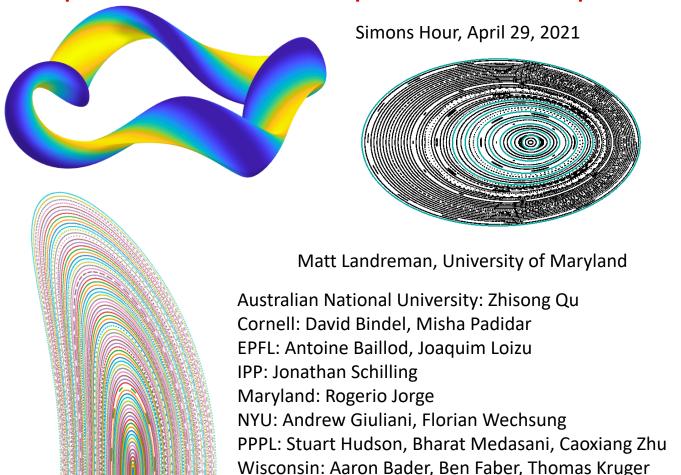
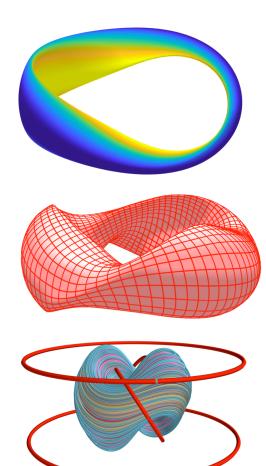
Update on the simsopt stellarator optimization framework





- Vision
- Examples
- Design
- Next steps

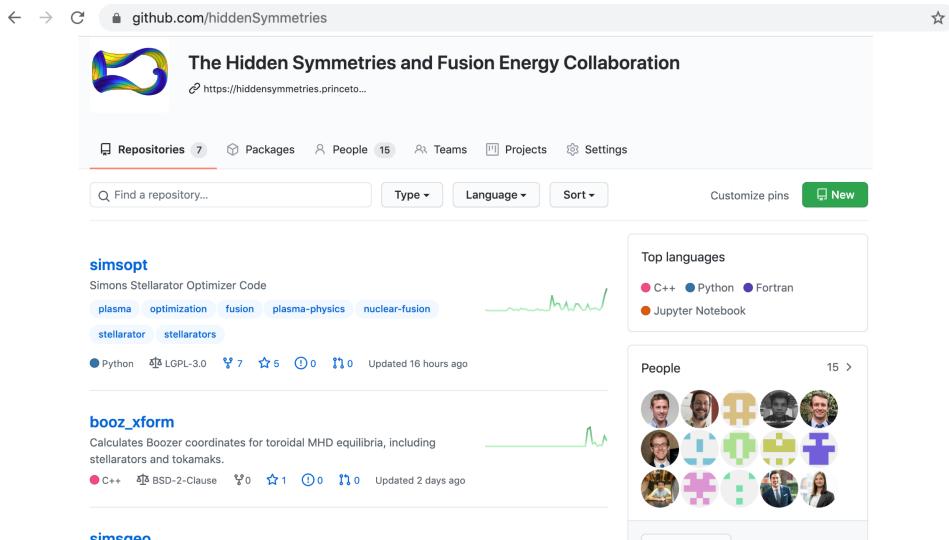
Simsopt vision

- New stellarator optimization software that brings together expertise & code from the whole team & friends.
- Extensibility: It should be possible to add new codes and terms to an objective function without editing the core infrastructure or build system. Any edits to working code can potentially introduce bugs.
- Modularity: Physics modules that are not needed for your optimization problem do not need to be installed.
- Flexibility: Components can be used for many purposes, not just standard optimization.
- Thorough unit testing, regression testing, and continuous integration.

Project with similar goals at Wisconsin: Plasma Equilibrium Toolkit & LASSO.

Simsopt components

- Interfaces to physics codes
- Surface & curve objects, with several parameterizations
- Tools for defining objective function & parameter space, e.g. fixed vs free degrees of freedom
- Fast Biot-Savart implementation, with derivatives
- Parallelized finite differences
- Plotting & graphics





Simsopt documentation

simsopt is a system for optimizing stellarators. The high-level routines are in python, with calls to C++ or fortran where needed for performance. Several types of components are included:

- Interfaces to physics codes, e.g. for MHD equilibrium.
- Tools for defining objective functions and parameter spaces for optimization.
- Geometric objects that are important for stellarators surfaces and curves with several available parameterizations.
- An efficient implementation of the Biot-Savart law, including derivatives.
- Tools for parallelized finite-difference gradient calculations.

