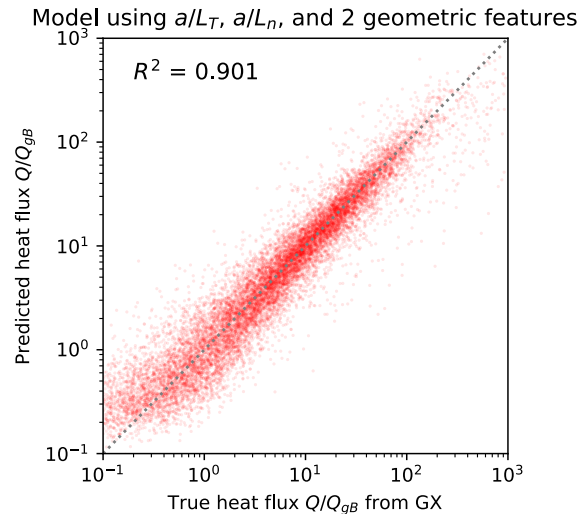
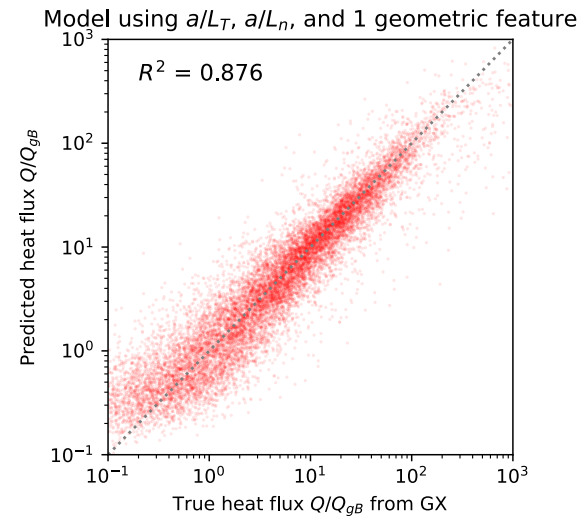
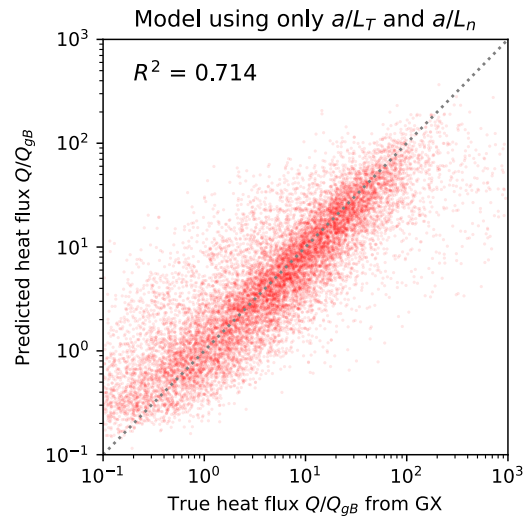
Stiffness

Critical gradient

Regressions on the heat flux



Sequential feature selection allows closer fit to the data as more geometric features are included



Performance shown on 20% held-out test data

At each step, the top features are variations on a theme

Sequential feature selection step 3		Sequential feature selection step 4	
Feature	R^2	Feature	R^2
$\text{mean}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^4 / B^2)$	0.876	$\text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 \nabla x ^8 / B^8)$	0.901
$\text{mean}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^4 / B)$	0.874	$\text{quantile0.75}(\text{ReLU}(-\mathbf{B} \times \nabla B \cdot \nabla x)^2 \nabla x ^8 / B^6)$	0.901
$\text{variance}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^2 / B)$	0.871	$\text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 \nabla x ^8 / B^6)$	0.901
$\text{quantile0.9}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^2 / B)$	0.870	$\text{median}(\mathbf{B} \times \nabla B \cdot \nabla x \nabla x ^4 / B^4)$	0.901
$\text{mean}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^8 / B^4)$	0.869	$\text{quantile0.75}(\text{ReLU}(-\mathbf{B} \times \nabla B \cdot \nabla x) \nabla x ^4 / B^3)$	0.901

Regression for the random-gradient dataset

Spearman correlation is a quick tool to find the most important feature

- Unlike Pearson, Spearman is invariant to any monotonic function.
- Features with highest correlation to heat flux Q at fixed dT/dx & dn/dx :

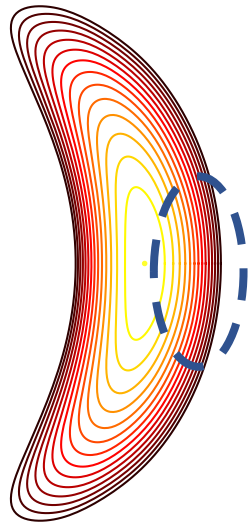
Feature	Correlation
$\text{variance}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^2 / B)$	0.775
$\text{mean}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^8 / B^2)$	0.774
$\text{mean}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^4 / B)$	0.772
$\text{variance}(\Theta(\mathbf{B} \times \kappa \cdot \nabla y) \nabla x ^4 / B)$	0.769
$\text{mean}(\underbrace{\Theta(\mathbf{B} \times \kappa \cdot \nabla y)}_{\text{Heaviside function: Where there is bad curvature,}} \nabla x ^4 / B^2)$	0.769

