Parameterizing toroidal surfaces

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1 Introduction

In this note we compare the VMEC and Garabedian representation of toroidal surfaces. The transformation between the coefficients of each representation is derived. A demonstration is given that for a given physical surface shape, the coefficients in either representation are not unique.

2 VMEC representation

In the VMEC code, the cylindrical coordinates (R, Z) are parameterized as functions of a poloidal angle θ and toroidal angle ζ using

$$R(\theta,\zeta) = \sum_{m,n} R_{m,n}^c \cos(m\theta - n\zeta) + R_{m,n}^s \sin(m\theta - n\zeta),$$
(1)
$$Z(\theta,\zeta) = \sum_{m,n} Z_{m,n}^c \cos(m\theta - n\zeta) + Z_{m,n}^s \sin(m\theta - n\zeta),$$

where $R_{m,n}^c$, $R_{m,n}^s$, $Z_{m,n}^c$, and $Z_{m,n}^s$ are coefficients that determine the surface shape.

Notice that $R_{m,n}^c$ and $Z_{m,n}^c$ give identical contributions to $R_{-m,-n}^c$ and $Z_{-m,-n}^c$, and $R_{m,n}^s$ and $Z_{m,n}^s$ give (-1) times the contributions of $R_{-m,-n}^s$ and $Z_{-m,-n}^s$. Therefore it is no loss of generality to consider only non-negative m, and for the m = 0 modes it is no loss of generality to consider only non-negative n.

If the surface is stellarator-symmetric about $(\theta, \zeta) = (0, 0)$, then flipping the sign of θ and ζ will leave R unchanged but will flip the sign of Z. In this case $R_{m,n}^s = 0$ and $Z_{m,n}^c = 0$ for all m and n.

3 Garabedian's representation

The representation introduced by Paul Garabedian is

$$R(\theta,\zeta) + iZ(\theta,\zeta) = e^{i\theta} \sum_{m,n} \Delta_{m,n} e^{-im\theta + in\zeta},$$
(2)

where the parameters $\Delta_{m,n}$ determine the surface shape. (Here we sum over all integer values of m and n, including negative values.) If the surface is stellarator-symmetric about $(\theta, \zeta) = (0, 0)$, then flipping the sign of θ and ζ will leave R unchanged but will flip the sign of Z. Thus:

$$R(\theta,\zeta) - iZ(\theta,\zeta) = e^{-i\theta} \sum_{m,n} \Delta_{m,n} e^{im\theta - in\zeta}.$$
(3)

The complex conjugate of this relation is identical to (2), except with $\Delta_{m,n}$ replaced by its complex conjugate. Equating Fourier components to (2), we find $\Delta_{m,n} = \Delta_{m,n}^*$, that is, $\Delta_{m,n}$ is real. Hence, stellarator symmetry (about $(\theta, \zeta) = (0, 0)$) is equivalent to $\Delta_{m,n}$ being real.

3.1 Converting from VMEC to Garabedian coefficients

To relate the VMEC and Garabedian representations, we plug (1) into (2):

$$\sum_{m,n} \Delta_{m,n} e^{i(1-m)\theta + in\zeta} = \sum_{m,n} \left[(R_{m,n}^c + iZ_{m,n}^c) \cos(m\theta - n\zeta) + (R_{m,n}^s + iZ_{m,n}^s) \sin(m\theta - n\zeta) \right].$$
(4)

Writing the cosine and sine functions in terms of complex exponentials,

$$\sum_{m,n} \Delta_{m,n} e^{i(1-m)\theta + in\zeta} = \frac{1}{2} \sum_{m,n} \left\{ \left(R_{m,n}^c + iZ_{m,n}^c \right) \left[e^{im\theta - in\zeta} + e^{-im\theta + in\zeta} \right] + \left(-iR_{m,n}^s + Z_{m,n}^s \right) \left[e^{im\theta - in\zeta} - e^{-im\theta + in\zeta} \right] \right\}.$$
(5)

For the terms $\propto \exp(im\theta - in\zeta)$ on the right-hand side, we are free to replace the dummy index m with -m, noting that the sum over all m is equivalent to a sum over all -m, and similarly we can replace $n \to -n$. The result is

$$\sum_{m,n} \Delta_{m,n} e^{i(1-m)\theta + in\zeta} = \frac{1}{2} \sum_{m,n} e^{-im\theta + in\zeta} \left[R^c_{-m,-n} + iZ^c_{-m,-n} + R^c_{m,n} + iZ^c_{m,n} - iR^s_{-m,-n} + Z^s_{-m,-n} + iR^s_{m,n} - Z^s_{m,n} \right].$$
(6)

