

Second In-Class Exam Solutions
Math 246, Professor David Levermore
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- (1) [4] Give the interval of definition for the solution of the initial-value problem

$$z''' + \frac{7}{t^2 - 25} z' = \frac{3}{\sin(t)}, \quad z(-4) = z'(-4) = z''(-4) = 0.$$

Solution. The equation is linear and is already in normal form. The coefficient is undefined at $t = \pm 5$ and is continuous everywhere else. The forcing is undefined at $t = n\pi$ for every integer n and is continuous everywhere else. Therefore the interval of definition is $(-5, -\pi)$ because

- the initial time $t = -4$ is in the interval $(-5, -\pi)$,
- the coefficient and forcing are both continuous over the interval $(-5, -\pi)$,
- the forcing is undefined at $-\pi$ while the coefficient is undefined at -5 .

- (2) [10] The functions e^{3t} and $t e^{3t}$ are a fundamental set of solutions to $y'' - 6y' + 9y = 0$.
(a) Find the solution $Y(t)$ to the general initial-value problem

$$y'' - 6y' + 9y = 0, \quad y(0) = y_0, \quad y'(0) = y_1.$$

- (b) Find the associated natural fundamental set of solutions to $y'' - 6y' + 9y = 0$.

Solution (a). Since e^{3t} and $t e^{3t}$ is a fundamental set of solutions to $y'' - 6y' + 9y = 0$, a general solution is $y(t) = c_1 e^{3t} + c_2 t e^{3t}$. Because $y'(t) = 3c_1 e^{3t} + 3c_2 t e^{3t} + c_2 e^{3t}$, the initial conditions imply

$$y_0 = y(0) = c_1, \quad y_1 = y'(0) = 3c_1 + c_2.$$

We solve these equations to obtain

$$c_1 = y_0, \quad c_2 = y_1 - 3y_0.$$

Therefore the solution to the general initial-value problem is

$$y(t) = y_0 e^{3t} + (y_1 - 3y_0) t e^{3t}.$$

Solution (b). Because the above solution to the general initial-value problem can be written as

$$y(t) = (1 - 3t)e^{3t} y_0 + t e^{3t} y_1,$$

the associated natural fundamental set of solutions is seen to be

$$N_0(t) = (1 - 3t)e^{3t}, \quad N_1(t) = t e^{3t}.$$

- (3) [4] Suppose that $X_1(t)$, $X_2(t)$, and $X_3(t)$ are solutions of the differential equation

$$x''' - x'' + e^t x' - t^2 x = 0,$$

Suppose you know that $W[X_1, X_2, X_3](0) = 3$. What is $W[X_1, X_2, X_3](t)$?

Solution. Abel's Theorem states that $w(t) = W[X_1, X_2, X_3](t)$ satisfies $w' - w = 0$. It follows that $w(t) = w(0)e^t$. Because $w(0) = W[X_1, X_2, X_3](0) = 3$, we obtain $w(t) = 3e^t$. Therefore

$$W[X_1, X_2, X_3](t) = 3e^t.$$

(4) [10] Give a general real solution of the equation

$$D^2x - 4Dx - 21x = 12 \cos(3t) - 7e^{4t}, \quad \text{where } D = \frac{d}{dt}.$$

Solution. This is a nonhomogeneous linear equation with constant coefficients. Its characteristic polynomial is

$$p(z) = z^2 - 4z - 21 = (z + 3)(z - 7),$$

which has the two simple real roots -3 and 7 . Therefore a general solution of the associated homogeneous equation is

$$x_H(t) = c_1e^{-3t} + c_2e^{7t}.$$

The forcing term $12 \cos(3t)$ has degree $d = 0$ and characteristic $\mu + i\nu = i3$, which is a root of $p(z)$ of multiplicity $m = 0$. The forcing term $-7e^{4t}$ has degree $d = 0$ and characteristic $\mu + i\nu = 4$, which is a root of $p(z)$ of multiplicity $m = 0$. Because the forcing has composite characteristic form, either Key Identity Evaluations or Undetermined Coefficients can be used to find particular solutions $x_{P_1}(t)$ and $x_{P_2}(t)$ that satisfy

$$L(x_{P_1}(t)) = 12 \cos(3t), \quad L(x_{P_2}(t)) = -7e^{4t}.$$

Then a general solution will be given by $x(t) = x_H(t) + x_{P_1}(t) + x_{P_2}(t)$.