Some of the physics modules with compiled code reside in separate repositories. These separate modules include

- VMEC, for MHD equilibrium.
- SPEC, for MHD equilibrium. (This repository is private.)
- booz xform, for Boozer coordinates and quasisymmetry.

The design of simsopt is guided by several principles:

- Thorough unit testing, regression testing, and continuous integration.
- Extensibility: It should be possible to add new codes and terms to the objective function without editing modules that already work, i.e. the open-closed principle. This is because any edits to working code can potentially introduce bugs.
- Modularity: Physics modules that are not needed for your optimization problem do not need to be installed. For instance, to optimize SPEC equilibria, the VMEC module need not be installed.

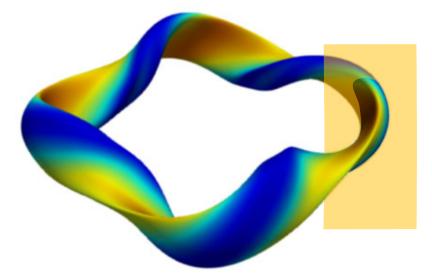
How to get involved

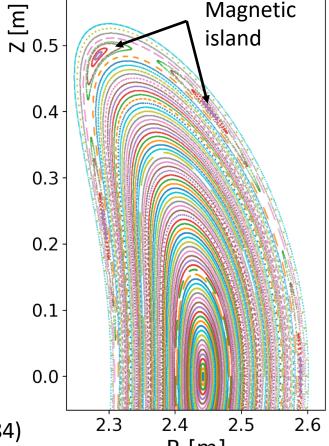
- https://github.com/hiddenSymmetries/simsopt
- Everyone is welcome at development meetings: Mondays @ 9am NY, 3pm Europe
- simsopt slack workspace, #developers channel
- Play around with the code and examples
- Fork the repository, add a feature, submit pull request

- Vision
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Simsopt can optimize SPEC configurations to eliminate magnetic islands

Starting point: a quasi-helically symmetric configuration from Wisconsin [Bader et al (2020)]





We'll minimize Greene's residue, similar to Hanson & Cary (1984)

2.3

2.4

2.5

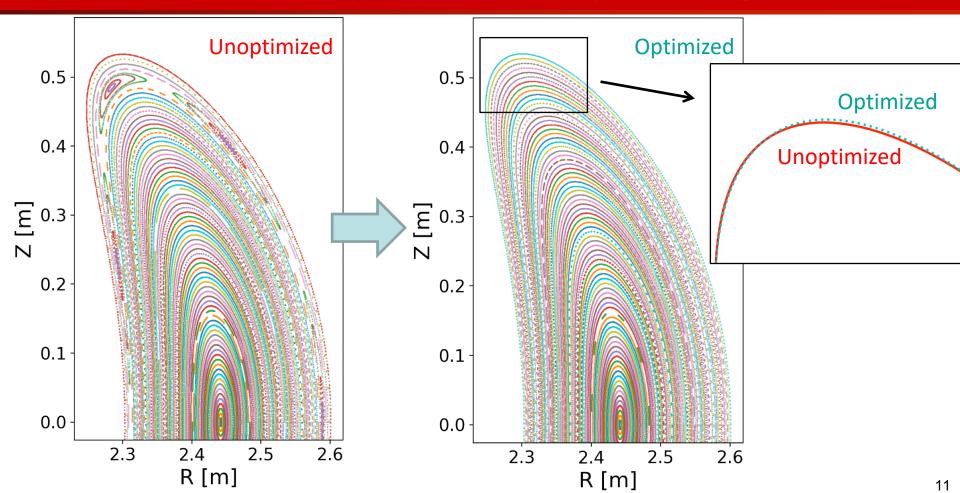
R [m]