Heaviside function: Where there is bad curvature,

local temperature gradient in real space (to various powers)

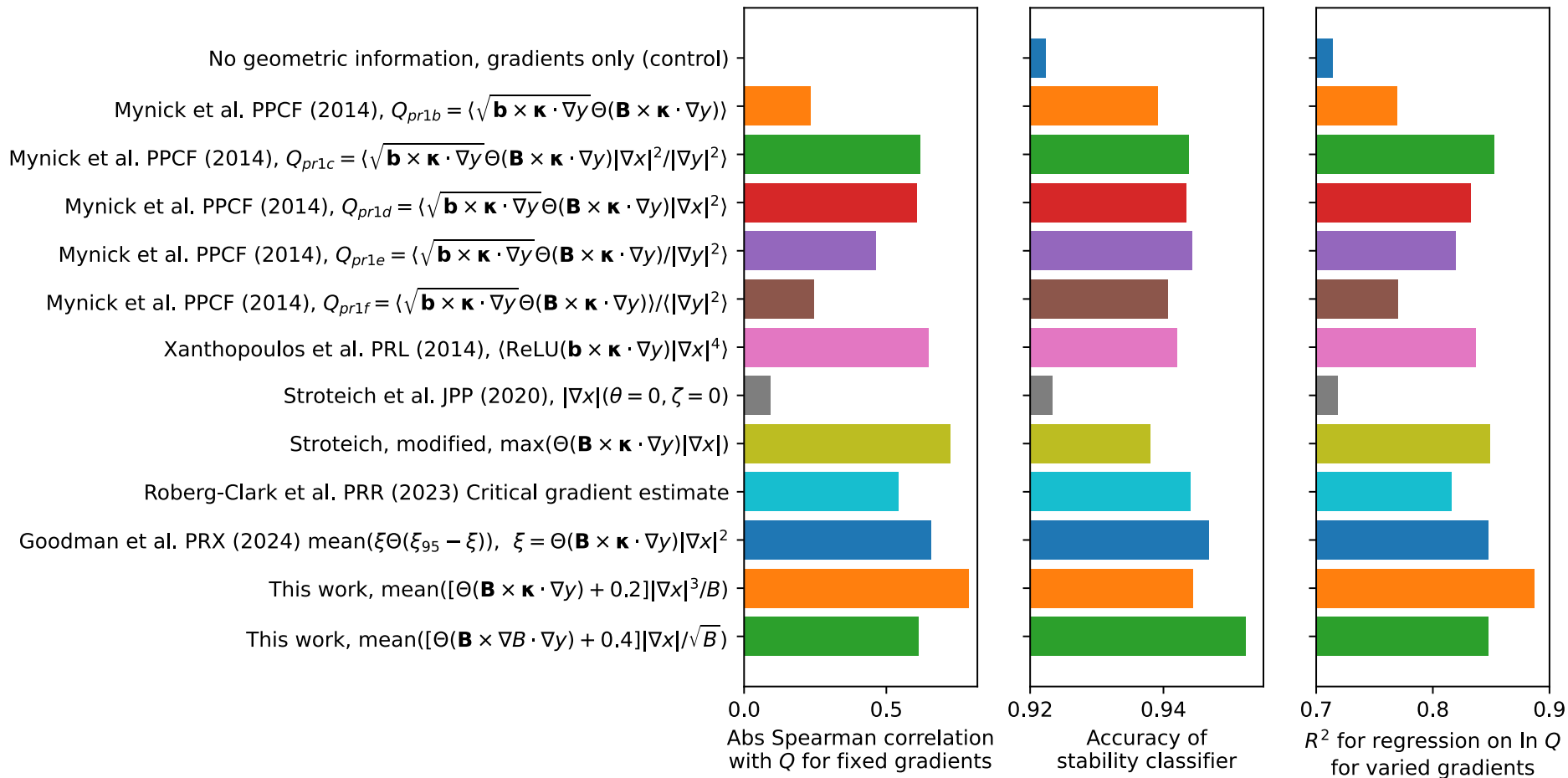
Jacobian (maybe squared)

