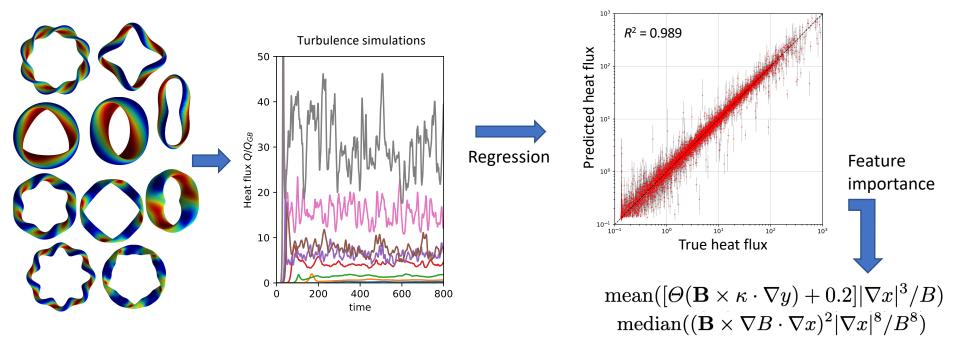
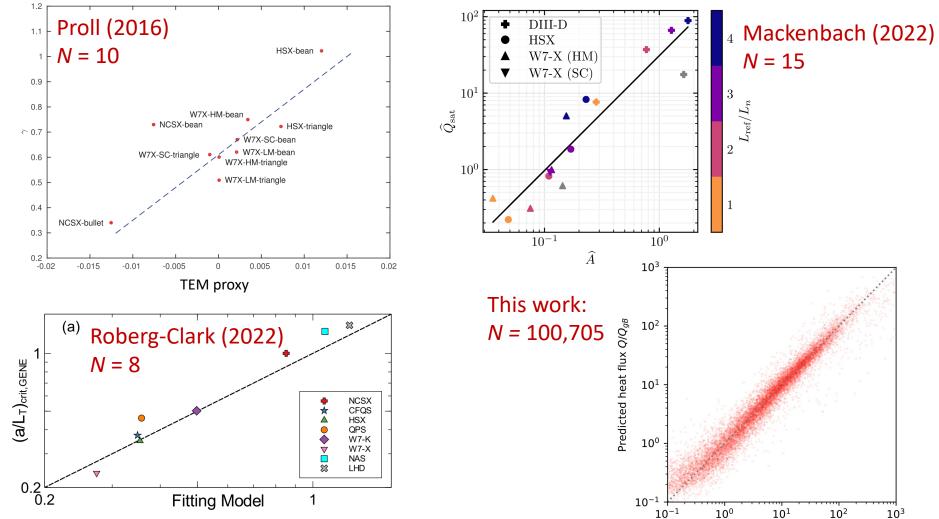
How does magnetic geometry affect ITG turbulence? Insights from data & machine learning



M Landreman, J Y Choi, C Alves, P Balaprakash, R M Churchill, R Conlin, G Roberg-Clark arXiv:2502.11657

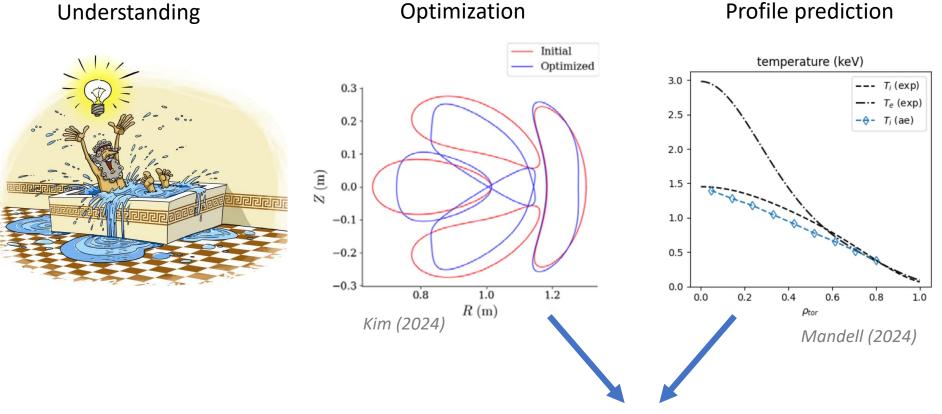
Thanks to many others who gave suggestions