Islands can be eliminated by optimizing Greene's residue with simsopt using a high-level python script

```
[w] <sub>0.5</sub>
                                                                          Magnetic
# Create an equilibrium object to optimize:
                                                                          island
spec = Spec('QH-residues.sp')
spec.boundary.change resolution(mpol=12, ntor=12)
                                                          0.4 - 
# Define the parameter space for optimization:
spec.boundary.all fixed()
spec.boundary.set fixed('zs(6,1)', False)
                                                          0.3
# Main island chain has helicity iota = 8/7:
residue1 = Residue(spec, 8, 7)
                                                          0.2
residue2 = Residue(spec, 12, 11)
# Objective function is \sum j residue j ** 2
                                                          0.1 -
prob = LeastSquaresProblem([(residue1, 0, 1),
                              (residue2, 0, 1)))
                                                          0.0 -
least squares serial solve(prob)
                                                                2.3
                                                                      2.4
                                                                            2.5
                                                                                  2.6
```

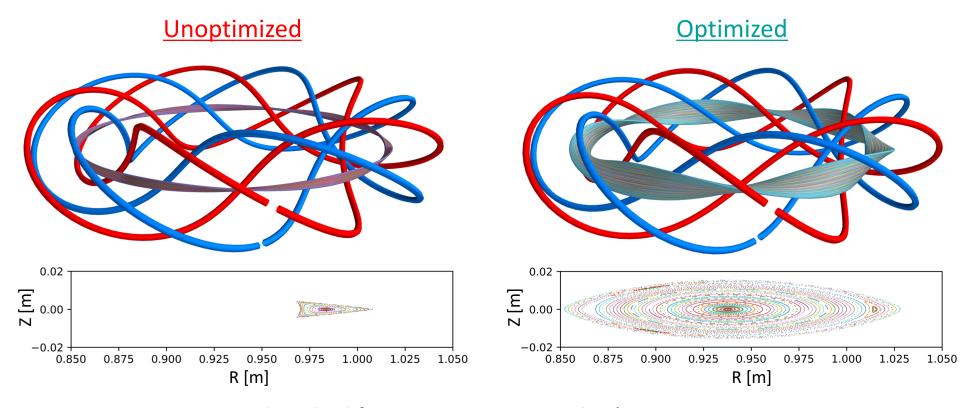
R [m]

Optimization of boundary shape successfully results in good surfaces



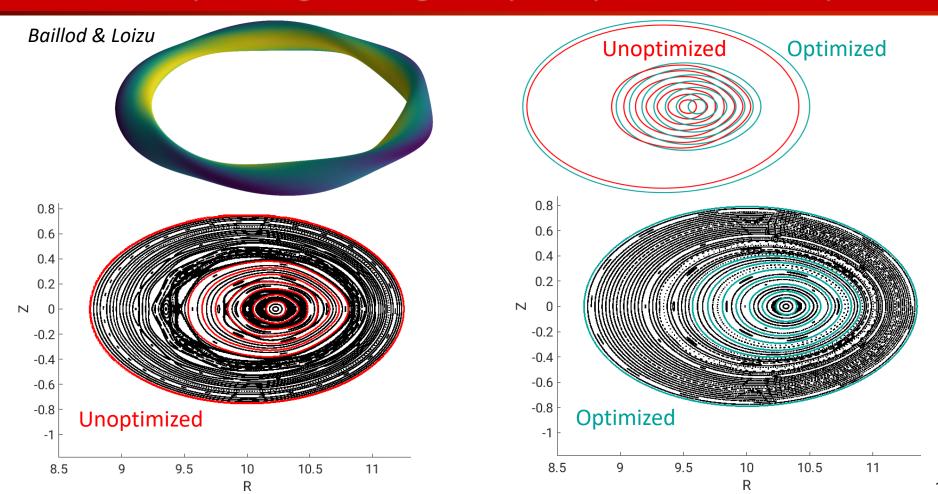
Optimization for good surfaces can also be done in the parameter space of coil shapes rather than the boundary shape

Reproduction of Cary & Hanson (1986) with simsopt by Rogerio Jorge



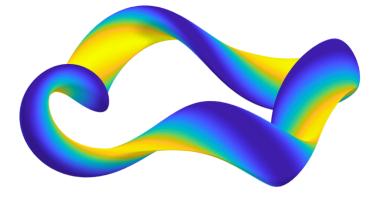
Good testbed for converse KAM, Mather's ΔW, etc.

