#### What other quantities can we compute in < 1ms from the near-axis expansion?

Goal: Filter out points from this database that are unacceptable for some reason.



- Magnetic well
- Mercier stability criterion
- $\nabla \mathbf{B}$  and  $\nabla \nabla \mathbf{B}$  tensors
- Departure from quasisymmetry
- Aspect ratio at which surfaces become singular.

## Magnetic well

- Related to MHD interchange stability.
- Dominant term in Mercier's criterion near the axis at low  $\beta$ .
- Usually included in stellarator design (W7-X, HSX, LHD, etc)
- Various definitions out there:

$$V'' = \frac{d^2 V}{d\psi^2}, \text{ want } < 0.$$
$$\hat{W} = \frac{V}{\langle B^2 \rangle} \frac{d\langle B^2 \rangle}{dV}, \text{ want } > 0.$$

V = Volume inside flux surface  $2\pi\psi$  = Toroidal flux

$$W = \frac{V}{\left\langle B^2 \right\rangle} \frac{d}{dV} \left\langle 2\mu_0 p + B^2 \right\rangle, \text{ want } > 0.$$

### Magnetic well can be computed directly from the near-axis expansion



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### **Mercier criterion**

Ideal MHD stability to radially localized perturbations (basically interchanges).

Mercier (1964): 
$$M_{G} = \left[\frac{s_{G}}{2}\frac{d\left(1/|l|\right)}{d\Phi} + \int \frac{\mathbf{B}\cdot\mathbf{\Xi} \, dS}{\left|\nabla\Phi\right|^{3}}\right]^{2} + \left[\frac{s_{\iota}s_{\psi}}{\iota^{2}}\frac{dp}{d\Phi}\frac{d^{2}V}{d\Psi^{2}} - \int \frac{\left|\mathbf{\Xi}\right|^{2}dS}{\left|\nabla\Phi\right|^{3}}\right]\int \frac{B^{2}dS}{\left|\nabla\Phi\right|^{3}} > 0$$

 $\Phi = \text{poloidal flux}, \quad \Psi = \text{toroidal flux}, \quad \Xi = \mathbf{J} - \mathbf{B} \frac{dI_{tor}}{d\Psi}, \quad s_G = \text{sgn}(G), \quad s_{\psi} = \text{sgn}(\Psi), \quad s_\iota = \text{sgn}(\iota)$ 

Bauer, Betancourt, & Garabedian (1984):

$$M_{B} = \frac{1}{4} \left( \frac{d\iota}{d\Psi} \right)^{2} - s_{G} \frac{d\iota}{d\Psi} \iint \frac{d\theta d\varphi \left| \sqrt{g} \right| \mathbf{B} \cdot \Xi}{\left| \nabla \Psi \right|^{2}} + \frac{dp}{d\Psi} \left[ s_{\psi} \frac{d^{2}V}{d\Psi^{2}} - \frac{dp}{d\Psi} \iint \frac{d\theta d\varphi \left| \sqrt{g} \right|}{B^{2}} \right] \iint \frac{d\theta d\varphi \left| \sqrt{g} \right| B^{2}}{\left| \nabla \Psi \right|^{2}} + \left[ \iint \frac{d\theta d\varphi \left| \sqrt{g} \right| \mathbf{B} \cdot \mathbf{J}}{\left| \nabla \Psi \right|^{2}} \right]^{2} - \left[ \iint \frac{d\theta d\varphi \left| \sqrt{g} \right| B^{2}}{\left| \nabla \Psi \right|^{2}} \right] \left[ \iint \frac{d\theta d\varphi \left| \sqrt{g} \right| (\mathbf{B} \cdot \mathbf{J})^{2}}{\left| \nabla \Psi \right|^{2} B^{2}} \right] > 0$$

### All statements of Mercier stability Rogerio & I can find do not respect parity transformations

$$\mathbf{B} = \frac{1}{2\pi} \Big( \nabla \Psi \times \nabla \theta + \nabla \varphi \times \nabla \Phi \Big) = \beta \nabla \psi + I \nabla \theta + G \nabla \varphi$$

Parity transformation 1: Flip signs of  $\Psi$ ,  $\theta$ ,  $\beta$ , I,  $\iota$ . Unchanged:  $\varphi$ , G,  $\Phi$ . Parity transformation 2: Flip signs of  $\varphi$ , G,  $\Phi$ ,  $\iota$ . Unchanged:  $\Psi$ ,  $\theta$ ,  $\beta$ , I.