Key Identity Evaluations. Because $m = 0$ and $m + d = 0$ for both forcing terms, we need only the Key Identity

$$L(e^{zt}) = p(z)e^{zt} = (z^2 - 4z - 21)e^{zt}.$$

By evaluating this at $z = i3$ and $z = 4$ we obtain

$$\begin{aligned} L(e^{i3t}) &= ((i3)^2 - 4(i3) - 21)e^{i3t} = (-9 - i12 - 21)e^{i3t} = -(30 + i12)e^{i3t}, \\ L(e^{4t}) &= (4^2 - 4 \cdot 4 - 21)e^{4t} = (16 - 16 - 21)e^{4t} = -21e^{4t}. \end{aligned}$$

Because the first forcing term is $12 \cos(3t) = 12 \operatorname{Re}(e^{i3t})$, we write

$$L\left(-\frac{12e^{i3t}}{30 + i12}\right) = 12e^{i3t},$$

which implies that

$$\begin{aligned} x_{P_1}(t) &= -\operatorname{Re}\left(\frac{12e^{i3t}}{30 + i12}\right) = -2 \operatorname{Re}\left(\frac{e^{i3t}}{5 + i2} \frac{5 - i2}{5 - i2}\right) = -2 \operatorname{Re}\left(\frac{(5 - i2)e^{i3t}}{5^2 + 2^2}\right) \\ &= -\frac{2}{25+4} \operatorname{Re}((5 - i2)e^{i3t}) = -\frac{2}{29}(5 \cos(3t) + 2 \sin(3t)). \end{aligned}$$

Because the second forcing term is $-7e^{4t}$, we write

$$L\left(\frac{-7e^{4t}}{-21}\right) = -7e^{4t},$$

which implies that

$$x_{P_2}(t) = \frac{1}{3}e^{4t}.$$

Therefore a general solution of the equation is

$$\begin{aligned} x(t) &= x_H(t) + x_{P_1}(t) + x_{P_2}(t) \\ &= c_1e^{-3t} + c_2e^{7t} - \frac{10}{29} \cos(3t) - \frac{4}{29} \sin(3t) + \frac{1}{3}e^{4t}. \end{aligned}$$

Undetermined Coefficients. Because $\mu + i\nu = i3$ and $m + d = m = 0$ for the forcing term $12 \cos(3t)$, we *seek* a particular solution in the form

$$x_{P_1}(t) = A \cos(3t) + B \sin(3t).$$

Because

$$x'_{P_1}(t) = -3A \sin(3t) + 3B \cos(3t), \quad x''_{P_1}(t) = -9A \cos(3t) - 9B \sin(3t),$$

we see that

$$\begin{aligned} \mathbb{L}x_{P_1}(t) &= x''_{P_1}(t) - 4x'_{P_1}(t) - 21x_{P_1}(t) \\ &= [-9A \cos(3t) - 9B \sin(3t)] - 4[-3A \sin(3t) + 3B \cos(3t)] \\ &\quad - 21[A \cos(3t) + B \sin(3t)] \\ &= (-30A - 12B) \cos(3t) + (12A - 30B) \sin(3t). \end{aligned}$$

By setting $\mathbb{L}x_{P_1}(t) = 12 \cos(3t)$, we see that

$$-30A - 12B = 12, \quad 12A - 30B = 0.$$

The second equation implies $A = \frac{5}{2}B$, which when placed into the first equation yields $-87B = 12$. Hence, $B = -\frac{4}{29}$ and $A = -\frac{10}{29}$, which gives

$$x_{P_1}(t) = -\frac{10}{29} \cos(3t) - \frac{4}{29} \sin(3t).$$

Because $\mu + i\nu = 4$ and $m + d = m = 0$ for the forcing term $-7e^{4t}$, we *seek* a particular solution in the form

$$x_{P_2}(t) = Ae^{4t}.$$

Because

$$x'_{P_2}(t) = 4Ae^{4t}, \quad x''_{P_2}(t) = 16Ae^{4t},$$

we see that

$$\begin{aligned} \mathbb{L}x_{P_2}(t) &= x''_{P_2}(t) - 4x'_{P_2}(t) - 21x_{P_2}(t) \\ &= [16Ae^{4t}] - 4[4Ae^{4t}] - 21[Ae^{4t}] = (16 - 16 - 21)Ae^{4t} = -21Ae^{4t}. \end{aligned}$$

