Constructing magnetic fields with hidden symmetry



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arXiv:1809.10246

https://github.com/landreman/quasisymmetry

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The conventional approach to finding quasisymmetric fields works but has shortcomings

Want magnetic field strength *B* to have quasisymmetry: $B = B(r, \theta - N\zeta)$



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 $\min_{X} f(X)$

Parameter space: X = toroidal boundary shapes

Objective:
$$f = \sum_{m,n \neq Nm} B_{m,n}^2(r_0)$$
 where $B(r,\theta,\zeta) = \sum_{m,n} B_{m,n}(r) \exp(im\theta - in\zeta)$

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- Computationally expensive.
- What is the size & character of the solution space?
- Result depends on initial condition, so cannot be sure you've found all solutions.

Alternative: expand equations near the magnetic axis



Mercier (1964), Lortz & Nührenberg (1976), Garren & Boozer (1991)

Using the near-axis expansion, we can directly construct quasisymmetric B fields



• Generate good initial conditions for optimization.

Outline

- Construction for *O*(*r*) quasisymmetry
 - Theory, & the number of solutions
 - Numerical results
 - Comparison to "real experiments"
 - The landscape of solutions
- Extensions
 - Omnigenity
 - $O(r^2)$ quasisymmetry

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We will expand in the skinniness of the inner flux surfaces



Even for a low aspect ratio stellarator, this expansion describes the core



A key ingredient of the theory is the Frenet frame of the magnetic axis

Frenet frame
$$(\mathbf{t}, \mathbf{n}, \mathbf{b})$$
: $\frac{d\mathbf{x}_0}{d\ell} = \mathbf{t}$, $\frac{d\mathbf{t}}{d\ell} = \kappa \mathbf{n}$, $\frac{d\mathbf{n}}{d\ell} = -\kappa \mathbf{t} + \tau \mathbf{b}$, $\frac{d\mathbf{b}}{d\ell} = -\tau \mathbf{n}$
 $\mathbf{x}_0 = \text{magnetic axis}$, $\kappa = \text{curvature}$, $\tau = \text{torsion}$, $\mathbf{t} = \text{tangent}$, $\mathbf{n} = \text{normal}$, $\mathbf{b} = \text{binormal}$



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Theory: Write position vector **x** using axis's Frenet frame, expand in small *r*

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 $\mathbf{J} \times \mathbf{B} = \nabla p$, $B = B(r, \theta - N\zeta)$, $\mathbf{x} = \mathbf{x}_0 + O(r)$
 $\stackrel{-\text{Magnetic axis}}{\longrightarrow} = \text{Tangent}$
 $-\text{Normal}$
 $= \text{Binormal}$

Theory: Write position vector **x** using axis's Frenet frame, expand in small r

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 $\mathbf{x}(r, \theta, \zeta) = \mathbf{x} \ (\zeta) + r \frac{\overline{\eta}}{\langle \zeta \rangle} \cos \vartheta \mathbf{n}(\zeta) + r \left[\frac{\kappa(\zeta)}{\zeta} \sin \vartheta + \frac{\sigma(\zeta)\kappa(\zeta)}{\zeta} \cos \vartheta \right] \mathbf{b}(\zeta) + O(r^2)$

$$\mathbf{x}(r,\theta,\zeta) = \mathbf{x}_0(\zeta) + r\frac{\overline{\eta}}{\kappa(\zeta)}\cos\vartheta\mathbf{n}(\zeta) + r\left[\frac{\kappa(\zeta)}{\overline{\eta}}\sin\vartheta + \frac{\sigma(\zeta)\kappa(\zeta)}{\overline{\eta}}\cos\vartheta\right]\mathbf{b}(\zeta) + O(r^2)$$

Toroidal angle $\zeta \propto axis$ arclength ℓ , \overline{r}

$$\frac{d\sigma}{d\zeta} + \iota \left[\frac{\overline{\eta}^4}{\kappa^4} + 1 + \sigma^2\right] - 2\frac{\overline{\eta}^2}{\kappa^2} \left[I_2 - \tau\right] = 0$$

$$\overline{\eta} = \text{constant:} B = B_0 \Big[1 + r\overline{\eta}\cos\vartheta + O(r^2) \Big]$$

$$\vartheta = \theta - N\zeta$$
,

l = rotational transform on axis,

$$I_2 =$$
 current density on axis

The size of the space of fields that are quasisymmetric to O(r) can be precisely understood.