Supported by the US DOE StellFoundry SciDAC

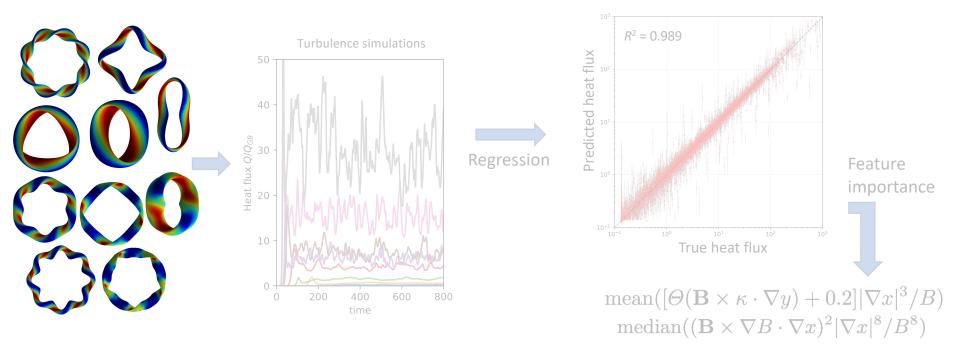


True heat flux Q/Q_{qB} from GX

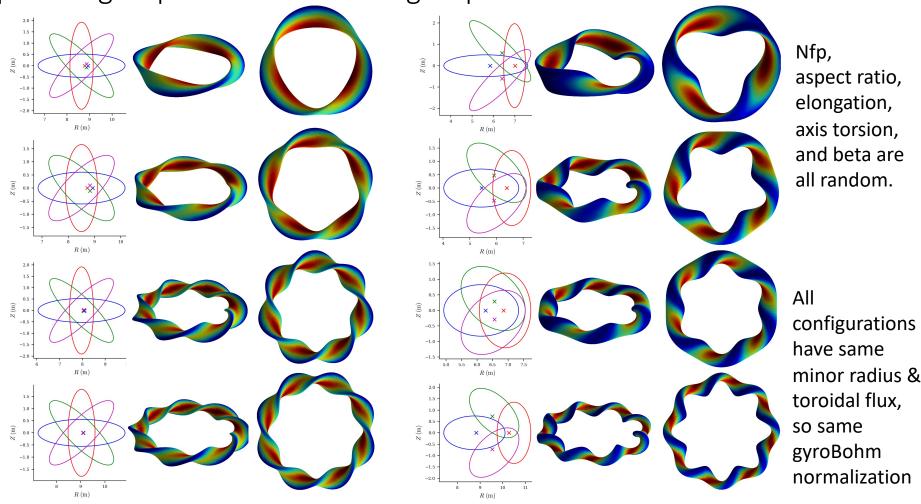
Motivations



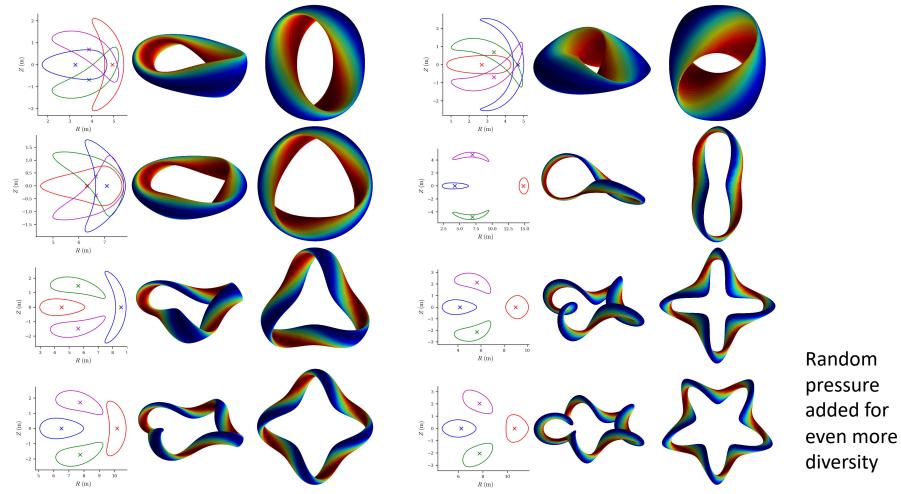
Optimize geometry for maximum fusion power



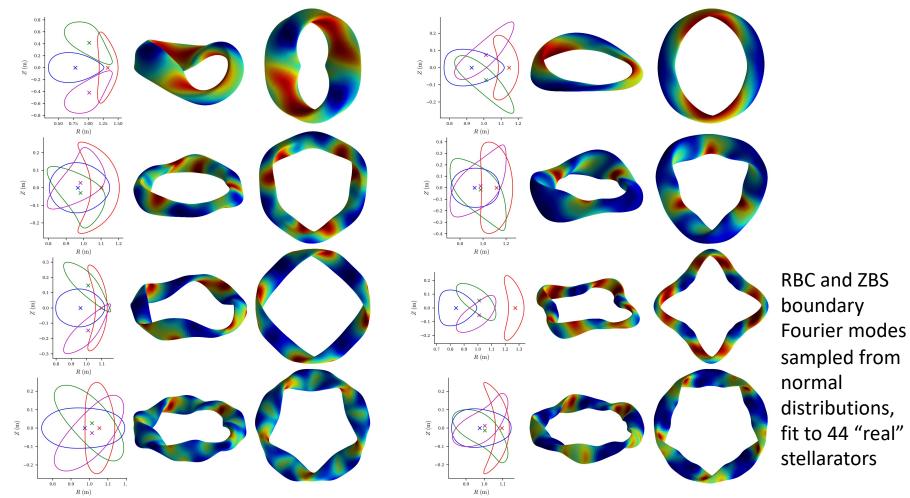
Equilibria group 1: random rotating ellipses