$|\nabla T| = (dT/dx) |\nabla x|$

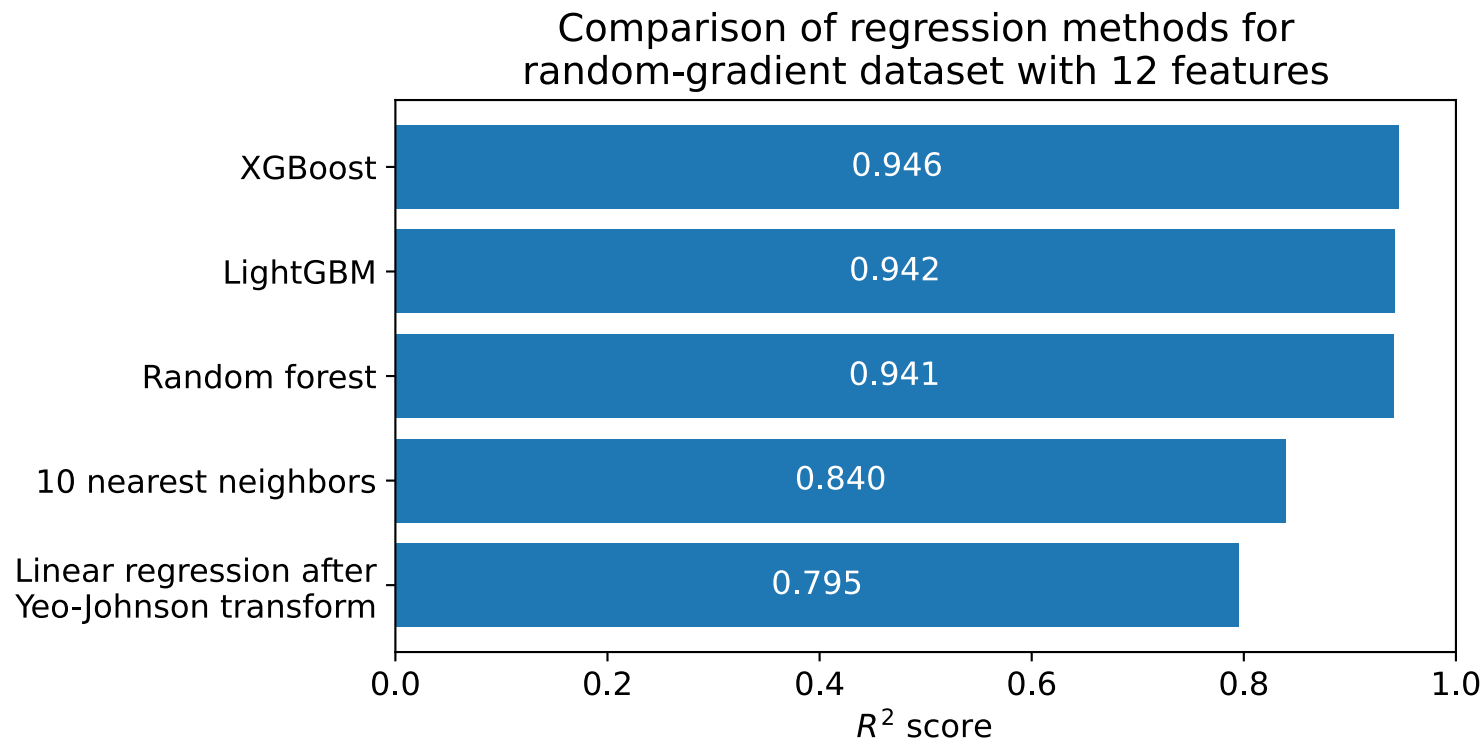


Extremely similar to Mynick (2010), Xanthopoulos (2014), Stroteich (2022), Goodman (2024)!