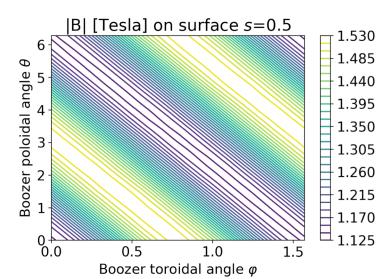
We are now optimizing for integrability with plasma current & pressure



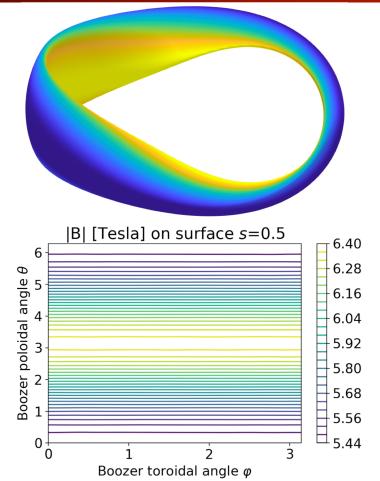
Like STELLOPT & ROSE, SIMSOPT can optimize VMEC configurations for quasisymmetry

```
mpi = MpiPartition()
vmec = Vmec("input.nfp4 QH", mpi)
surf = vmec.boundary
surf.all fixed()
surf.fixed range(mmin=0, mmax=3,
                 nmin=-3, nmax=3, fixed=False)
surf.set fixed("rc(0,0)") # Average major radius
# Set parameters for quasisymmetry objective:
qs = Quasisymmetry(Boozer(vmec),
                   0.5, # Radius to target.
                   1, 1) # (M, N) you want in |B|.
# Define objective function:
prob = LeastSquaresProblem([(qs, 0, 1),
                             (vmec.aspect, 7, 1)])
least squares mpi solve(prob, mpi, grad=True)
```





Scripting allows dynamic increase in resolution during optimization



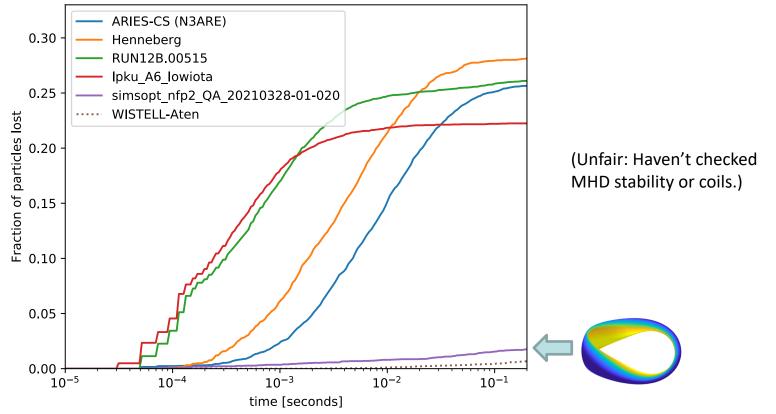
```
surf = vmec.boundary
boozer = Boozer(vmec)
qs = Quasisymmetry(boozer, 0.5, # Radius to target
                   1, 0) # (M, N) you want in |B|
prob = LeastSquaresProblem([(vmec.aspect, 6, 1),
                            (vmec.iota axis, 0.465, 1),
                            (vmec.iota_edge, 0.495, 1),
                            (qs, 0, 1))
for step in range(4):
    vmec.indata.mpol = 3 + step # Increase resolution
    vmec.indata.ntor = vmec.indata.mpol
    boozer.mpol = 16 + step * 8 # Increase resolution
    boozer.ntor = boozer.mpol
    surf.all fixed()
    max mode = step + 1
    surf.fixed range(mmin=0, mmax=max mode,
                     nmin=-max mode, nmax=max mode,
                     fixed=False)
    surf.set fixed("rc(0,0)") # Major radius
    least squares mpi solve(prob, mpi, grad=True)
```

mpi = MpiPartition()

vmec = Vmec("input.nfp2 QA", mpi=mpi)

