Quiz 9 Solutions, Math 246, Professor David Levermore Tuesday, 12 November 2019

(1) [5] Consider the vector-valued functions $\mathbf{x}_1(t) = \begin{pmatrix} 1 \\ -t^2 \end{pmatrix}$, $\mathbf{x}_2(t) = \begin{pmatrix} 2t^4 \\ 4-t^6 \end{pmatrix}$. (a) [2] Compute their Wronskian $Wr[\mathbf{x}_1, \mathbf{x}_2](t)$.

- (b) [3] Find $\mathbf{A}(t)$ such that $\mathbf{x}_1, \mathbf{x}_2$ is a fundamental set of solutions to $\mathbf{x}' = \mathbf{A}(t)\mathbf{x}$.

Solution (a). The Wronskian is

Wr[
$$\mathbf{x}_1, \mathbf{x}_2$$
](t) = det $\begin{pmatrix} 1 & 2t^4 \\ -t^2 & 4-t^6 \end{pmatrix}$ = 1 · (4 - t^6) - (- t^2) · 2 t^4 = 4 + t^6

Solution (b). Let $\Psi(t) = \begin{pmatrix} 1 & 2t^4 \\ -t^2 & 4-t^6 \end{pmatrix}$. Because $\Psi'(t) = \mathbf{A}(t)\Psi(t)$, we have

$$\begin{aligned} \mathbf{A}(t) &= \mathbf{\Psi}'(t)\mathbf{\Psi}(t)^{-1} = \begin{pmatrix} 0 & 8t^3 \\ -2t & -6t^5 \end{pmatrix} \begin{pmatrix} 1 & 2t^4 \\ -t^2 & 4 - t^6 \end{pmatrix}^{-1} \\ &= \frac{1}{4+t^6} \begin{pmatrix} 0 & 8t^3 \\ -2t & -6t^5 \end{pmatrix} \begin{pmatrix} 4-t^6 & -2t^4 \\ t^2 & 1 \end{pmatrix} \\ &= \frac{1}{4+t^6} \begin{pmatrix} 8t^5 & 8t^3 \\ -8t - 4t^7 & -2t^5 \end{pmatrix}. \end{aligned}$$

Remark. This problem is related to Problem 3 on Quiz 8.

(2) [4] Let $\mathbf{B} = \begin{pmatrix} -1 & -2 \\ 4 & -5 \end{pmatrix}$. Compute $e^{t\mathbf{B}}$.

Solution. Because **B** is 2×2 its characteristic polynomial is

$$p(\zeta) = \zeta^2 - \operatorname{tr}(\mathbf{B})\zeta + \det(\mathbf{B}) = \zeta^2 + 6\zeta + 13 = (\zeta + 3)^2 + 2^2$$

Because this is a sum of squares with roots $-3 \pm i2$, the 2 \times 2 formula gives

$$e^{t\mathbf{B}} = e^{-3t} \left[\cos(2t)\mathbf{I} + \frac{\sin(2t)}{2} (\mathbf{B} + 3\mathbf{I}) \right]$$

= $e^{-3t} \left[\cos(2t) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \frac{\sin(2t)}{2} \begin{pmatrix} 2 & -2 \\ 4 & -2 \end{pmatrix} \right]$
= $e^{-3t} \begin{pmatrix} \cos(2t) + \sin(2t) & -\sin(2t) \\ 2\sin(2t) & \cos(2t) - \sin(2t) \end{pmatrix}$.

Remark. An alternative solution is on the back.

(3) [1] Suppose that $e^{t\mathbf{C}} = e^{3t} \begin{pmatrix} \cosh(4t) & -\frac{1}{2}\sinh(4t) \\ -2\sinh(4t) & \cosh(4t) \end{pmatrix}$. Compute the Green matrix $\mathbf{G}(t,s)$ for the system $\mathbf{x}' = \mathbf{C}\mathbf{x} + \mathbf{f}(t)$. **Solution.** The Green matrix is

$$\mathbf{G}(t,s) = e^{(t-s)\mathbf{C}} = e^{3(t-s)} \begin{pmatrix} \cosh(4(t-s)) & -\frac{1}{2}\sinh(4(t-s)) \\ -2\sinh(4(t-s)) & \cosh(4(t-s)) \end{pmatrix}$$

$$p(\zeta) = \zeta^2 - \operatorname{tr}(\mathbf{B})\zeta + \det(\mathbf{B}) = \zeta^2 + 6\zeta + 13 = (\zeta + 3)^2 + 2^2.$$

This is a sum of squares with roots $-3 \pm i2$. Because the Green function for p(D) satisfies the initial-value problem

$$p(\mathbf{D})g = 0, \qquad g(0) = 0, \quad g'(0) = 1,$$

it had the form

$$g(t) = c_1 e^{-3t} \cos(2t) + c_2 e^{-3t} \sin(2t)$$

Because $g(0) = c_1$, the initial condition g(0) = 0 implies that $c_1 = 0$, whereby

$$g'(t) = c_2 e^{-3t} 2\cos(2t) - c_2 3 e^{-3t} \sin(2t) \,.$$

Because $g'(0) = 2c_2$, the initial condition g'(0) = 1 implies that $c_2 = \frac{1}{2}$, whereby

$$g(t) = \frac{1}{2}e^{-3t}\sin(2t)$$

Because $p(\zeta) = \zeta^2 + 6\zeta + 13$, the natural fundamental set associated with $t_I = 0$ is

$$N_{1}(t) = g(t) = \frac{1}{2}e^{-3t}\sin(2t),$$

$$N_{0}(t) = N'_{1}(t) + 6g(t)$$

$$= e^{-3t}\cos(2t) - \frac{3}{2}e^{-3t}\sin(2t) + 3e^{-3t}\sin(2t)$$

$$= e^{-3t}\cos(2t) + \frac{3}{2}e^{-3t}\sin(2t).$$

The natural fundamental set method then gives

$$e^{t\mathbf{B}} = N_0(t)\mathbf{I} + N_1(t)\mathbf{B}$$

= $\left(e^{-3t}\cos(2t) + \frac{3}{2}e^{-3t}\sin(2t)\right) \begin{pmatrix} 1 & 0\\ 0 & 1 \end{pmatrix} + \frac{1}{2}e^{-3t}\sin(2t) \begin{pmatrix} -1 & -2\\ 4 & -5 \end{pmatrix}$
= $e^{-3t}\cos(2t) \begin{pmatrix} 1 & 0\\ 0 & 1 \end{pmatrix} + \frac{1}{2}e^{-3t}\sin(2t) \begin{pmatrix} 2 & -2\\ 4 & -2 \end{pmatrix}$
= $e^{-3t} \begin{pmatrix} \cos(2t) + \sin(2t) & -\sin(2t)\\ 2\sin(2t) & \cos(2t) - \sin(2t) \end{pmatrix}$.

Remark. For 2×2 matrices the 2×2 formula for the matrix exponential will always be the fastest way to go because it precomputes the natural fundamental set.