Now on the right hand side we can replace the dummy index m with m-1, noting that the sum over all m is identical to a sum over all m-1. The result is

$$\sum_{m,n} \Delta_{m,n} e^{i(1-m)\theta + in\zeta} = \frac{1}{2} \sum_{m,n} e^{i(1-m)\theta + in\zeta} \left[R_{1-m,-n}^c + iZ_{1-m,-n}^c + R_{m-1,n}^c + iZ_{m-1,n}^c - iR_{1-m,-n}^s + Z_{1-m,-n}^s + iR_{m-1,n}^s - Z_{m-1,n}^s \right].$$
(7)

Each Fourier mode of the left hand side must equal the corresponding Fourier mode on the right hand side, so

$$\Delta_{m,n} = \frac{1}{2} \left[R_{1-m,-n}^c + i Z_{1-m,-n}^c + R_{m-1,n}^c + i Z_{m-1,n}^c - i R_{1-m,-n}^s + Z_{1-m,-n}^s + i R_{m-1,n}^s - Z_{m-1,n}^s \right]$$
(8)

Specializing now to stellar ator symmetry, the left side is real, and the quantities multiplied by i on the right side are each 0, leaving

$$\Delta_{m,n} = \frac{1}{2} \left[R_{1-m,-n}^c + R_{m-1,n}^c + Z_{1-m,-n}^s - Z_{m-1,n}^s \right].$$
(9)

3.2 Converting from Garabedian to VMEC coefficients

Here we work out the conversion from the Garabedian to VMEC representation for the case of stellarator symmetry. First, we replace $n \to -n$ and $m \to 2 - m$ in (9):

$$\Delta_{2-m,-n} = \frac{1}{2} \left[R^c_{m-1,n} + R^c_{1-m,-n} + Z^s_{m-1,n} - Z^s_{1-m,-n} \right].$$
(10)

Adding (9) to (10),

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$$R_{1-m,-n}^c + R_{m-1,n}^c = \Delta_{m,n} + \Delta_{2-m,-n}.$$
(11)

When m = 1 and n = 0, (11) gives

$$R_{0,0}^c = \Delta_{1,0}.$$
 (12)

When m = 1 and n > 0, (11) gives

$$R_{0,n}^c = \Delta_{1,n} + \Delta_{1,-n}.$$
 (13)

The same result follows if m = 1 and n < 0 in (11). If m > 1, then the first term of (11) vanishes. We can then replace $m \to m + 1$ in the remaining terms, giving

$$R_{m,n}^{c} = \Delta_{1-m,-n} + \Delta_{1+m,n}.$$
(14)

The same result follows if m < 1 in (11). Equations (12)-(14) give the VMEC $R_{m,n}^c$ coefficients in terms of the Garabedian coefficients.

Next we derive similar relations for the $Z_{m,n}^s$ coefficients. Subtracting (10) from (9) gives

$$Z_{1-m,-n}^s - Z_{m-1,n}^s = \Delta_{m,n} - \Delta_{2-m,-n}.$$
(15)

If m = 1 and n = 0, this expression reduces to 0 = 0. If m = 1 and n > 0, (15) gives

$$Z_{0,n}^s = \Delta_{1,-n} - \Delta_{1,n}.$$
 (16)

This same result is obtained if m = 1 and n < 0 in (15). If m > 1, the first term in (15) vanishes. Substituting $m \to m + 1$ in the remaining terms, we find

$$Z_{m,n}^{s} = \Delta_{1-m,-n} - \Delta_{1+m,n}.$$
 (17)

The same equation results if m < 1 in (15). Equations (16)-(17) give the VMEC $Z_{m,n}^s$ coefficients in terms of the Garabedian coefficients.

3.3 Counting degrees of freedom

Given a finite number of nonzero VMEC coefficients $R_{m,n}^c$ and $Z_{m,n}^s$, (9) indicates that there is an exactly equivalent Garabedian representation with a finite number of nonzero $\Delta_{m,n}$ coefficients. Considering that the VMEC coefficients vanish for m < 0, (9) indicates that the $\Delta_{m,n}$ coefficients will need to be nonzero for negative m. The Garabedian representation requires twice as many mvalues as the VMEC representation, but the Garabedian representation also requires half as many quantities for each m and n (a single $\Delta_{m,n}$, compared to the two quantities $R_{m,n}^c$ and $Z_{m,n}^s$ for the VMEC representation.) Hence, the number of degrees of freedom required to represent a given shape is (at least roughly) the same.

