## Sample Problems for the Third In-Class Exam Math 246, Fall 2018, Professor David Levermore

- (1) Compute the Laplace transform of  $f(t) = te^{3t}u(t-2)$  from its definition.
- (2) Consider the following (old style) MATLAB commands.

>> syms t s Y; f = ['heaviside(t)\*t^2 + heaviside(t - 3)\*(3\*t - t^2)']; >> diffeqn = sym('D(D(y))(t) - 6\*D(y)(t) + 10\*y(t) = 'f);  $\gg$  eqntrans = laplace(diffeqn, t, s);  $\Rightarrow$  algeqn = subs(eqntrans, {'laplace(y(t),t,s),t,s)', 'y(0)', 'D(y)(0)'}, {Y, 2, 3});  $\gg$  ytrans = simplify(solve(algeqn, Y));  $>> y =$ ilaplace(ytrans, s, t)

- (a) Give the initial-value problem for  $y(t)$  that is being solved.
- (b) Find the Laplace transform  $Y(s)$  of the solution  $y(t)$ .

DO NOT take the inverse Laplace transform of  $Y(s)$  to find  $y(t)$ , just solve for  $Y(s)!$ You may refer to the table on the last page.

(3) Find  $Y(s) = \mathcal{L}[y](s)$  where  $y(t)$  solves the initial-value problem

$$
y'' + 4y' + 13y = f(t), \t y(0) = 4, \t y'(0) = 1,
$$

where

$$
f(t) = \begin{cases} \cos(t) & \text{for } 0 \le t < 2\pi \\ t - 2\pi & \text{for } t \ge 2\pi \end{cases}
$$

DO NOT take the inverse Laplace transform of  $Y(s)$  to find  $y(t)$ , just solve for  $Y(s)!$ You may refer to the table on the last page.

(4) Find  $X(s) = \mathcal{L}[x](s)$  where  $x(t)$  solves the initial-value problem

 $x'' + 4x = \delta(t - 3), \quad x(0) = 5, \quad x'(0) = 0.$ 

DO NOT take the inverse Laplace transform of  $X(s)$  to find  $x(t)$ , just solve for  $X(s)$ ! You may refer to the table on the last page.

(5) Find the inverse Laplace transforms of the following functions.

(a) 
$$
F(s) = \frac{2}{(s+5)^2}
$$
,  
(b)  $F(s) = \frac{3s}{s^2 - s - 6}$ ,

$$
s^{2}-s-6
$$
  
(c)  $F(s) = \frac{(s-2)e^{-3s}}{s^{2}-4s+5}$ .

You may refer to the table on the last page.

- (6) For each of the following differential operators compute its Green function  $q(t)$  and its natural fundamental set for  $t = 0$ .
	- (a)  $L = D^4 + 8D^2 9$ ,
	- (b)  $L = (D 2)^3$ .

You may refer to the table on the last page.

- (7) Recast the equation  $u''' + t^2u' 3u = \sinh(2t)$  as a first-order system of ordinary differential equations.
- (8) Two interconnected tanks are filled with brine (salt water). At  $t = 0$  the first tank contains 45 liters and the second contains 30 liters. Brine with a salt concentration of 5 grams per liter flows into the first tank at 6 liters per hour. Well-stirred brine flows from the first tank into the second at 8 liters per hour, from the second into the first at 7 liters per hour, from the first into a drain at 4 liter per hour, and from the second into a drain at 3 liters per hour. At  $t = 0$  there are 27 grams of salt in the first tank and 18 grams in the second.
	- (a) Give an initial-value problem that governs the amount of salt in each tank as a function of time.
	- (b) Give the interval of definition for the solution of this initial-value problem.
- (9) Consider the matrices

$$
\mathbf{A} = \begin{pmatrix} -i2 & 1+i \\ 2+i & -4 \end{pmatrix}, \qquad \mathbf{B} = \begin{pmatrix} 7 & 6 \\ 8 & 7 \end{pmatrix}
$$

.

Compute the matrices

- (a)  $\mathbf{A}^{\!\mathrm{T}}\!$  ,  $(b)$   $\overline{A}$ ,  $(c)$   $A^H$ , (d)  $5\mathbf{A} - \mathbf{B}$ ,  $(e)$   $AB$ ,
- $(f)$  **B**<sup>-1</sup>.

(10) Consider the vector-valued functions  $\mathbf{x}_1(t) = \begin{pmatrix} t^4 + 3 \\ 9t^2 \end{pmatrix}$  $2t^2$  $\Big), \mathbf{x}_2(t) = \begin{pmatrix} t^2 \\ 3 \end{pmatrix}$ 3  $\setminus$ .

- (a) Compute the Wronskian  $Wr[**x**<sub>1</sub>, **x**<sub>2</sub>](t)$ .
- (b) Find  $\mathbf{A}(t)$  such that  $\mathbf{x}_1, \mathbf{x}_2$  is a fundamental set of solutions to the system

$$
\mathbf{x}' = \mathbf{A}(t)\mathbf{x},
$$

wherever  $Wr[\mathbf{x}_1, \mathbf{x}_2](t) \neq 0.$ 

- (c) Give a fundamental matrix  $\Psi(t)$  for the system found in part (b).
- (d) For the system found in part (b), solve the initial-value problem

$$
\mathbf{x}' = \mathbf{A}(t)\mathbf{x}, \qquad \mathbf{x}(1) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}.
$$

(e) For the  $\mathbf{A}(t)$  found in part (b), give the Green matrix for the system  $\mathbf{x}' = \mathbf{A}(t)\mathbf{x} + \mathbf{f}(t)$ .