Previously proposed proxies can be tested

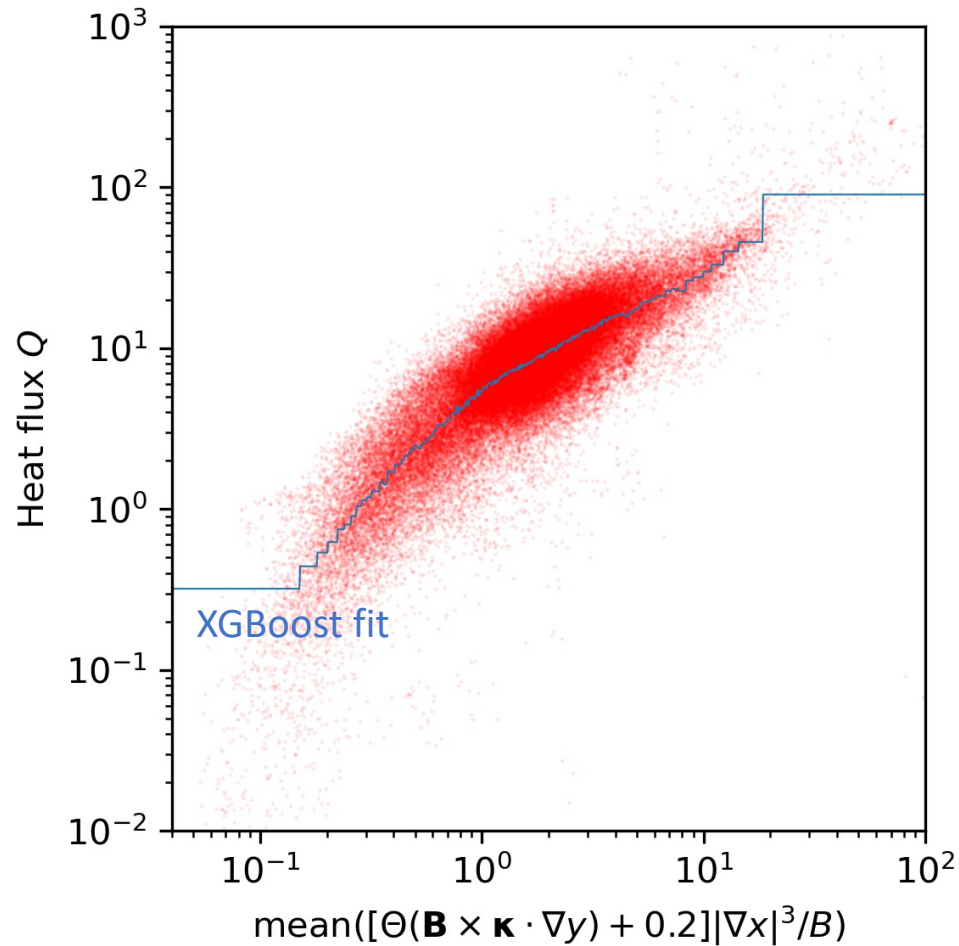


Other machine learning regression methods work also



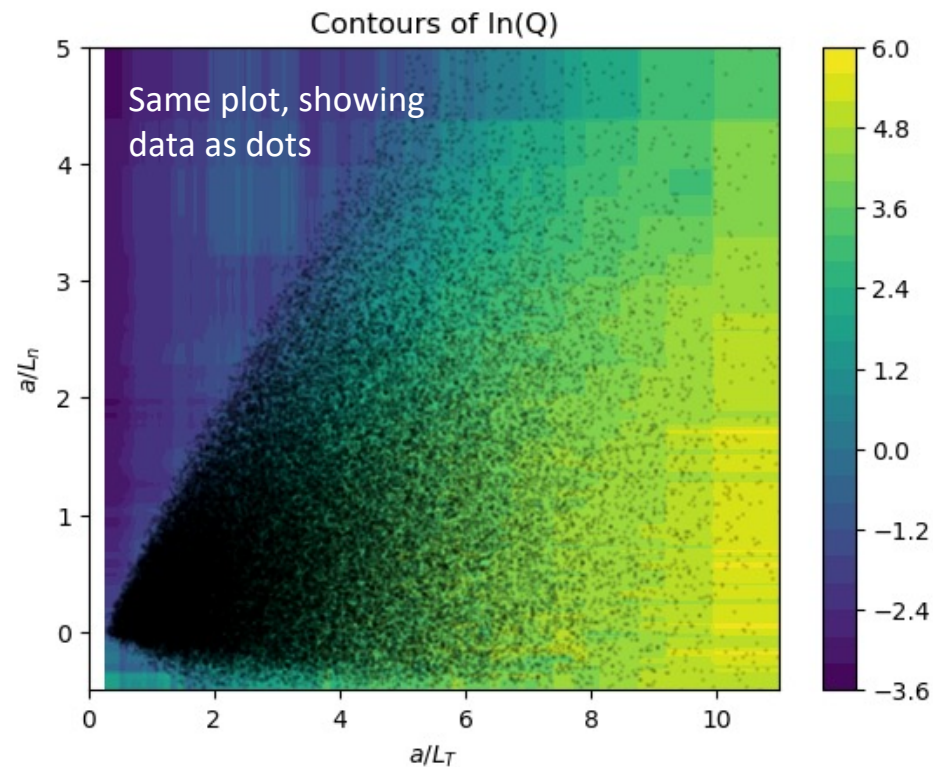
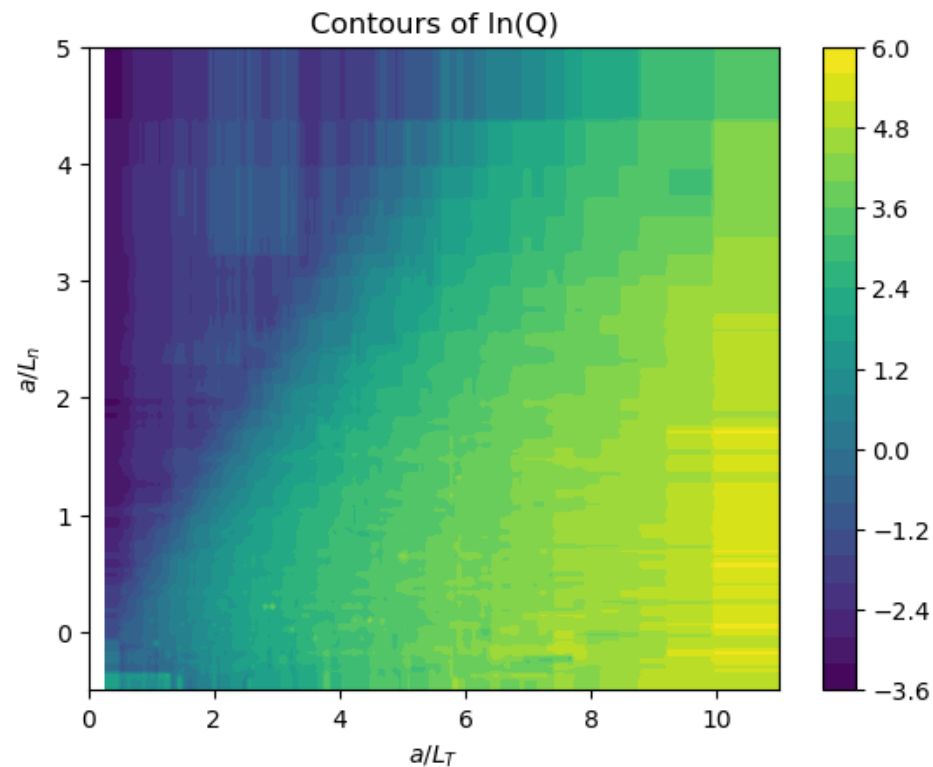
All using a/L_T , a/L_n , and the top 10 geometric features selected via XGBoost