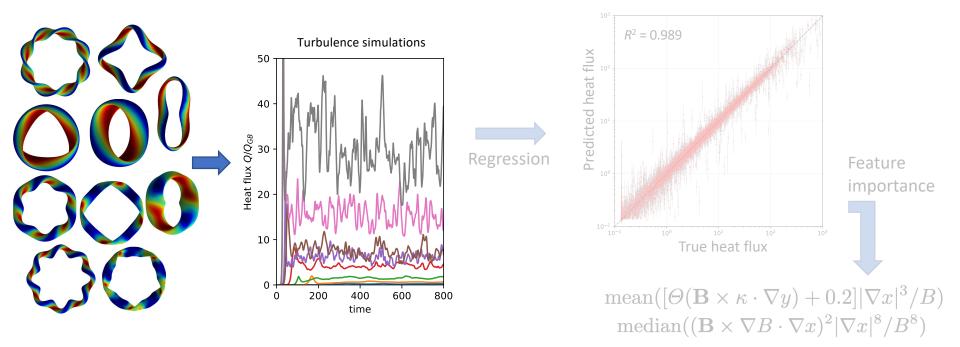


Equilibria group 2: QUASR QA & QH (Giuliani 2024)

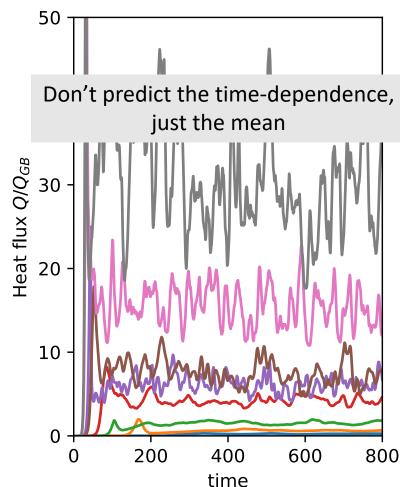


Equilibria group 3: random boundary modes

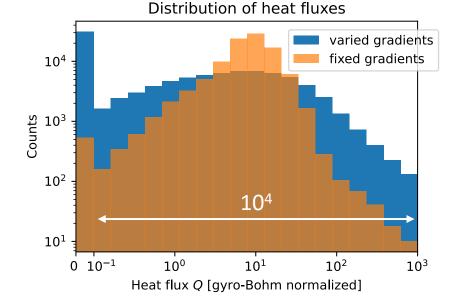




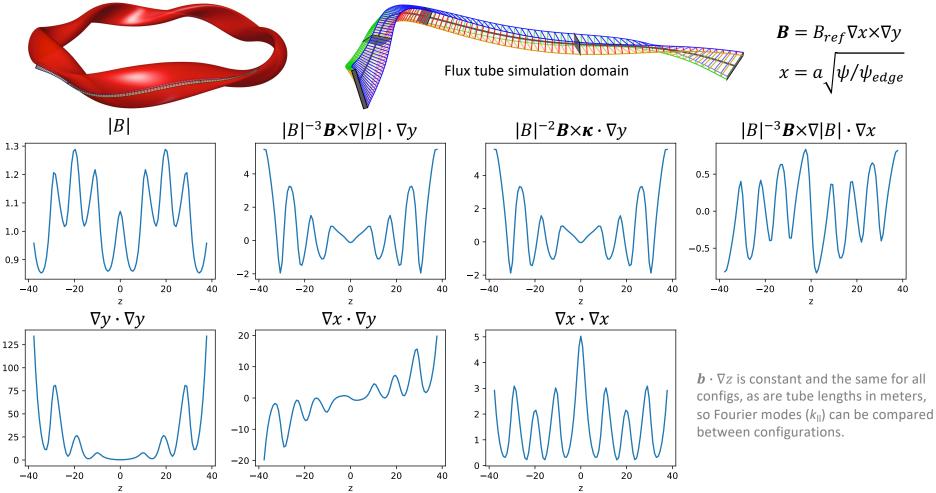
Nonlinear turbulence simulations were run with GX in every equilibrium