This QA configuration from simsopt has decent alpha particle confinement

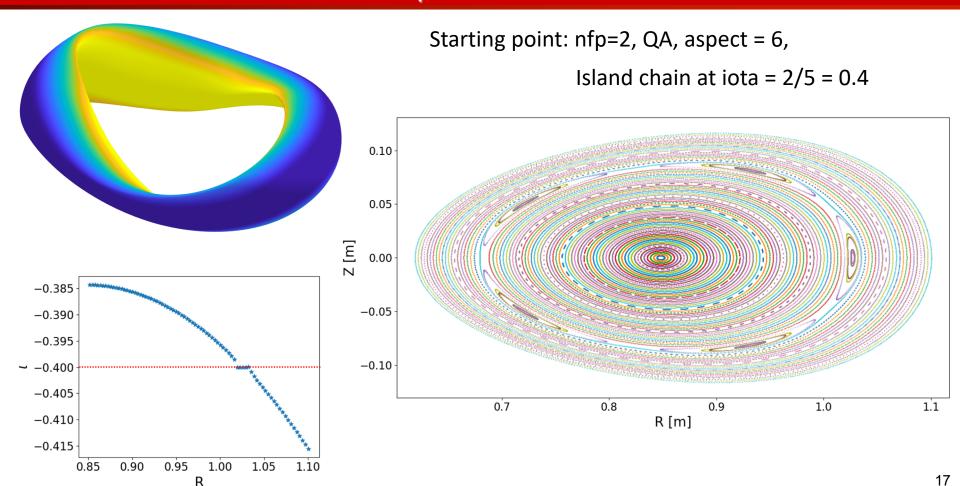
Collisionless losses of alpha particles for particles born at radius s = 0.3



Configurations scaled to the ARIES-CS volume and average |B|.

With Aaron Bader, Sophia Henneberg, Neil Pomphrey

Simsopt can also optimize for quasisymmetry & good surfaces simultaneously, with both VMEC and SPEC in the loop.



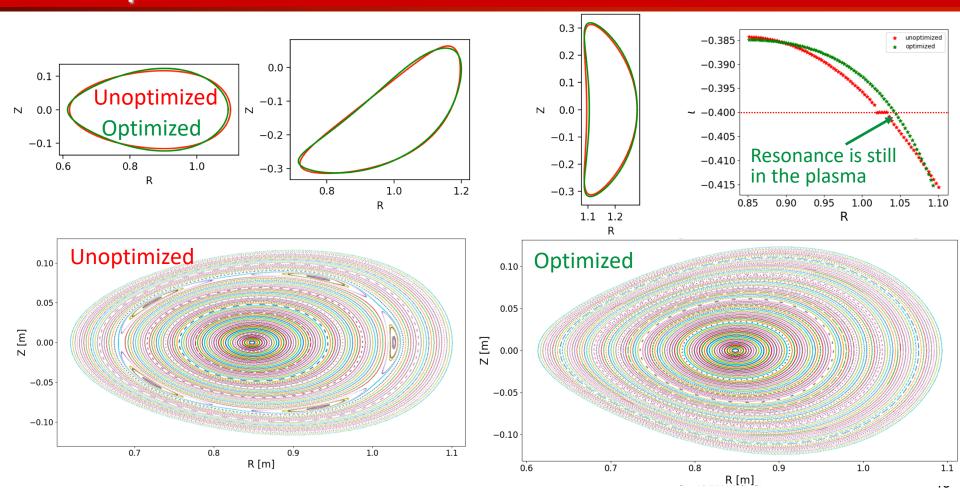
Simsopt driver script applied:

SPEC told to use the same boundary surface object as VMEC.