XGBoost regression model with 1 feature

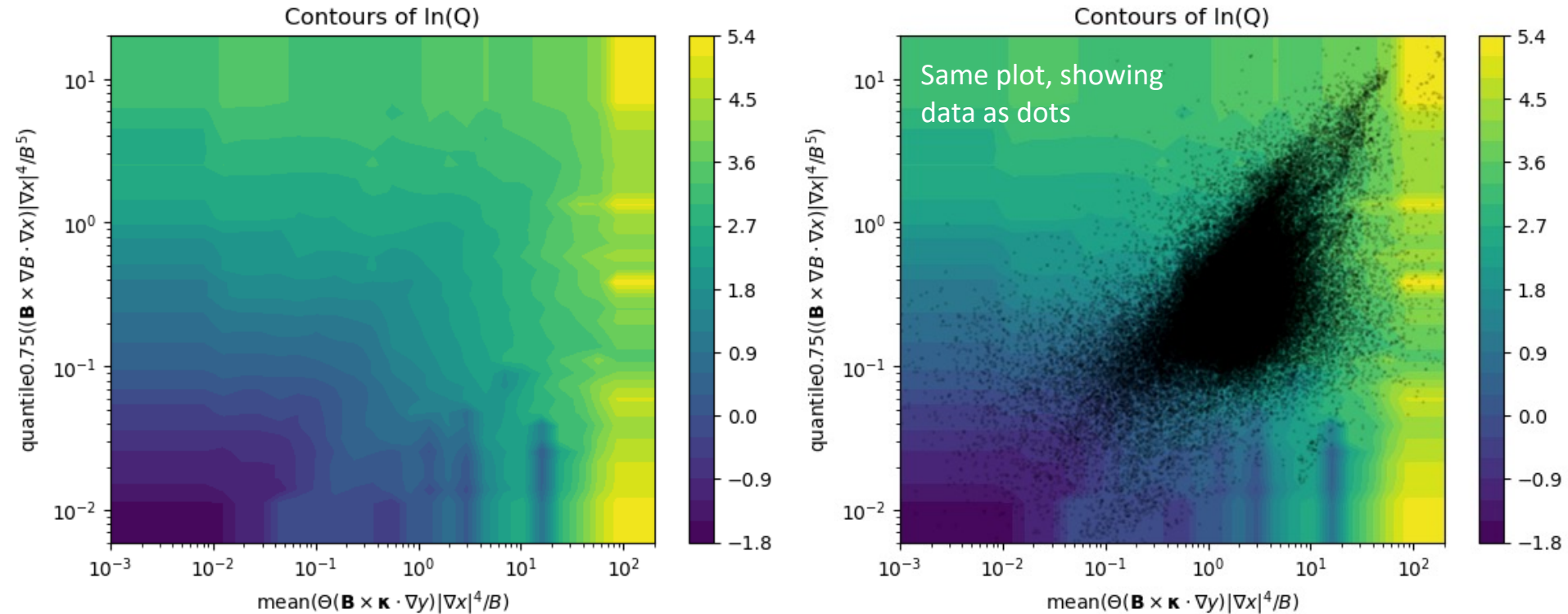


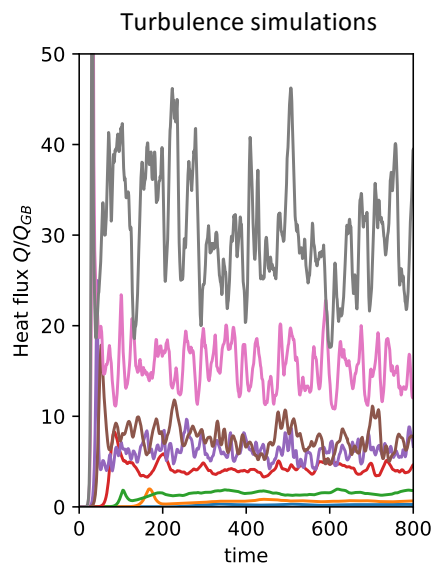
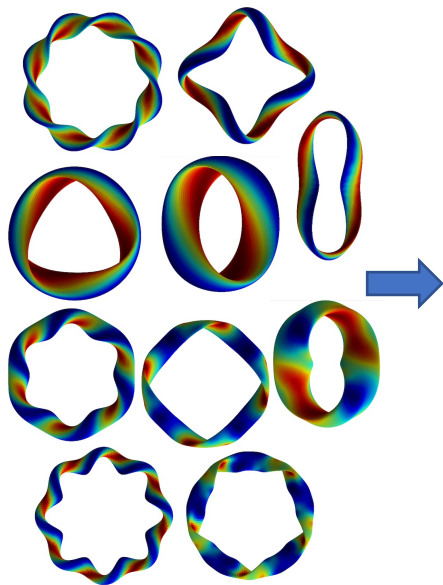
Fixed-gradient dataset

