

Math 246, Professor David Levermore
Group Work Exercises for Discussion
Wednesday, 9 December 2020

Set A of Group Work Exercises [3]

Consider the planar system

$$\dot{p} = 2p + q, \quad \dot{q} = 5p - 2q + 3p^2.$$

Last week we saw that its stationary points are $(0, 0)$ and $(-3, 6)$. We also saw that this system is Hamiltonian. Use teamwork for each exercise.

- A.1. Compute the Jacobian matrix of this system and evaluate the coefficient matrix for its linearization at each stationary point. Check that each stationary point is regular — i.e. that the determinant of its coefficient matrix is nonzero.
- A.2. Use linearization to classify the type and stability of each stationary point. Sketch a single phase-plane portrait for the system in the pq -plane that shows its behavior near each stationary point. Carefully mark all sketched orbits with arrows! (Different teammates should do each stationary point.)
- A.3. Last week we saw that this system has the Hamiltonian

$$H(p, q) = \frac{1}{2}q^2 + 2pq - \frac{5}{2}p^2 - p^3.$$

Find q as a function of p for each level set $H(p, q) = c$ that contains a stationary point. Use these functions to add to the sketch of the phase-plane portrait all orbits on each level set $H(p, q) = c$ that contains a stationary point. Carefully mark all sketched orbits with arrows! (You may use a computer.)

Set B of Group Work Exercises [3]

Consider the planar system

$$\dot{u} = u^2 + v - 9, \quad \dot{v} = -2uv.$$

Last week we saw that its stationary points are $(-3, 0)$, $(3, 0)$, and $(0, 9)$. We also saw that this system is Hamiltonian. Use teamwork.

- B.1. Compute the Jacobian matrix of this system and evaluate the coefficient matrix for its linearization at each stationary point. Check that each stationary point is regular — i.e. that the determinant of its coefficient matrix is nonzero.
- B.2. Use linearization to classify the type and stability of each stationary point. Sketch a single phase-plane portrait for the system in the uv -plane that shows its behavior near each stationary point. Carefully mark all sketched orbits with arrows! (Different teammates should do each stationary point.)
- B.3. Last week we saw that this system has the Hamiltonian

$$H(u, v) = u^2v + \frac{1}{2}v^2 - 9v.$$

Add to the sketch of the phase-plane portrait all orbits on each level set $H(u, v) = c$ that contains a saddle point. Carefully mark all sketched orbits with arrows! (Do not use a computer.)

Set C of Group Work Exercises [4]

Consider the planar system

$$x' = (21 - 3x - 6y)x, \quad y' = (5 - 2x - y)y.$$

Use teamwork. The classification of each stationary point can be done independently.

- C.1. This system has four stationary points. Find them.
- C.2. Compute the Jacobian matrix of this system and evaluate the coefficient matrix for its linearization at each stationary point. Check that each stationary point is regular — i.e. that the determinant of its coefficient matrix is nonzero.
- C.3. Use linearization classify the type and stability of each stationary point. Sketch a single phase-plane portrait for the system in the xy -plane that shows its behavior near each stationary point. Carefully mark all sketched orbits with arrows! (Different teammates should do each stationary point.)
- C.4. Add any semistationary orbits to the sketch of the phase-plane portrait. Carefully mark all sketched orbits with arrows! Explain why this system is not conservative (i.e. why it does not have an integral) over the entire xy -plane.