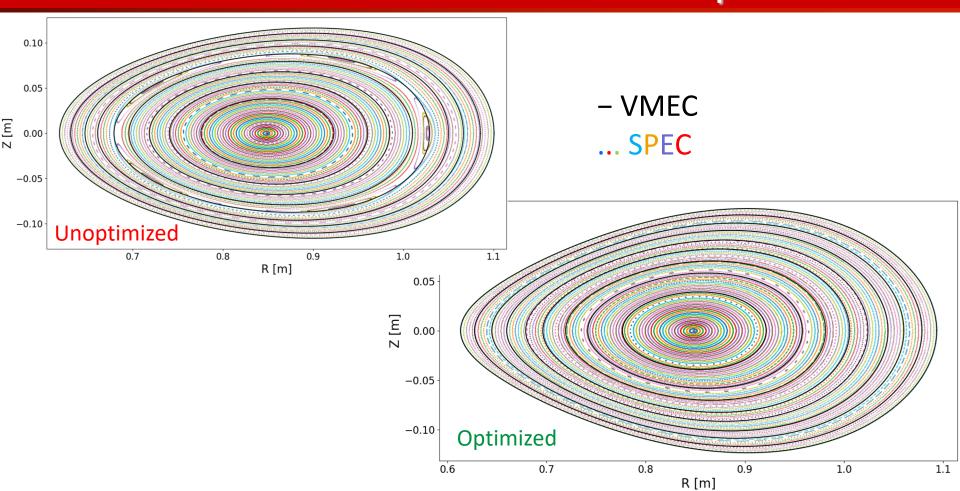
```
vmec = Vmec("input.nfp2 QA")
surf = vmec.boundary
spec = Spec("nfp2 QA.sp")
spec.boundary = surf
Define parameter space:
surf.all fixed()
surf.fixed range(mmin=0, mmax=4,
                nmin=-3, nmax=3, fixed=False)
surf.set fixed("rc(0,0)") # Major radius
qs = Quasisymmetry(Boozer(vmec),
                   0.5, # Radius s to target
                   1, 0) # (M, N) you want in |B|
p = -2; q = 5
residue1 = Residue(spec, p, q)
residue2 = Residue(spec, p, q, theta=np.pi)
# Define objective function
prob = LeastSquaresProblem([(vmec.aspect, 6, 1),
                            (vmec.iota axis, 0.385, 1),
                            (vmec.iota edge 0.415, 1),
                            (qs, 0, 1),
                            (residue1, 0, 2),
                            (residue2, 0, 2)])
least squares serial solve(prob)
```

Objective function includes both quasisymmetry from VMEC + booz_xform and residues from SPEC + pyoculus.

