## Quiz 8 Solutions, Math 246, Professor David Levermore Tuesday, 5 November 2019

Short Table:  $\mathcal{L}[t^n e^{at}](s) = \frac{n!}{\sqrt{ns}}$  $\frac{h!}{(s-a)^{n+1}}$  for  $s > a$ ,  $\mathcal{L}[u(t-c)j(t-c)](s) = e^{-cs}\mathcal{L}[j](s)$ .

(1) [5] Find  $F(s) = \mathcal{L}[f](s)$  where  $f(t) = u(t-4)e^{-3t} + 5\delta(t-2)$ .

Solution. By linearity we have

$$
\mathcal{L}[f](s) = \mathcal{L}[u(t-4)e^{-3t}](s) + 5\mathcal{L}[\delta(t-2)](s).
$$
  
Q method 
$$
u(t-4)e^{-3t} = u(t-4)i(t-4)
$$
 where

By the shifty step method  $u(t-4)e^{-3t} = u(t-4)j(t-4)$  where  $j(t) = e^{-3(t+4)} = e^{-3t}e^{-12}.$ 

Hence, the second entry in our short table with  $c = 4$  gives

$$
\mathcal{L}[u(t-4)e^{-3t}](s) = \mathcal{L}[u(t-4)j(t-4)](s) = e^{-4s}\mathcal{L}[j](s)
$$
  
=  $e^{-4s}e^{-12}\mathcal{L}[e^{-3t}](s)$ .

The first entry in our short table with  $n = 0$  and  $a = -3$  gives

$$
\mathcal{L}[e^{-3t}](s) = \frac{1}{s+3}
$$

.

Therefore

$$
\mathcal{L}[u(t-4)e^{-3t}](s) = e^{-4s}e^{-12}\frac{1}{s+3}.
$$

By the rule for evaluating the unit impulse under an integral we have

$$
\mathcal{L}[\delta(t-2)](s) = \int_0^\infty e^{-st} \delta(t-2) dt = e^{-2s}.
$$

Therefore

$$
\mathcal{L}[f](s) = \frac{e^{-4s-12}}{s+3} + 5e^{-2s}.
$$

(2) [2] Recast the equation  $x'''' - e^{t+x''}x' + \sin(x) = 0$  as a first-order system of ordinary differential equations.

Solution. Because the equation is fourth order, the first-order system must have dimension four. The simplest such first-order system is

$$
\frac{\mathrm{d}}{\mathrm{d}t} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} = \begin{pmatrix} y_2 \\ y_3 \\ y_4 \\ e^{t+y_3}y_2 + \sin(y_1) \end{pmatrix}, \quad \text{where} \quad \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} = \begin{pmatrix} x \\ x' \\ x'' \\ x''' \end{pmatrix}.
$$

**Remark.** There should be no x, x', x'', or x''' appearing in the first-order system. The only place these should appear is in the dictionary on the right that shows their relationship to the new variables. The first-order system should be expressed solely in terms of the new variables. The new variables are  $y_1, y_2, y_3$ , and  $y_4$  in the solution above. Any similar set of new variables could be used.

(3) [3] Consider the matrix-valued function  $\Psi(t) = \begin{pmatrix} 1 & 2t^4 \\ -t^2 & 4 \end{pmatrix}$  $-t^2$  4 –  $t^6$  $\setminus$ .

- (a) Compute det  $(\Psi(t))$ .
- (b) Compute  $\Psi(t)^{-1}$ .
- (c) Compute  $\Psi'(t)$ .

**Solution (a).** The determinant of  $\Psi(t)$  is

$$
\det(\mathbf{\Psi}(t)) = \det\begin{pmatrix} 1 & 2t^4 \\ -t^2 & 4-t^6 \end{pmatrix} = 1 \cdot (4-t^6) - (-t^2) \cdot (2t^4) = 4 + t^6.
$$

**Solution (b).** The inverse of  $\Psi(t)$  is

$$
\Psi(t)^{-1} = \frac{1}{\det(\Psi(t))} \begin{pmatrix} 4-t^6 & -2t^4 \\ t^2 & 1 \end{pmatrix} = \frac{1}{4+t^6} \begin{pmatrix} 4-t^6 & -2t^4 \\ t^2 & 1 \end{pmatrix}.
$$

**Solution (c).** The derivative of  $\Psi(t)$  is

$$
\Psi'(t) = \begin{pmatrix} 0 & 8t^3 \\ -2t & -6t^5 \end{pmatrix}.
$$