XGBoost regression model using only a/L_T and a/L_n

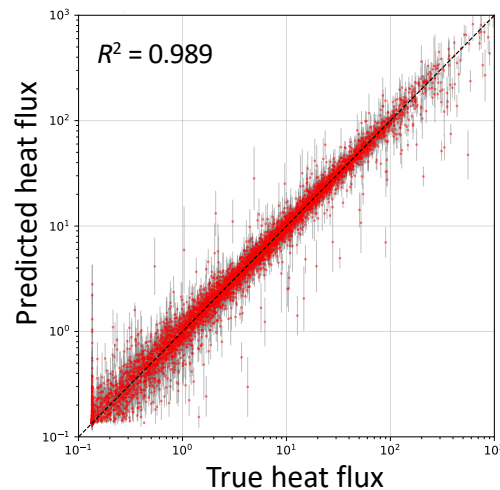


XGBoost regression model for fixed gradients using 2 features





Regression



Feature importance

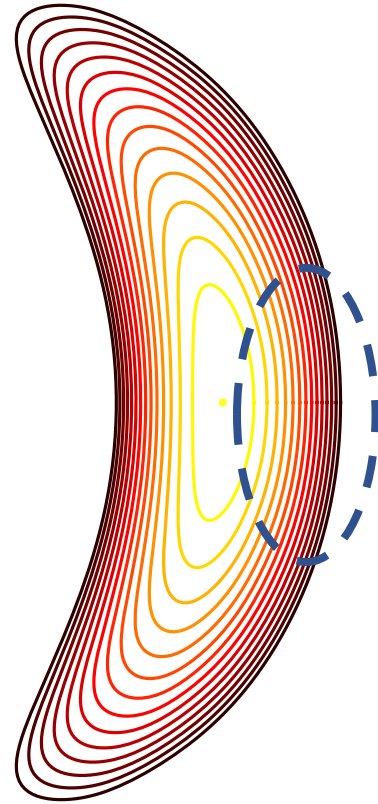


$$\text{mean}([\Theta(\mathbf{B} \times \kappa \cdot \nabla y) + 0.2] |\nabla x|^3 / B)$$

$$\text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 |\nabla x|^8 / B^8)$$

Multiple lines of evidence agree that the most important geometric feature is $|\nabla\psi|$ in regions of bad curvature

- Highest Spearman correlation at fixed gradients.
- Consistently the first geometric feature chosen in sequential feature selection:
 - In regression on the heat flux above the critical gradient
 - And in the classifier for stability vs instability (i.e. determines critical gradient)
 - Chosen by XGBoost, nearest-neighbors, & other algorithms
- Also the largest Shapley values



There are many extensions possible

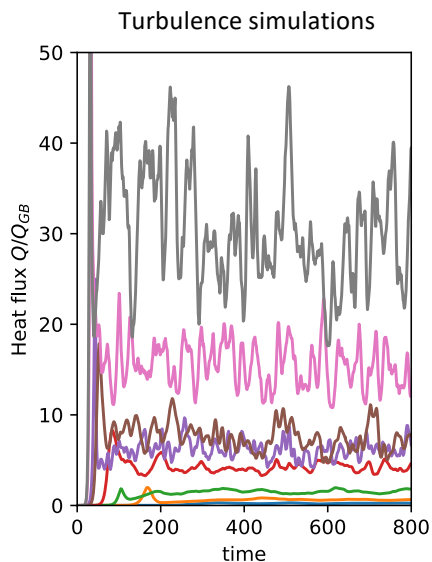
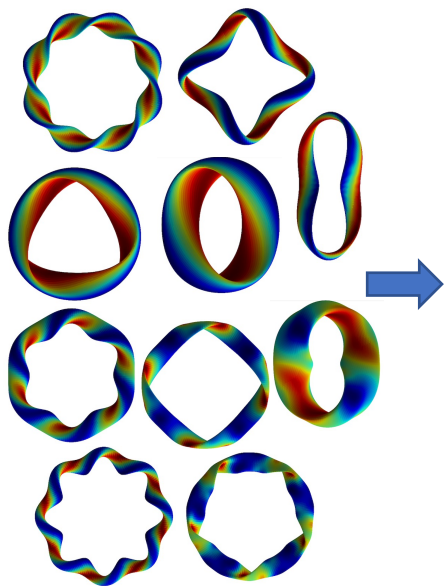
- Try larger sets of possible features
- From the gyrokinetic equation, understand how these features affect turbulence.
- Kinetic electrons, magnetic fluctuations.
- Saliency maps to understand the features learned by the neural networks.
- Symbolic regression.
- Kolmogorov-Arnold Networks.
- Optimization, profile prediction.
- Include & test other physics-motivated features.

Data is online at [doi:10.5281/zenodo.14867776](https://doi.org/10.5281/zenodo.14867776), so have a go at it!