The optimization eliminates the islands



VMEC & SPEC solutions match at the optimum



Quasisymmetry is simultaneously improved during the optimization

 10^{-3}

0.0

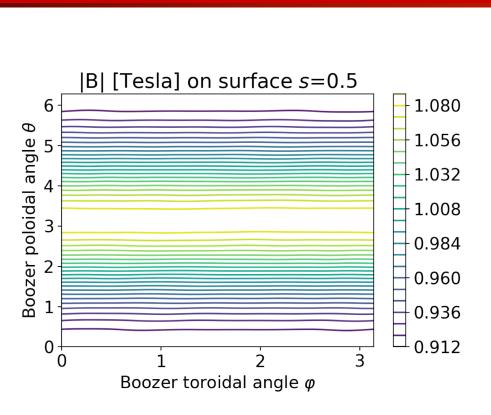
0.2

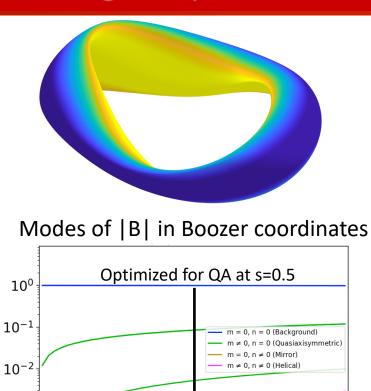
0.4

0.6

s = Normalized toroidal flux

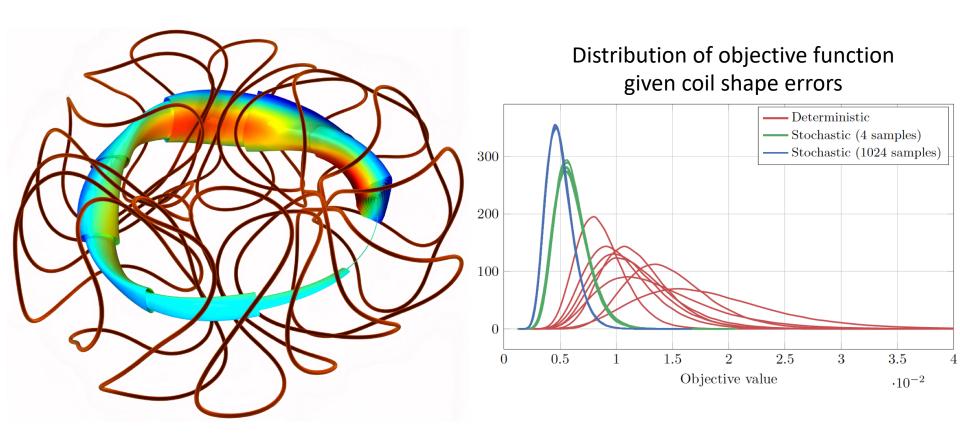
8.0





1.0

Simsopt is used for the NYU derivative-based stochastic coil optimization



Wechsung, Giuliani, et al

Simsopt objective functions can be plugged into outside libraries

```
# E.g., Bayesian global optimization library
# from David Bindel's student:
from turbo import TurboM
From simsopt import LeastSquaresProblem, ...
# Define objective function as in previous slides:
prob = LeastSquaresProblem([(vmec.aspect, 6, 1),
                            (vmec.iota axis, 0.465, 1),
                            (vmec.iota edge, 0.495, 1),
                            (qs, 0, 1)])
turbo = TurboM(prob.objective, ...)
```

turbo.optimize()

- Vision
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Design aspects

- Driver and infrastructure is in python.
- New compiled code is in C++, via pybind11.
- Fortran codes (e.g. VMEC, SPEC) interfaced via f90wrap.

A variety of geometric objects and B field types have been implemented

Curve subclasses:

CurveXYZFourier, CurveRZFourier, CurveHelical, JaxCurveXYZFourier, RotatedCurve

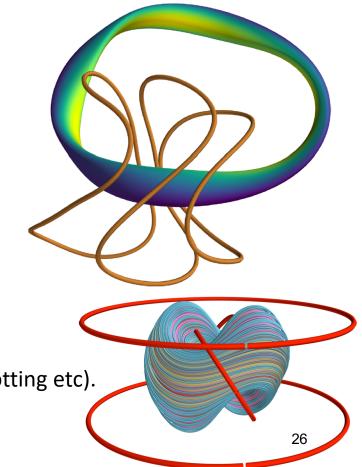
Surface subclasses:

SurfaceRZFourier, SurfaceGarabedian, SurfaceXYZFourier, SurfaceXYZTensorFourier

MagneticField subclasses:

BiotSavart, ToroidalField, CircularCoil, Dommaschk, ScalarPotentialRZMagneticField, MagneticFieldSum

- All include 1 or 2 derivatives.
- All can include code in C++ (for speed) & python (for plotting etc).
- All have caching to avoid repeated calculations.
- Example with automatic differentiation is included.



As an example of a new standalone physics module, booz_xform has been re-written



CONTENTS

Getting started

Theory and numerical implementation

Typical usage

Plotting

API Reference

Developer notes

Source code on GitHub

booz_xform documentation

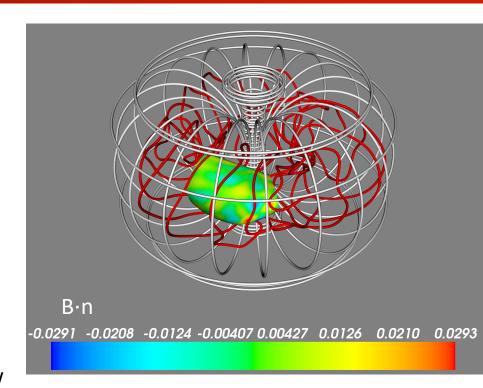
booz_xform is a package for computing Boozer coordinates in toroidal magnetohydrodynamic equilibria, including both stellarators and tokamaks. The package described here follows the same algorithm as the fortran 77 code of the same name in Stellopt. However the package here is written in C++, with python bindings. The package here is also written so as to allow input from equilibrium codes other than VMEC, it is parallelized using OpenMP, and it includes functions for plotting output. It is also equipped with unit and regression tests and continuous integration.