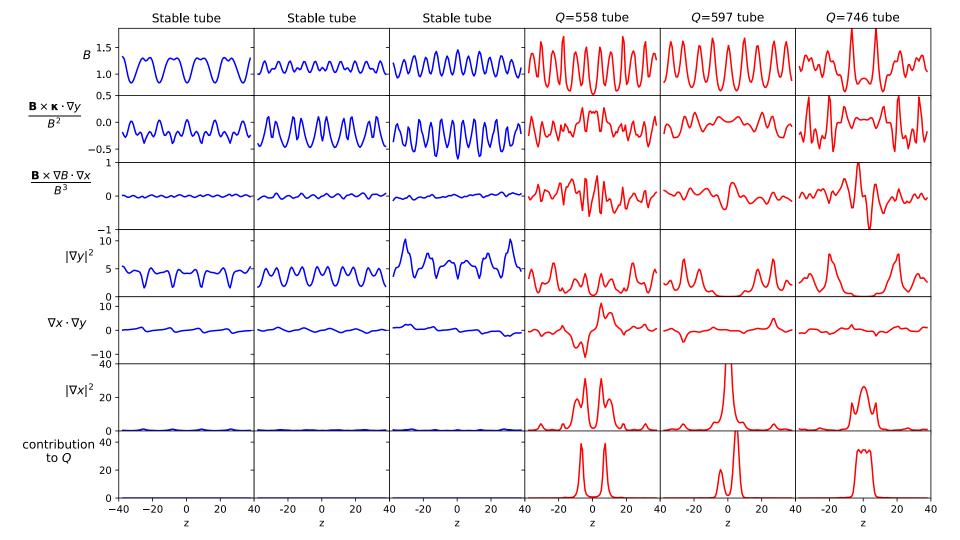


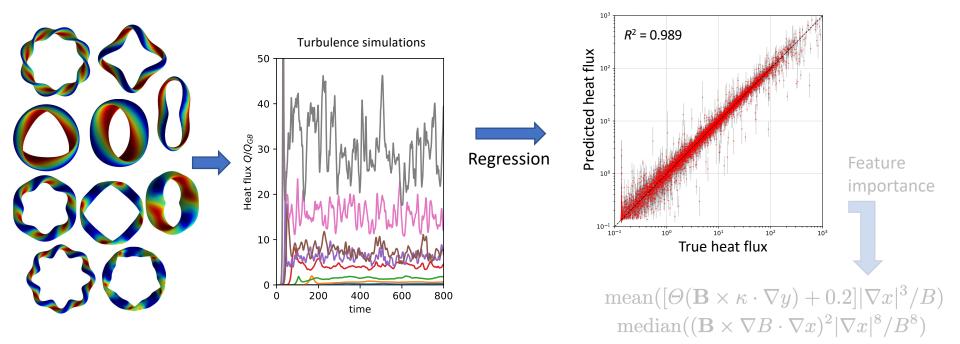
- Electrostatic, adiabatic electrons.
- 1 simulation in each tube with random dT/dx and dn/dx.
- 1 simulation in each tube with (a/T) dT/dx = 3, (a/n) dn/dx=0.9
- 8 minutes to get heat flux on 1 GPU
- 2×10⁵ nonlinear simulations took < 7000 node-hours (1/8 allocation)