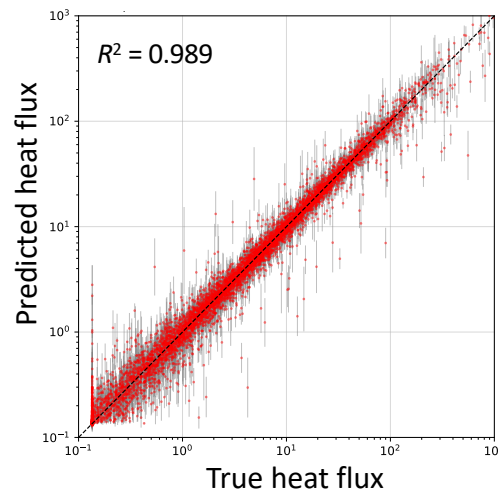
Paper: arXiv:2502.11657



Dataset doi:10.5281/zenodo.14867776

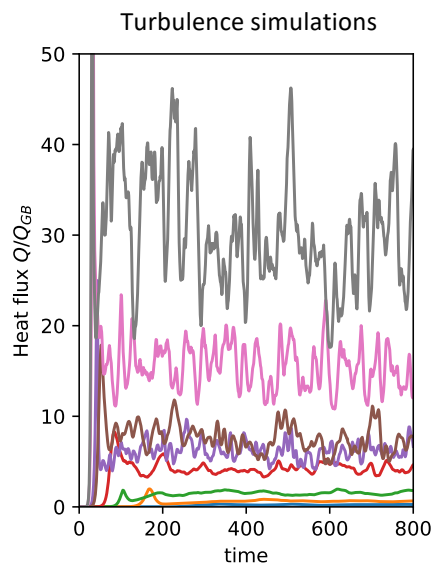
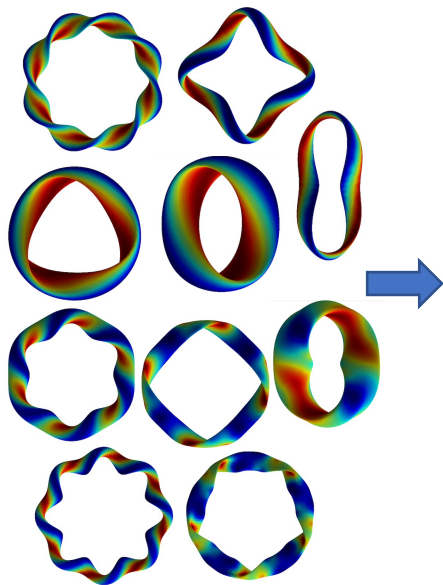


Regression

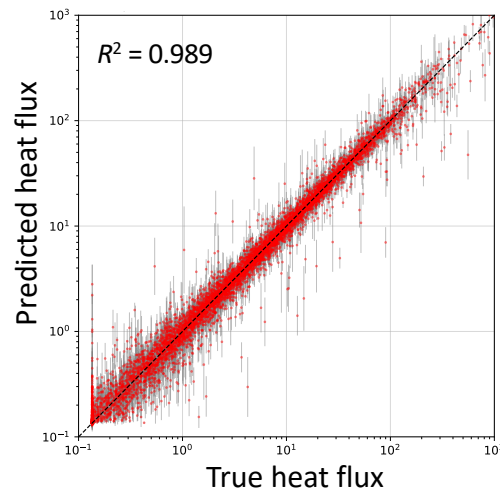


Feature importance

$$\begin{aligned} & \text{mean}([\Theta(\mathbf{B} \times \kappa \cdot \nabla y) + 0.2] |\nabla x|^3 / B) \\ & \text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 |\nabla x|^8 / B^8) \end{aligned}$$



Regression



Feature importance



$$\text{mean}([\Theta(\mathbf{B} \times \kappa \cdot \nabla y) + 0.2] |\nabla x|^3 / B)$$

$$\text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 |\nabla x|^8 / B^8)$$

To create library of candidate features, apply any translation-invariant reduction to translation-equivariant operations

Start with inputs to the gyrokinetic equation & local shear:

$$B, \quad B^{-3} \mathbf{B} \times \nabla B \cdot \nabla y, \quad B^{-2} \mathbf{B} \times \mathbf{k} \cdot \nabla y, \quad B^{-3} \mathbf{B} \times \nabla B \cdot \nabla x, \\ |\nabla x|^2, \quad \nabla x \cdot \nabla y, \quad |\nabla y|^2, \quad d/dz(\nabla x \cdot \nabla y / |\nabla x|^2).$$

Apply unary operations on $f(z)$: f^2 , df/dz , Heaviside(f), etc.,

Include all pairwise products,

Reductions: max, median, abs of fft coefficients, $k_{||}$ with largest amplitude, etc.