Mercier (1964): 
$$M_{G} = \left[\frac{1}{2}\frac{d(1/\iota)}{d\Phi} + \int \frac{\mathbf{B} \cdot \Xi \, dS}{\left|\nabla\Phi\right|^{3}}\right]^{2} + \left[\frac{1}{\iota^{2}}\frac{dp}{d\Phi}\frac{d^{2}V}{d\Psi^{2}} - \int \frac{\left|\Xi\right|^{2}dS}{\left|\nabla\Phi\right|^{3}}\right] \int \frac{B^{2}dS}{\left|\nabla\Phi\right|^{3}} > 0$$

 $\Phi = \text{poloidal flux}, \quad \Psi = \text{toroidal flux}, \quad \Xi = \mathbf{J} - \mathbf{B} \frac{dI_{tor}}{d\Psi}, \quad s_G = \text{sgn}(G), \quad s_{\psi} = \text{sgn}(\Psi), \quad s_\iota = \text{sgn}(\iota)$ 

Invariant: 
$$M_{G} = \left[\frac{s_{G}}{2}\frac{d(1/|\iota|)}{d\Phi} + \int \frac{\mathbf{B}\cdot\Xi \, dS}{\left|\nabla\Phi\right|^{3}}\right]^{2} + \left[\frac{s_{\iota}s_{\psi}}{\iota^{2}}\frac{dp}{d\Phi}\frac{d^{2}V}{d\Psi^{2}} - \int \frac{\left|\Xi\right|^{2}dS}{\left|\nabla\Phi\right|^{3}}\right]\int \frac{B^{2}dS}{\left|\nabla\Phi\right|^{3}} > 0$$

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### All statements of Mercier stability Rogerio & I can find do not respect parity transformations

$$\mathbf{B} = \frac{1}{2\pi} \Big( \nabla \Psi \times \nabla \theta + \nabla \varphi \times \nabla \Phi \Big) = \beta \nabla \psi + I \nabla \theta + G \nabla \varphi$$

Parity transformation 1: Flip signs of  $\Psi$ ,  $\theta$ ,  $\beta$ , I,  $\iota$ . Unchanged:  $\varphi$ , G,  $\Phi$ .

Parity transformation 2: Flip signs of  $\varphi$ , *G*,  $\Phi$ , *ι*. Unchanged:  $\Psi$ ,  $\theta$ ,  $\beta$ , *I*.

Is there a slick way to get a parity-transformation-  
invariant form of Mercier's criterion?
$$2^{-a\Psi}$$
 $\nabla \Phi$  $1^{-a\Psi a\Psi}$  $\nabla \Phi$ 

 $\Phi = \text{poloidal flux}, \quad \Psi = \text{toroidal flux}, \quad \Xi = \mathbf{J} - \mathbf{B} \frac{dI_{tor}}{d\Psi}, \quad s_G = \text{sgn}(G), \quad s_{\psi} = \text{sgn}(\Psi), \quad s_\iota = \text{sgn}(\iota)$ 

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### **∇B** and **∇∇B** tensors

- And rew Giuliani targets  $\nabla B$  in his direct coil optimization for QS.
- These tensors contain all possible scale lengths in the 1<sup>st</sup> and 2<sup>nd</sup> derivatives of the field. These should probably be long in order to make this **B** with distant coils.

$$L_{\nabla B} = B \sqrt{\frac{2}{\nabla \mathbf{B} : \nabla \mathbf{B}}} \qquad \qquad L_{\nabla \nabla B} = \sqrt{\frac{4B}{\sqrt{\sum_{i,j,k=1}^{3} (\nabla \nabla \mathbf{B})_{i,j,k}^{2}}}}$$

At a distance *R* from an infinite straight wire,  $L_{\nabla B} = L_{\nabla \nabla B} = R$ .

### Garren-Boozer **∇B**

$$\nabla \mathbf{B} = \frac{B_0}{\ell'} \Big[ \Big( X_{1c}' Y_{1s} + \iota X_{1c} Y_{1c} \Big) \mathbf{nn} + \Big( -\ell' \tau - \iota X_{1c}^2 \Big) \mathbf{bn} \\ + \Big( Y_{1c}' Y_{1s} - Y_{1s}' Y_{1c} + \ell' \tau + \iota Y_{1s}^2 + \iota Y_{1c}^2 \Big) \mathbf{nb} + \Big( X_{1c} Y_{1s}' - \iota X_{1c} Y_{1c} \Big) \mathbf{bb} \Big] + \kappa B_0 \Big( \mathbf{tn} + \mathbf{nt} \Big) \Big] \Big]$$

Frenet frame: 
$$(\mathbf{t}, \mathbf{n}, \mathbf{b})$$
  $\ell' = (axis length) / (2\pi)$   $Y'_{1s} = dY_{1s} / d\varphi$ 

$$\mathbf{x}(r,\theta,\varphi) = \mathbf{x}_0(\varphi) + rX_{1c}(\varphi)\cos\theta \mathbf{n} + r\left[Y_{1c}(\varphi)\cos\theta + Y_{1s}(\varphi)\sin\theta\right]\mathbf{b} + O(r^2)$$

## 5 configurations to compare



## These tensor norms seem correlated with intuition for how hard these configurations are to shape



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# How can we compute the aspect ratio at which surfaces are no longer smooth & nested?