Given
$$P(\zeta) > 0$$
, $Q(\zeta)$, and $\sigma(0)$, with $P(\zeta)$ and $Q(\zeta)$

 2π -periodic, bounded, and integrable, a solution to

$$\frac{d\sigma}{d\zeta} + \iota \left(P + \sigma^2 \right) + Q = 0 \qquad (1)$$

is a pair $\{\iota, \sigma(\zeta)\}$ solving (1) where $\sigma(\zeta)$ is 2π -periodic.

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Theorem: A solution exists and it is unique.

ML, Sengupta, and Plunk (2019). Probably an earlier reference?

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is a pair $\{\iota, \sigma(\zeta)\}$ solving (1) where $\sigma(\zeta)$ is 2π -periodic.

Theorem: A solution exists and it is unique.

 \Rightarrow Numerical solution is very robust.

The theorem informs an algorithm for constructing quasisymmetric fields

<u>Inputs:</u>

- Shape of the magnetic axis.
- 3 real numbers:
 - I_2 : Current density on the axis. (Usually 0).
 - $\sigma(0)$: Rotation of the elliptical flux surfaces at toroidal angle=0.
 - $\overline{\eta}$, which controls elongation and field strength: $B = B_0 \left| 1 + r\overline{\eta} \cos \vartheta + O(r^2) \right|$
- (Pressure doesn't matter to this order.)

<u>Outputs:</u>

- Shape of the surfaces around the axis. (Elongation & rotation of ellipses.)
- Rotational transform on axis.

Quasi-axisymmetry vs quasi-helical symmetry is determined purely by the axis normal vector

$$\mathbf{J} \times \mathbf{B} = \nabla \mathbf{p} \qquad \Rightarrow \qquad \nabla_{\perp} B = B \kappa \mathbf{n}$$

So *B* contours rotate about axis with the same topology as **n**.

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$$\mathbf{J} \times \mathbf{B} = \nabla \mathbf{p} \qquad \Rightarrow \qquad \nabla_{\perp} B = B \kappa \mathbf{n}$$

So *B* contours rotate about axis with the same topology as **n**.



n does not rotate about the axis as you follow the axis around.

 \Rightarrow Quasi-axisymmetry

 $B = B(r, \theta)$

n rotates about the axis 4 times as you follow the axis around.

 \Rightarrow Quasi-helical symmetry

$$B = B(r, \theta - 4\zeta)$$

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Example construction: quasi-axisymmetry

Inputs:

axis shape
$$R_0(\phi) = 1 + 0.045 \cos(3\phi)$$
,
 $Z_0(\phi) = -0.045 \sin(3\phi)$,

$$I_2 = 0, \qquad \overline{\eta} = -0.9.$$

$$\sigma(0) = 0,$$

<u>Results</u>: (R/a = 10)|B 0.2 **—** φ = **0** $-\phi = \pi/6$ 1.1 $-\phi = \pi/3$ 0.1 $-\phi = \pi/2$ 1.05 Ν 0 1 -0.1 0.95 -0.2 0.8 1.1 0.9 1 0.9 R

The construction can be verified by comparing to an MHD equilibrium calculation that does not make the *r* expansion.



Alternative method to generate a finite-thickness boundary: find coils to make a skinny surface, then see what you get outside.



Example construction: Quasi-helical symmetry

Inputs:

axis shape
$$R_0(\phi) = 1 + 0.265 \cos(4\phi),$$
 $I_2 = 0,$ $\overline{\eta} = -2.25.$
 $Z_0(\phi) = -0.21 \sin(4\phi),$ $\sigma(0) = 0,$



The construction can be verified by comparing to an MHD equilibrium calculation that does not make the *r* expansion.



All stellarators built to date have 'stellarator symmetry', which is unrelated to quasisymmetry



Sugama et al (2011)

You can make a quasi-axisymmetric stellarator without stellarator symmetry

Inputs: axis shape
$$R_0(\phi) = 1 + 0.042\cos(3\phi)$$
, $I_2 = 0$, $\overline{\eta} = -1.1$.
 $Z_0(\phi) = -0.042\sin(3\phi) - 0.025\cos(3\phi)$, $\sigma(0) = -0.6$,



You can make a quasi-axisymmetric stellarator without stellarator symmetry



The symmetry-breaking Fourier amplitudes scale as predicted.



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- Adopt the same axis shape.
- Fit $\overline{\eta}$ to minimize difference in the shapes of a near-axis surface.

The direct construction gives an accurate match to the on-axis rotational transform in quasisymmetric stellarators designed by optimization

- Adopt the same axis shape.
- Fit $\overline{\eta}$ to minimize difference in the shapes of a near-axis surface.