$\Rightarrow$ > 1 million combinations

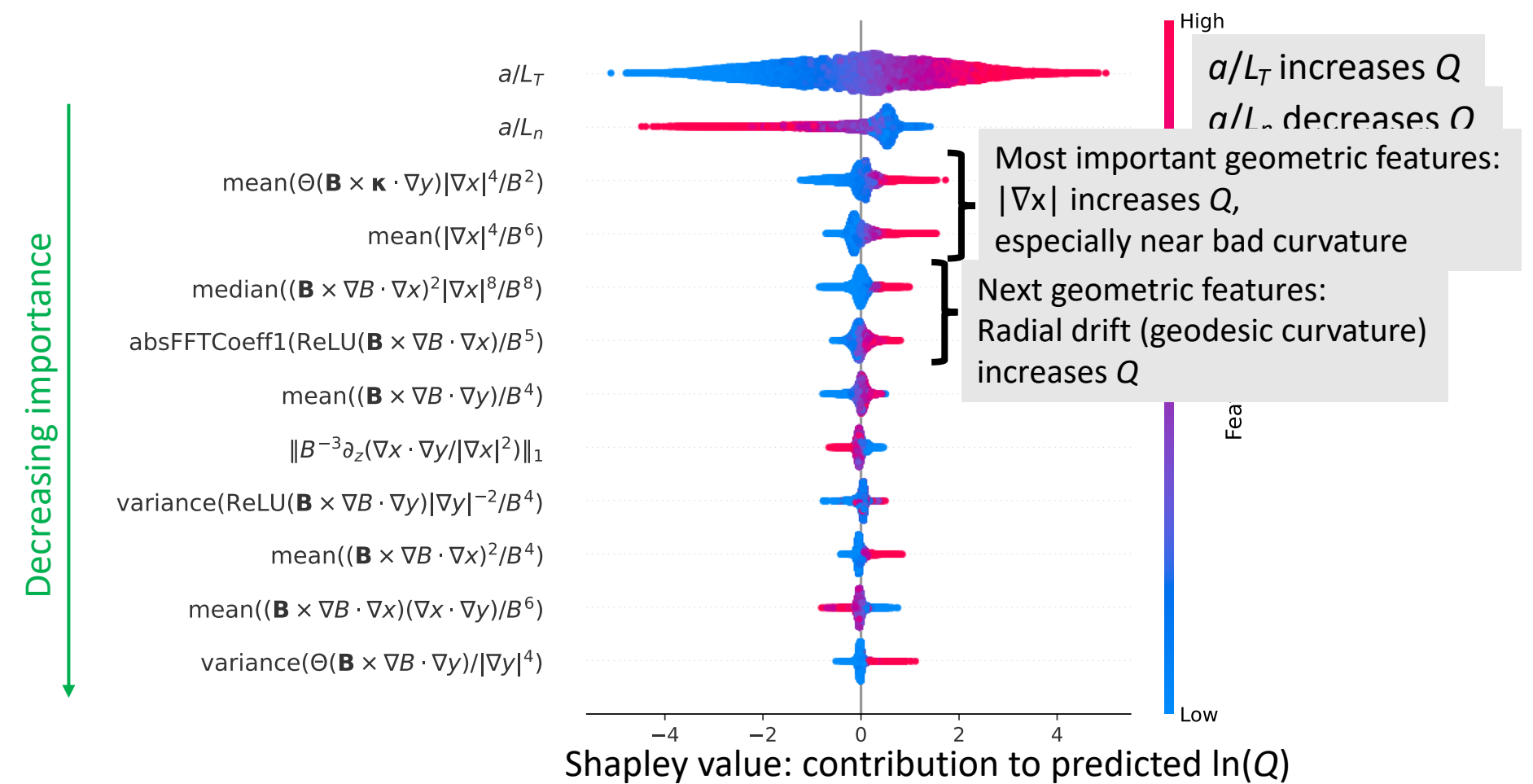
Most important features from sequential feature selection

Regression on heat flux		Classification (stability vs instability)	
Feature	R^2	Feature	log-loss
a/L_T	0.524	a/L_T	0.361
a/L_n	0.714	a/L_n	0.189
$\text{mean}(\Theta(\mathbf{B} \times \kappa \cdot \nabla u) \nabla x ^4 / B^2)$	0.876	$\text{mean}(\Theta(\mathbf{B} \times \nabla B \cdot \nabla u) \nabla x ^2 / B)$	0.122
$\text{median}((\mathbf{B} \times \nabla B \cdot \nabla x)^2 \nabla x ^8 / B^8)$	0.901	$\text{mean}(\Theta(-\mathbf{B} \times \nabla B \cdot \nabla x) \nabla x ^2 B)$	0.105
$\text{absFFTCoeff1}(\text{ReLU}(\mathbf{B} \times \nabla B \cdot \nabla x) / B^5)$	0.917	$\text{mean}((\mathbf{B} \times \kappa \cdot \nabla y) / B)$	0.094

The 2nd most important geometric feature is flux surface surface compression and radial ∇B drift. The 1st and 3rd are more important than any geometric feature.

Xanthopoulos et al (2011), Nakata & Matsuoka (2022):
Larger geodesic curvature (= radial drift) $\Rightarrow$ Stronger damping of zonal flows $\Rightarrow$ higher heat flux

Shapley values show the sign and magnitude of each feature's effect



Summary

- Interpretable ML can reveal trends and stimulate theory.
- Most important feature for ITG seems to be $|\nabla\psi|$ in regions of bad curvature.

Future work

- From the gyrokinetic equation, understand how top features affect turbulence.
- Saliency maps to understand the features learned by the neural networks.
- Other interpretable methods (symbolic regression, Kolmogorov-Arnold Networks)
- Kinetic electrons, magnetic fluctuations.
- Optimization & profile prediction.

Paper:
arXiv:2502.11657



Dataset
doi:10.5281/zenodo.14867776