Raw feature space: 7x 1D functions that enter the turbulence simulations

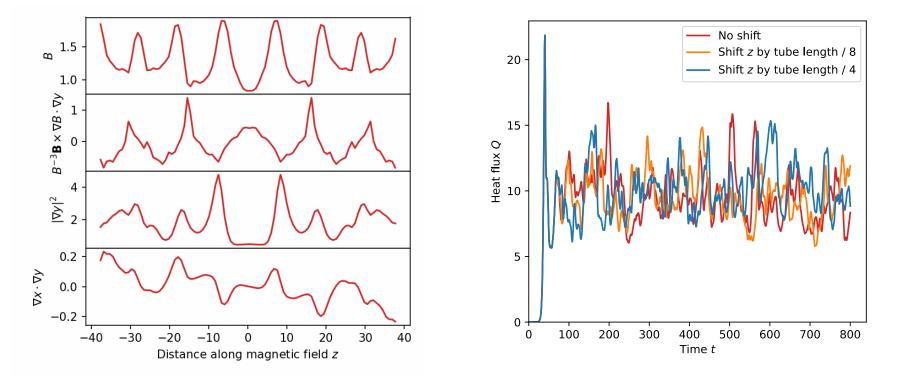




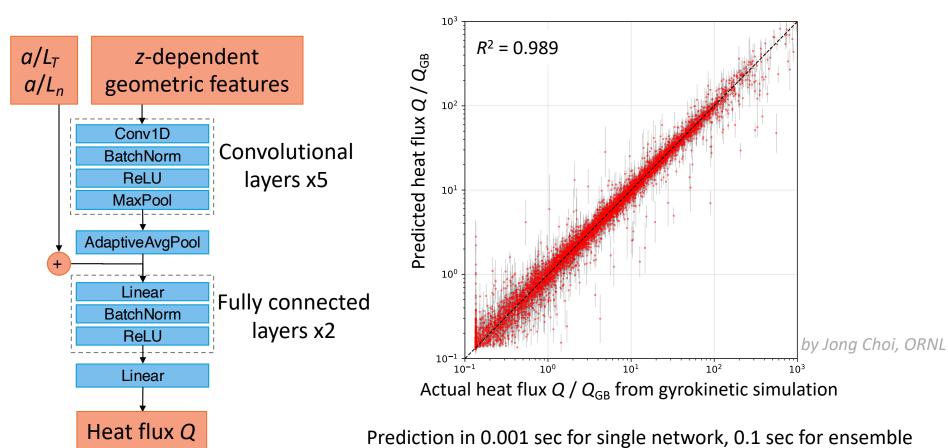


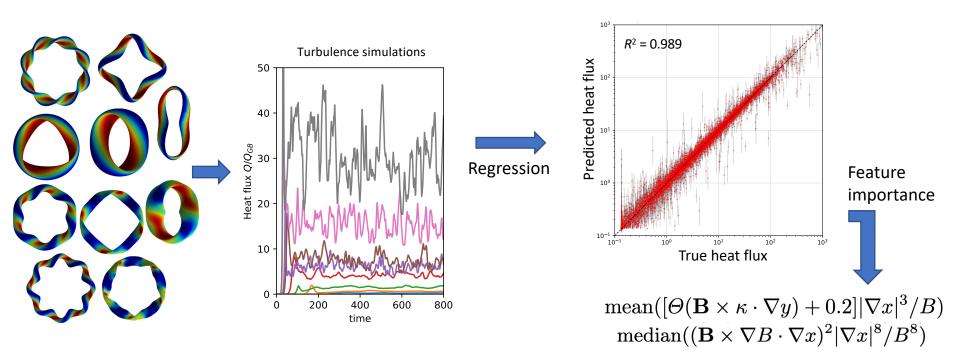
Raw features should *not* be directly fed to classical regression or fullyconnected neural network, since model should be translation-invariant

- GK equation, hence heat flux, is invariant under periodic translation of the raw features in z.
- Similar to computer vision, where convolutional neural networks give approximate translation-invariance.



Convolutional neural networks give accurate prediction of the turbulence





- Spearman correlation
- Sequential feature selection
- Shapley values
- Testing physics-based surrogates

Our interpretable models use a large library of candidate features, all translation-invariant

Start with inputs to the gyrokinetic equation & local shear: $F = \{B, B^{-3}B \times \nabla B \cdot \nabla y, B^{-2}B \times \kappa \cdot \nabla y, B^{-3}B \times \nabla B \cdot \nabla x, |\nabla x|^2, \nabla x \cdot \nabla y, |\nabla y|^2, d/dz(\nabla x \cdot \nabla y / |\nabla x|^2)\}.$

U = unary operations on f(z): identity, df/dz, Heaviside(f), Heaviside(-f), ReLU(f), ReLU(-f), 1/f, f², f/B (Jacobian), f*B

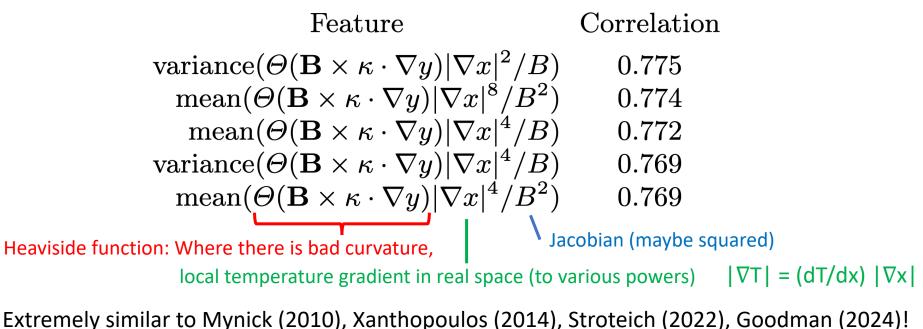
C(U(F)) = U(F) and all pairwise products of functions in U(F)

Reductions: R = {min, max, max-min, mean, median, mean square, variance, skewness, L₁ norm, quantiles 0.1, 0.25, 0.75, or 0.9, abs of fft coefficients 1-3, $k_{||}$ with largest amplitude, expected $k_{||}$, count above [-2, -1, 0, 1, 2]}