Quasi-helically symmetric configurations

Dotted: VMEC equilibrium Solid: Garren-Boozer construction



Quasi-axisymmetric configurations

Dotted: VMEC equilibrium Solid: Garren-Boozer construction



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The construction enables fast scans over parameter space.



The fast construction enables brute-force surveys of "all" quasisymmetric fields





The fast construction enables brute-force surveys of "all" quasisymmetric fields

Axis shape:
$$R_0(\phi) = 1 + \sum_{j=1}^{3} R_j \cos(jn_{fp}\phi), \quad Z_0(\phi) = 1 + \sum_{j=1}^{3} Z_j \sin(jn_{fp}\phi)$$
 4x10⁶ configurations



Brute-force searching is already yielding some new configurations

Quasi-helical symmetry with

1 field period

2 field periods



Brute-force searching is already yielding some new configurations

Quasi-helical symmetry with



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Omnigenity is a weaker confinement condition than quasisymmetry.

Definition of omnigenity: The radial drift has a time average of 0 for all particles. $\oint (\mathbf{v}_d \cdot \nabla r) dt = 0 \quad \forall \text{ magnetic moments \& energies.}$

- J Cary & S Shasharina, *Physics of Plasmas* **4**, 3323 (1997).
- J Cary & S Shasharina, *Physical Review Letters* **78**, 674 (1997).
- P Helander & J Nührenberg, *Plasma Physics and Controlled Fusion* 51, 055004 (2009).
- M Landreman & P J Catto, *Physics of Plasmas* **19**, 056103 (2012).

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The near-axis analysis can be generalized to construct omnigenous configurations



B

1.4

1.3

1.2

1.1

0.9

0.8

0.7

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Extending the construction to higher order is tricky

- We can only "half-specify" the axis shape:
 - A curve like the axis is given by 2 functions, e.g. {curvature, torsion} or $\{R(\phi), Z(\phi)\}$.
 - At O(r), (# unknowns)-(# equations)=2 so we can specify (almost) any axis. But at $O(r^2)$, (# unknowns)-(# equations)=1 so we cannot.

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 - At O(r), (# unknowns)-(# equations)=2 so we can specify (almost) any axis. But at $O(r^2)$, (# unknowns)-(# equations)=1 so we cannot.
- No existence & uniqueness theorem for solutions (yet).
- Magnetic shear (variation of rotational transform) does not appear until $O(r^3)$.

We are working to extend the construction to O(r²), enabling greater shaping



Questions – your input is welcome!

- How can coils be connected to this model?
 - Since we know B and ∇B along the axis, can we say anything about how close coils must be?
- Are there other ways to extrapolate outward from the axis? E.g. Laplace's equation as initial value problem in *r*, with regularization.
- It is effective to optimize in the space of axis shapes? (H Mynick).
- For $O(r^2)$, how do you best half-specify the axis shape? Can anything be proved about the number or character of $O(r^2)$ solutions?
- Is there an analogous construction to give quasisymmetry at an off-axis surface?

Conclusions

- The equations for quasisymmetric magnetic fields can be solved directly (without optimization) if you expand about the magnetic axis.
- The resulting construction can be useful for generating new initial conditions for optimization.
- We precisely understand the size of the space of magnetic fields that are quasisymmetric near the axis (i.e. to O(r)).
- The construction is consistent with configurations obtained by optimization.
- There is hope of definitively identifying all classes of practical quasisymmetric fields (near the axis).

https://github.com/landreman/quasisymmetry

Extra slides

We will expand in the skinniness of the inner flux surfaces





Theory: Write position vector using Frenet frame

Frenet frame
$$(\mathbf{t}, \mathbf{n}, \mathbf{b})$$
: $\frac{d\mathbf{r}_0}{d\ell} = \mathbf{t}$, $\frac{d\mathbf{t}}{d\ell} = \kappa \mathbf{n}$, $\frac{d\mathbf{n}}{d\ell} = -\kappa \mathbf{t} + \tau \mathbf{b}$, $\frac{d\mathbf{b}}{d\ell} = -\tau \mathbf{n}$
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 $\mathbf{r}(r, \theta, \zeta) = \mathbf{r}_0(\zeta) + X(r, \theta, \zeta) \mathbf{n}(\zeta) + Y(r, \theta, \zeta) \mathbf{b}(\zeta) + Z(r, \theta, \zeta) \mathbf{t}(\zeta)$
 $- \text{Magnetic axis}$
 $- \text{Tangent}$
 $- \text{Normal}$
 $- \text{Binormal}$