Contents

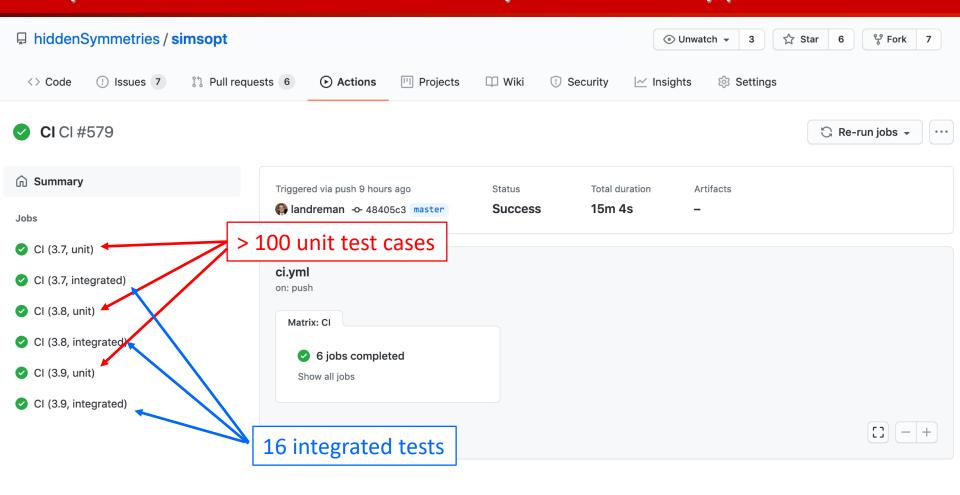
- Getting started
 - Requirements
 - Installation
 - 1. Installation from PyPI
 - 2. Installation from a local copy of the repository
 - 3. Installation without pip from a local copy of the repository
 - 4. Building outside of the python package system
- · Theory and numerical implementation
 - Theory
 - 1. Determining the toroidal angle difference
 - 2. Transforming other quantities
 - o Implementation details

Simsopt is being designed to handle both derivative-free and derivative-based problems

- Curves, surfaces, and magnetic fields all have 1-2 derivatives implemented.
- Curve types with automatic differentiation are implemented.
- Stage-2 coil optimization with derivatives (FOCUS) with simsopt classes works.
- Presently, simsopt handles naïve multiplication of Jacobians for the chain rule.
- In process of updating the system for defining problems with derivatives, to allow user-controlled forward vs reverse-mode chain rule.

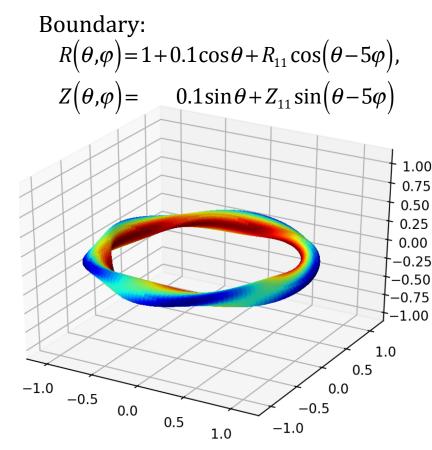


Comprehensive tests are automatically run after every push to GitHub

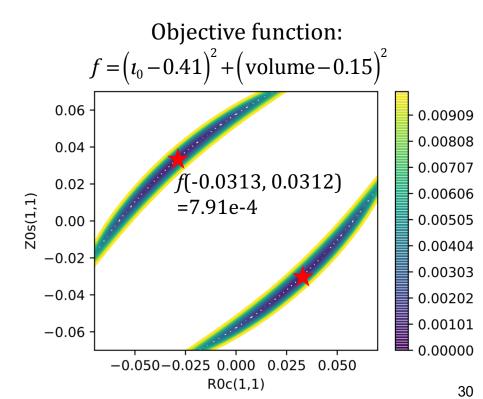


Several benchmark problems have been characterized. Simsopt+spec, simsopt+vmec, and stellopt give the same answer.

github.com/landreman/stellopt_scenarios



Independent variables: $\{R_{11}, Z_{11}\}$



- Vision
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There are many ways you could contribute

- Make sure the infrastructure can handle likely use cases
- Parallel global optimization algorithms
- Multi objective algorithms
- Code up adjoint problems by E Paul & A Geraldini
- Set up a container
- Write mgrid files, free boundary vmec
- Implement more measures of integrability
- Interface more physics objectives & codes
- Connect more equilibrium codes: GVEC, DESC, BIEST
- Interface NYU replacement for BNORM
- Guiding center trajectory integration
- Add more graphing tools

Closing questions

Any suggested modifications to the structure?

What to prioritize next?

Global optimization, multi-objective optimization, adjoints, ...

What other use cases would you like to be able to handle?

Join the project!

- Development meetings: Mondays @ 9am NY, 3pm Europe
- simsopt slack workspace, #developers channel
- mattland@umd.edu