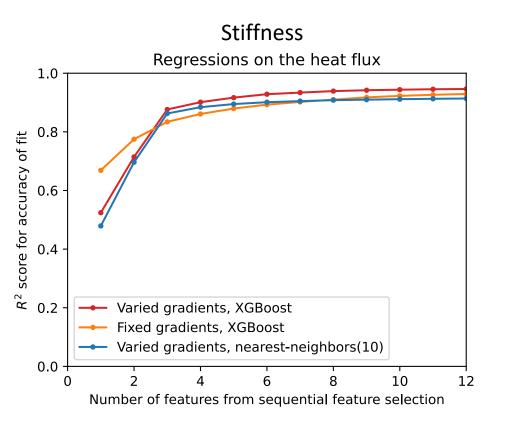
Features: $R(U(C(U(F)))) \implies > 1$ million combinations

Spearman correlation is a quick tool to find the most important feature

- Spearman correlation is the regular Pearson correlation of the the sorted rank of the target with the sorted rank of the feature.
- Its magnitude is invariant to any monotonic nonlinear function, e.g. corr(x, exp(x)) = 1
- No regression model required.
- Features with highest correlation to heat flux *Q* at fixed dT/dx & dn/dx:

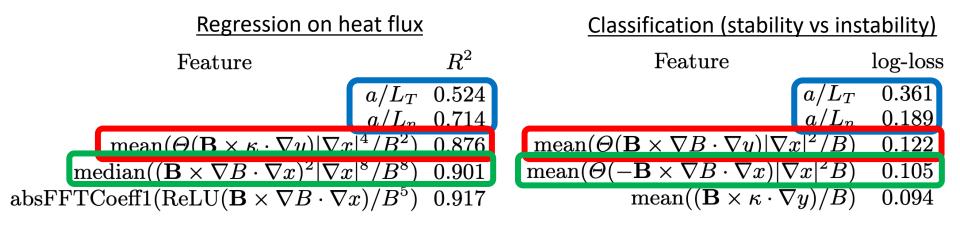


Forward sequential feature selection: \sim 3 features can be almost as predictive as all features



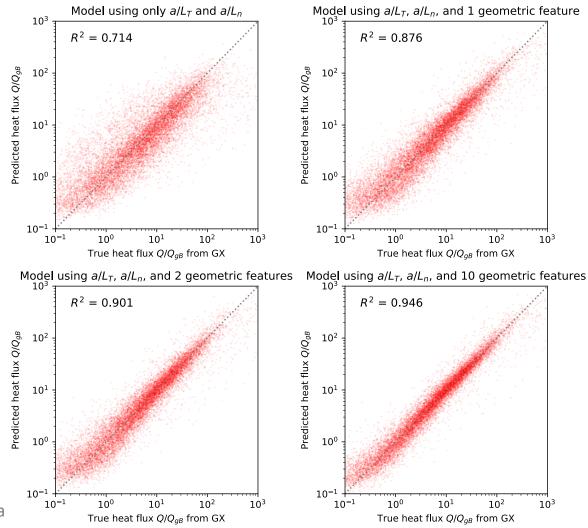
Critical gradient

Most important features from sequential feature selection



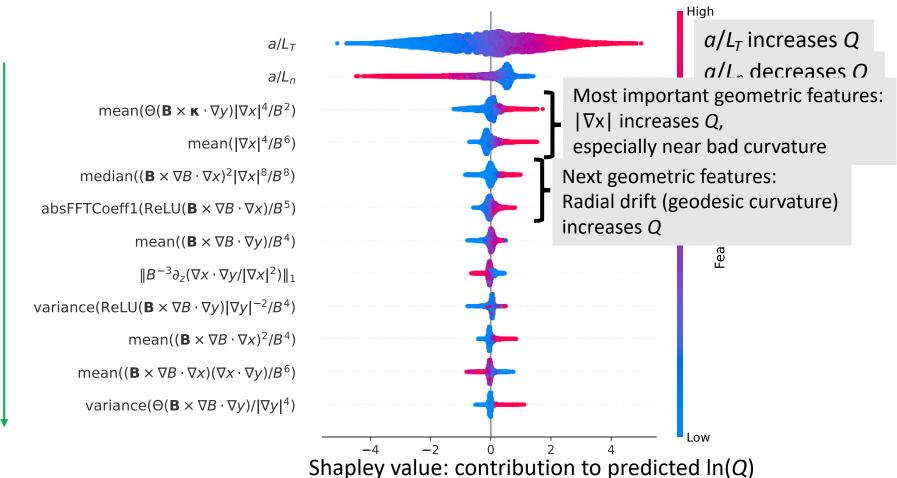
The Bed most important genometric feature is flakes of a greasion while a closed is Badift

Xanthopoulos et al (2011), Nakata & Matsuoka (2022): Larger geodesic curvature (= radial drift) \Rightarrow Stronger damping of zonal flows \Rightarrow higher heat flux Sequential feature selection allows closer fit to the data as more geometric features are included