Theory: Write position vector using Frenet frame, expand in small $r = (flux)^{1/2}$

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 $= \mathbf{r}_0(\zeta) + rX_{1c}(\zeta) \cos\theta \mathbf{n}(\zeta) + r[Y_{1s}(\zeta) \sin\theta + Y_{1c}(\zeta) \cos\theta] \mathbf{b}(\zeta) + O(r^2)$

Using magnetohydrodynamic equilibrium
$$(\mathbf{J} \times \mathbf{B} = \nabla p)$$

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 $X_{1c}(\zeta) = \frac{\overline{\eta}}{\kappa(\zeta)}$, $Y_{1s}(\zeta) = \frac{\kappa(\zeta)}{\overline{\eta}}$, $Y_{1c}(\zeta) = \frac{\sigma(\zeta)\kappa(\zeta)}{\overline{\eta}}$
Toroidal angle ζ wandows the second state \overline{n} = constant: $\overline{n} = R \left[1 + n\overline{n} \csc(\theta - N_{0}) + O(r^{2}) \right]$

Toroidal angle $\zeta \propto \operatorname{arclength}, \quad \overline{\eta} = \operatorname{constant}: B = B_0 \left[1 + r\overline{\eta} \cos(\theta - N\varphi) + O(r^2) \right]$

$$\frac{d\sigma}{d\zeta} + \iota \left[\frac{\overline{\eta}^4}{\kappa^4} + 1 + \sigma^2\right] - 2\frac{\overline{\eta}^2}{\kappa^2} \left[I_2 - \tau\right] = 0$$

 $I_2 =$ current density

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$$\mathbf{r}(r,\theta,\zeta) = \mathbf{r}_0(\zeta) + X(r,\theta,\zeta)\mathbf{n}(\zeta) + Y(r,\theta,\zeta)\mathbf{b}(\zeta) + Z(r,\theta,\zeta)\mathbf{t}(\zeta)$$

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$$X(r,\theta,\zeta) = r \Big[X_{1s}(\zeta)\sin\theta + X_{1c}(\zeta)\cos\theta \Big] + O(r^2). \quad \text{Same for } Y, Z.$$

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$$X(r,\theta,\zeta) = r \Big[X_{1s}(\zeta)\sin\theta + X_{1c}(\zeta)\cos\theta \Big] + O(r^{2}). \quad \text{Same for } Y, Z.$$
$$\mathbf{B} = B_{r}\nabla r + B_{\theta}\nabla\theta + B_{\zeta}\nabla\zeta, \qquad \mathbf{B} = \nabla\psi \times \nabla\theta + \iota\nabla\zeta \times \nabla\psi$$

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$$X(r,\theta,\zeta) = r \Big[X_{1s}(\zeta) \sin \theta + X_{1c}(\zeta) \cos \theta \Big] + O(r^2). \quad \text{Same for } Y, Z.$$

$$\mathbf{B} = B_r \nabla r + B_\theta \nabla \theta + B_\zeta \nabla \zeta , \qquad \mathbf{B} = \nabla \psi \times \nabla \theta + \iota \nabla \zeta \times \nabla \psi$$

Dual relations: $\nabla r = \left[\frac{\partial \mathbf{r}}{\partial r} \cdot \frac{\partial \mathbf{r}}{\partial \theta} \times \frac{\partial \mathbf{r}}{\partial \zeta}\right]^{-1} \frac{\partial \mathbf{r}}{\partial \theta} \times \frac{\partial \mathbf{r}}{\partial \zeta}$, cyclic permutations.

The rotational transform computed by VMEC converges to the value computed by the Garren-Boozer approach.



Difference in rotational transform ι between VMEC vs ODE

The ODE is solved with spectral accuracy using pseudospectral discretization + Newton iteration

Uniform grid in
$$\phi$$
 with N points: $\phi_1 = 0$, $\phi_2 = 2\pi / (Nn_{fp})$, ..., $\phi_N = 2\pi (N-1) / (Nn_{fp})$.
Vector of N unknowns: $(\iota, \sigma(\phi_2), \sigma(\phi_3), ..., \sigma(\phi_N))^T$
 N equations: impose ODE at ϕ_1 , ..., ϕ_N .

 $\frac{d\sigma}{d\phi} \rightarrow D\sigma$ where *D* is a pseudospectral differentiation matrix.



Of 10 configurations examined, the fit is less good for 2



The configurations with relatively poor fits can be explained by their larger symmetry-breaking