# How can we compute the aspect ratio at which surfaces are no longer smooth & nested?

$$\sqrt{g} = 0 \qquad \frac{\partial \sqrt{g}}{\partial \theta} = 0 \qquad \frac{\partial \sqrt{g}}{\partial \varphi} = 0 \qquad \sqrt{g} = \frac{\partial \mathbf{x}}{\partial r} \cdot \frac{\partial \mathbf{x}}{\partial \theta} \times \frac{\partial \mathbf{x}}{\partial \varphi}$$
$$\mathbf{x}(r,\theta,\varphi) = \mathbf{x}_0(\varphi) + X(r,\theta,\varphi)\mathbf{n}(\varphi) + Y(r,\theta,\varphi)\mathbf{b}(\varphi) + Z(r,\theta,\varphi)\mathbf{t}(\varphi)$$
$$X = r \Big[ X_{1s}(\varphi)\sin\theta + X_{1c}(\varphi)\cos\theta \Big] + r^2 \Big[ X_{20}(\varphi) + X_{2s}(\varphi)\sin2\theta + X_{2c}(\varphi)\cos2\theta \Big]$$
$$\sqrt{g} = r \Big[ g_0(\varphi) + rg_1(\theta,\varphi) + r^2 g_2(\theta,\varphi) + r^3 g_3(\theta,\varphi) + r^4 g_4(\theta,\varphi) \Big]$$
$$g_1(\theta,\varphi) = g_{1s}(\varphi)\sin\theta + g_{1c}(\varphi)\cos\theta$$
$$g_2(\theta,\varphi) = g_{20}(\varphi) + g_{2s}(\varphi)\sin2\theta + g_{2c}(\varphi)\cos2\theta$$
$$g_3(\theta,\varphi) = g_{3s1}(\varphi)\sin\theta + g_{3s3}(\varphi)\sin3\theta + g_{3c1}(\varphi)\cos\theta + g_{3c3}(\varphi)\cos3\theta$$

# How can we compute the aspect ratio at which surfaces are no longer smooth & nested?

$$\sqrt{g} = 0$$
  $\frac{\partial \sqrt{g}}{\partial \theta} = 0$   $\frac{\partial \sqrt{g}}{\partial \varphi} = 0$  Can replace last equation with min over  $\varphi$ .

- Could solve with Newton method, but need good initial guess or else not robust.
- Worried most about small-*r* solutions, so may be reasonable to set  $g_3=g_4=0$ .
- Then system has analytic solution. Can use as initial guess for Newton with  $g_3 \& g_4$ .

$$\sqrt{g} = r \Big[ g_0(\varphi) + r g_1(\theta, \varphi) + r^2 g_2(\theta, \varphi) + r^3 g_3(\theta, \varphi) + r^4 g_4(\theta, \varphi) \Big]$$

$$g_{1}(\theta,\varphi) = g_{1s}(\varphi)\sin\theta + g_{1c}(\varphi)\cos\theta$$
$$g_{2}(\theta,\varphi) = g_{20}(\varphi) + g_{2s}(\varphi)\sin2\theta + g_{2c}(\varphi)\cos2\theta$$
$$g_{3}(\theta,\varphi) = g_{3s1}(\varphi)\sin\theta + g_{3s3}(\varphi)\sin3\theta + g_{3c1}(\varphi)\cos\theta + g_{3c3}(\varphi)\cos3\theta$$

## This approach of generating initial guesses for Newton iteration works sometimes but not always







## This approach of generating initial guesses for Newton iteration works sometimes but not always



## **Closing questions**

- Is there a slicker way to get a parity-transformation-invariant form of Mercier's criterion?
- Is there anything else useful we can do with these  $\nabla B$  and  $\nabla \nabla B$  tensors?
- Are there other measures of **B** field complexity / coil difficulty?
- If we strive for QS to O(r<sup>2</sup>), can we compute the symmetry-breaking error at O(r<sup>3</sup>)? (So much algebra!!)
- Is there a better / more robust way to compute the minimum aspect ratio?
- What else can we compute in < a few ms?