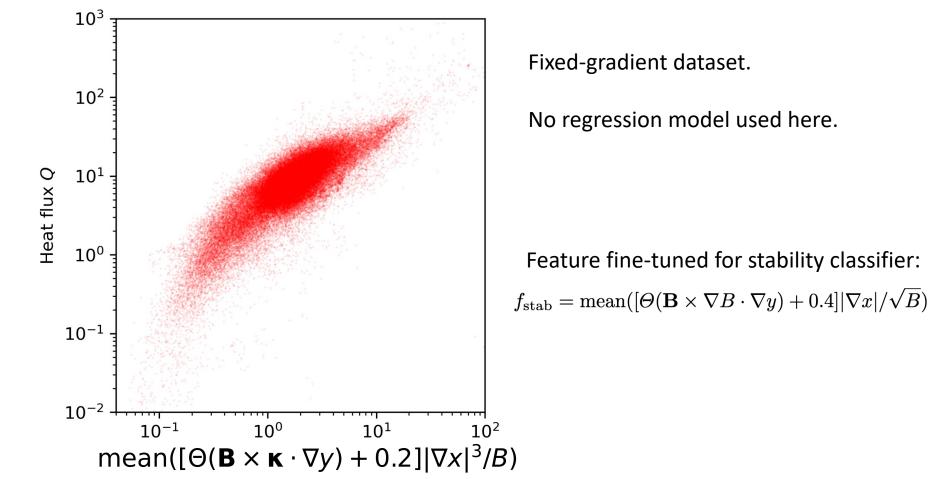


Performance shown on 20% held-out test data

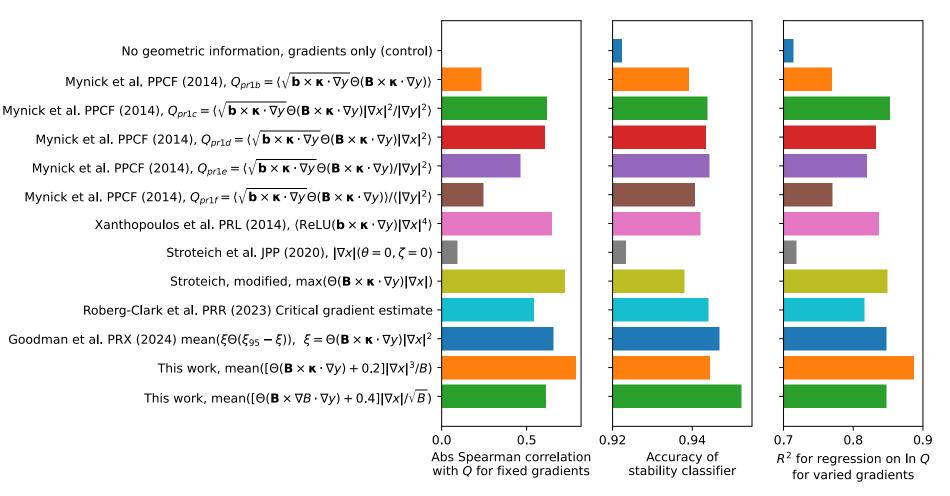
Shapley values show the sign and magnitude of each feature's effect



The first geometric feature can be fine-tuned for even better fit

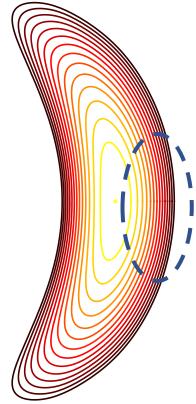


Previously proposed proxies can be tested



Multiple lines of evidence agree that the most important geometric feature is $|\pmb{\nabla}\psi|$ in regions of bad curvature

- Highest Spearman correlation at fixed gradients.
- Consistently the first geometric feature chosen in sequential feature selection:
 - In regression on the heat flux above the critical gradient
 - And in the classifier for stability vs instability (i.e. determines critical gradient)
 - Chosen by XGBoost, nearest-neighbors, & other algorithms
- Also the largest Shapley values



There are many extensions possible

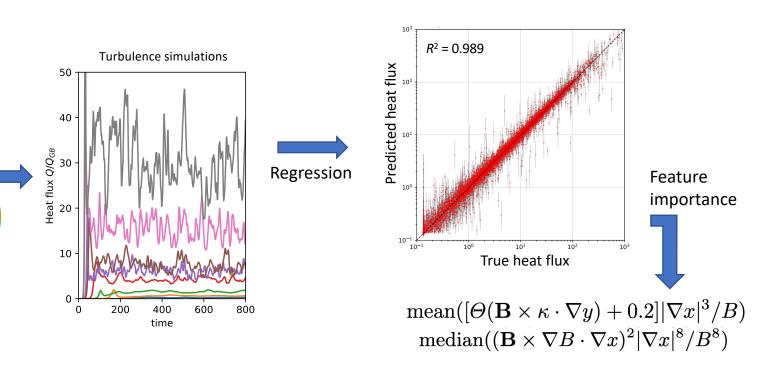
- Try larger sets of possible features
- From the gyrokinetic equation, understand how these features affect turbulence.
- Kinetic electrons, magnetic fluctuations.
- Saliency maps to understand the features learned by the neural networks.
- Symbolic regression.
- Kolmogorov-Arnold Networks.
- Optimization, profile prediction.
- Include & test other physics-motivated features.