(11) Compute  $e^{tA}$  for the following matrices.

(a) 
$$
\mathbf{A} = \begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix}
$$
  
(b)  $\mathbf{A} = \begin{pmatrix} 6 & 4 \\ -1 & 2 \end{pmatrix}$ 

(12) Give the Green matrix for the system  $\mathbf{x}' = \mathbf{A}\mathbf{x} + \mathbf{f}(t)$  when

(a) 
$$
\mathbf{A} = \begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix}
$$
  
(b)  $\mathbf{A} = \begin{pmatrix} 6 & 4 \\ -1 & 2 \end{pmatrix}$ 

(13) Consider the matrix

$$
\mathbf{A} = \begin{pmatrix} -1 & -2 & 1 \\ 4 & 0 & -2 \\ -2 & 0 & 1 \end{pmatrix}.
$$

Compute  $e^{tA}$  given that the characteristic polynomial of **A** is  $p(z) = z^3 + 9z$  and that the natural fundamental set of solutions associated with  $t = 0$  for  $D^3 + 9D$  is

 $N_0(t) = 1, \qquad N_1(t) = \frac{1}{3}\sin(3t), \qquad N_2(t) = \frac{1}{9}(1 - \cos(3t)).$ 

(14) Solve each of the following initial-value problems.

(a) 
$$
\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 & 2 \\ 5 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}, \qquad \begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}.
$$
  
\n(b)  $\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -4 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}, \qquad \begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$ 

(15) Find a general solution for each of the following systems.

(a) 
$$
\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3 & -4 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}
$$
  
\n(b)  $\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2 & -5 \\ 4 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$   
\n(c)  $\frac{d}{dt} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 5 & 4 \\ -5 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$ 

(16) Given that 1 is an eigenvalue of the matrix

$$
\mathbf{A} = \begin{pmatrix} 2 & -1 & 1 \\ 1 & 1 & -1 \\ 0 & -1 & 3 \end{pmatrix},
$$

find all the eigenvectors of A associated with 1.

(17) Consider the matrix

$$
\mathbf{A} = \begin{pmatrix} 3 & 3 \\ 4 & -1 \end{pmatrix} \, .
$$

- (a) Find all the eigenvalues of A.
- (b) For each eigenvalue of A find all of its eigenvectors.
- (c) Diagonalize A.
- (d) Compute  $e^{t\mathbf{A}}$ .
- (e) Compute  $(sI A)^{-1}$  for every s where it is defined.
- (18) What answer will be produced by the following Matlab command?

>> A = [1 4; 3 2]; [vect, val] = eig(sym(A))

You do not have to give the answer in Matlab format.

(19) A  $3 \times 3$  matrix **A** has the eigenpairs

$$
\left(-3, \begin{pmatrix}1\\1\\0\end{pmatrix}\right), \qquad \left(2, \begin{pmatrix}-1\\1\\1\end{pmatrix}\right), \qquad \left(5, \begin{pmatrix}1\\-1\\2\end{pmatrix}\right).
$$

- (a) Give an invertible matrix **V** and a diagonal matrix **D** such that  $e^{t\mathbf{A}} = \mathbf{V}e^{t\mathbf{D}}\mathbf{V}^{-1}$ . (You do not have to compute either  $V^{-1}$  or  $e^{tA}$ !)
- (b) Give a fundamental matrix for the system  $\mathbf{x}' = \mathbf{A}\mathbf{x}$ .

## Table of Laplace Transforms

$$
\mathcal{L}[t^n e^{at}](s) = \frac{n!}{(s-a)^{n+1}} \quad \text{for } s > a.
$$
  

$$
\mathcal{L}[e^{at}\cos(bt)](s) = \frac{s-a}{(s-a)^2 + b^2} \quad \text{for } s > a.
$$
  

$$
\mathcal{L}[e^{at}\sin(bt)](s) = \frac{b}{(s-a)^2 + b^2} \quad \text{for } s > a.
$$
  

$$
\mathcal{L}[j'(t)](s) = sJ(s) - j(0) \quad \text{where } J(s) = \mathcal{L}[j(t)](s).
$$
  

$$
\mathcal{L}[t^n j(t)](s) = (-1)^n J^{(n)}(s) \quad \text{where } J(s) = \mathcal{L}[j(t)](s).
$$
  

$$
\mathcal{L}[e^{at} j(t)](s) = J(s-a) \quad \text{where } J(s) = \mathcal{L}[j(t)](s).
$$
  

$$
\mathcal{L}[u(t-c)j(t-c)](s) = e^{-cs}J(s) \quad \text{where } J(s) = \mathcal{L}[j(t)](s), c \ge 0,
$$
  
and u is the unit step function.

$$
\mathcal{L}[\delta(t-c)h(t)](s) = e^{-cs}h(c)
$$

where  $c \geq 0$  and  $\delta$  is the unit impluse.

 $\mathcal{L}[j(t)](s)$ .

 $\mathcal{L}[j(t)](s)$ .

 $\mathcal{L}[j(t)](s)$ .

 $\mathcal{L}[j(t)](s), c \geq 0,$