4 Non-uniqueness

4.1 VMEC representation

For a given surface shape, the VMEC coefficients $R_{m,n}^c$ and $Z_{m,n}^s$ (and $R_{m,n}^s$ and $Z_{m,n}^c$ if the shape is not stellarator-symmetric) are not unique. For the particular case of a circular cross-section in the poloidal plane, we now demonstrate that we can can specify an infinite family of different $\{R_{m,n}^c, Z_{m,n}^s\}$ values that all yield the same shape. For simplicity, let us neglect the toroidal direction and shift R by the major radius, so we can consider the circle $R^2 + Z^2 = 1$. We replace $R_{m,n}^c \to R_m$ and $Z_{m,n}^s \to Z_m$ to simplify notation. One set of VMEC coefficients that corresponds to this shape is

$$R_m = 1 \text{ if } m = 1, \text{ otherwise } R_m = 0,$$

$$Z_m = 1 \text{ if } m = 1, \text{ otherwise } Z_m = 0.$$
(18)

However, we can obtain other VMEC coefficients for the same surface if we parameterize the circle using a different poloidal angle ϑ related to the original angle θ by

$$\theta = \vartheta - \alpha \sin \vartheta, \tag{19}$$

where α is some constant. The circle can then be written as

$$R = \cos\left(\vartheta - \alpha \sin\vartheta\right), \tag{20}$$
$$Z = \sin\left(\vartheta - \alpha \sin\vartheta\right).$$

We now write the VMEC representation of the shape in terms of the poloidal angle ϑ , adding a superscript $^{\alpha}$ to R_m and Z_m :

$$R = \sum_{m} R_{m}^{\alpha} \cos(m\vartheta), \qquad (21)$$
$$Z = \sum_{m} Z_{m}^{\alpha} \sin(m\vartheta).$$

Equating (20)-(21), and expressing the cosine and sine functions as complex exponentials,

$$\sum_{m} R_{m}^{\alpha} \left(e^{im\vartheta} + e^{-im\vartheta} \right) = e^{i(\vartheta - \alpha \sin\vartheta)} + e^{-i(\vartheta - \alpha \sin\vartheta)}, \qquad (22)$$
$$\sum_{m} Z_{m}^{\alpha} \left(e^{im\vartheta} - e^{-im\vartheta} \right) = e^{i(\vartheta - \alpha \sin\vartheta)} - e^{-i(\vartheta - \alpha \sin\vartheta)}.$$

We next apply the operation

$$\frac{1}{2\pi} \int_0^{2\pi} d\vartheta \ e^{-iM\vartheta}(\ldots),\tag{23}$$

where M is any integer. The right-hand sides can be evaluated using

$$J_n(\alpha) = \frac{1}{2\pi} \int_0^{2\pi} d\vartheta \ e^{i(n\vartheta - \alpha \sin \vartheta)},\tag{24}$$

where J_n is the Bessel function. Thus,

$$R_{M}^{\alpha} + R_{-M}^{\alpha} = J_{1-M}(\alpha) + J_{-1-M}(-\alpha), \qquad (25)$$
$$Z_{M}^{\alpha} - Z_{-M}^{\alpha} = J_{1-M}(\alpha) - J_{-1-M}(-\alpha).$$

When M = 0, (25) and the identity

$$J_n(-\alpha) = J_{-n}(\alpha) \tag{26}$$

imply

$$R_0^{\alpha} = J_1(\alpha). \tag{27}$$

(The term Z_0^{α} multiplies $\sin 0 = 0$ so is not used.) For M > 1, the second left-hand side term of each equation in (25) is defined to be 0, leaving

$$R_{M}^{\alpha} = J_{1-M}(\alpha) + J_{1+M}(\alpha),$$

$$Z_{M}^{\alpha} = J_{1-M}(\alpha) - J_{1+M}(\alpha).$$
(28)

For any value of α , equations (27)-(28) provide a different set of $\{R_m, Z_m\}$ coefficients for the unit circle, demonstrating the coefficients are not unique.

The sequences R_m^{α} and Z_m^{α} grow exponentially small with m, with $|R_m^{\alpha}|$ and $|Z_m^{\alpha}|$ both smaller than 10^{-15} for m > 15 when $|\alpha| \le 1$.

4.2 Garabedian representation

Similarly, the Garabedian coefficients $\Delta_{m,n}$ are not unique, as we can demonstrate with the same example. We apply (9) to the R_m^{α} and Z_m^{α} coefficients derived above. We again neglect the toroidal direction, so we write $\Delta_{m,n} \to \Delta_m^{\alpha}$. For m = 1,

$$\Delta_1^{\alpha} = R_0^{\alpha} = J_1(\alpha). \tag{29}$$

For m > 1,

$$\Delta_m^{\alpha} = \frac{1}{2} (R_{m-1}^{\alpha} - Z_{m-1}^{\alpha}) = J_{-m}(-\alpha) = J_m(\alpha), \tag{30}$$

where (26) has been applied. For m < 1,

$$\Delta_m^{\alpha} = \frac{1}{2} (R_{1-m}^{\alpha} + Z_{1-m}^{\alpha}) = J_m(\alpha).$$
(31)

Thus, we find $\Delta_m^{\alpha} = J_m(\alpha)$ for all m. This result demonstrates an infinite set of Garabedian coefficients that all describe the same shape, hence the Garabedian representation is not unique.