Data is online at doi:10.5281/zenodo.14867776, so have a go at it!

Paper: arXiv:2502.11657

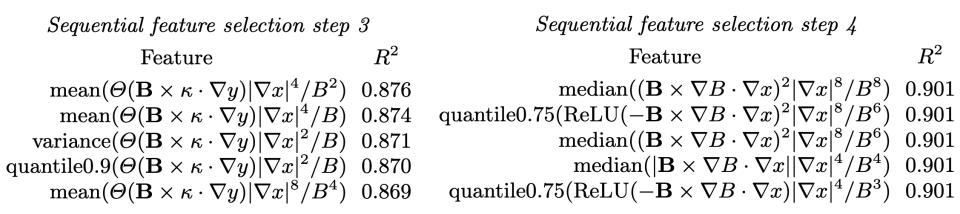
Dataset doi:10.5281/zenodo.14867776





Extra slides

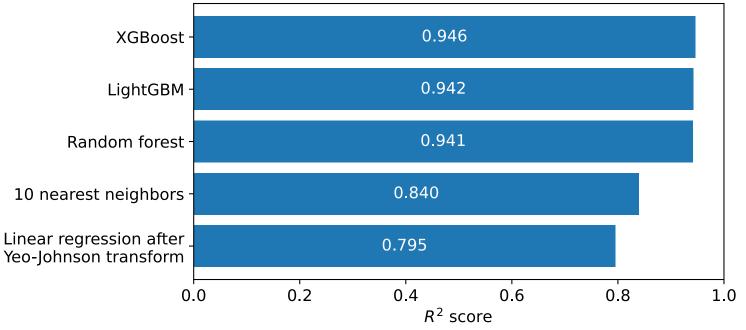
At each step, the top features are variations on a theme



Regression for the random-gradient dataset

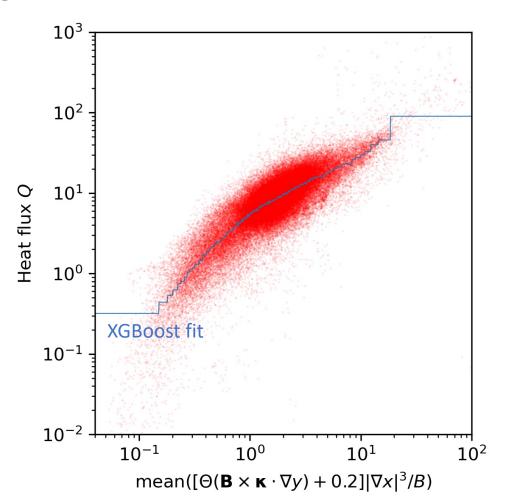
Other machine learning regression methods work also

Comparison of regression methods for random-gradient dataset with 12 features



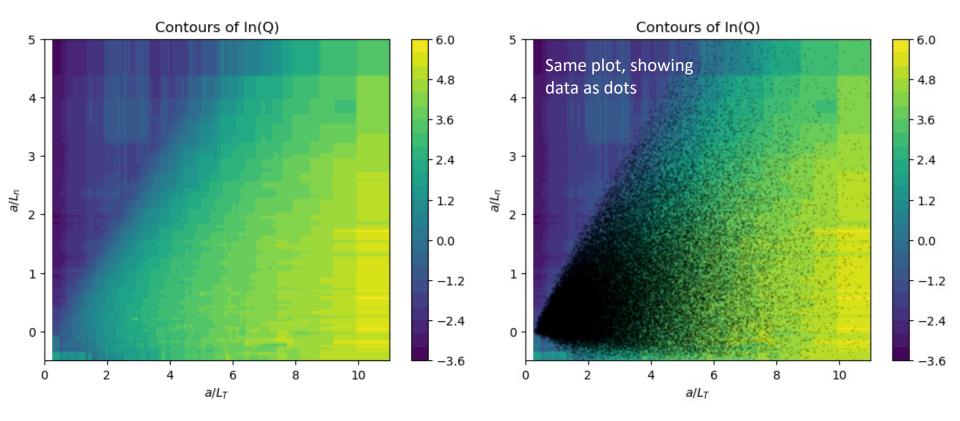
All using $a/L_{\overline{\nu}}$ a/L_{n} , and the top 10 geometric features selected via XGBoost

XGBoost regression model with 1 feature



Fixed-gradient dataset

XGBoost regression model using only a/LT and a/Ln



XGBoost regression model for fixed gradients using 2 features