By setting $\mathbb{L}x_{P_2}(t) = -7e^{4t}$, we see that $-21A = -7$, whereby $A = \frac{1}{3}$. Hence,

$$x_{P_2}(t) = \frac{1}{3}e^{4t}.$$

Therefore a general solution of the equation is

$$\begin{aligned} x(t) &= x_H(t) + x_{P_1}(t) + x_{P_2}(t) \\ &= c_1 e^{-3t} + c_2 e^{7t} - \frac{10}{29} \cos(3t) - \frac{4}{29} \sin(3t) + \frac{1}{3} e^{4t}. \end{aligned}$$

(5) [10] What answer will be produced by the following MATLAB commands?

```
>> ode = 'D2y - 4*Dy + 13*y = 9*exp(5*t)';
>> dsolve(ode, 't')
```

ans =

Solution. The commands ask MATLAB to give a general solution of the equation

$$D^2y - 4Dy + 13y = 9e^{5t}, \quad \text{where } D = \frac{d}{dt}.$$

This is a nonhomogeneous linear equation with constant coefficients. Its characteristic polynomial is

$$p(z) = z^2 - 4z + 13 = (z - 2)^2 + 9 = (z - 2)^2 + 3^2,$$

which has the conjugate pair of roots $2 \pm i3$. Therefore a general solution of the associated homogeneous equation is

$$y_H(t) = c_1 e^{2t} \cos(3t) + c_2 e^{2t} \sin(3t).$$

The forcing $9e^{5t}$ has degree $d = 0$ and characteristic $\mu + i\nu = 5$, which is a root of $p(z)$ of multiplicity $m = 0$. Therefore we can use either Key Identity Evaluations or Undetermined Coefficients to find a particular solution $y_P(t)$.

Key Identity Evaluations. Because $m + d = m = 0$ we only need the Key identity, which is

$$L(e^{zt}) = p(z)e^{zt} = (z^2 - 4z + 13)e^{zt}.$$

By evaluating this at $z = 5$ we obtain

$$L(e^{5t}) = (5^2 - 4 \cdot 5 + 13)e^{5t} = (25 - 20 + 13)e^{5t} = 18e^{5t}.$$

Because the forcing term is $9e^{5t}$, we see that a particular solution is $y_P(t) = \frac{1}{2}e^{5t}$. Therefore a general solution is

$$y(t) = c_1 e^{2t} \cos(3t) + c_2 e^{2t} \sin(3t) + \frac{1}{2}e^{5t}.$$

Undetermined Coefficients. Because $\mu + i\nu = 5$ and $m + d = m = 0$ for the forcing term $9e^{5t}$, we seek a particular solution in the form

$$y_P(t) = Ae^{5t}.$$

Because $y'_P(t) = 5Ae^{5t}$ and $y''_P(t) = 25Ae^{5t}$, we see that

$$\begin{aligned} Ly_P(t) &= y''_P(t) - 4y'_P(t) + 13y_P(t) \\ &= [25Ae^{5t}] - 4[5Ae^{5t}] + 13[Ae^{5t}] \\ &= (25 - 20 + 13)Ae^{5t} = 18Ae^{5t}. \end{aligned}$$

By setting $Ly_P(t) = 9e^{5t}$, we see that $18A = 9$, whereby $A = \frac{1}{2}$. Hence, we obtain the particular solution $y_P(t) = \frac{1}{2}e^{5t}$. Therefore a general solution is

$$y(t) = c_1 e^{2t} \cos(3t) + c_2 e^{2t} \sin(3t) + \frac{1}{2}e^{5t}.$$

(6) [8] Compute the Green function associated with the differential operator

$$L = D^2 - 8D + 16, \quad \text{where } D = \frac{d}{dt}.$$

Solution. Because the differential operator L has constant coefficients, the Green function $g(t)$ associated with it satisfies the initial-value problem

$$Lg = D^2g - 8Dg + 16g = 0, \quad g(0) = 0, \quad g'(0) = 1.$$

The characteristic polynomial is

$$p(z) = z^2 - 8z + 16 = (z - 4)^2,$$

which has the double real root 4. Hence, the Green function has the form

$$g(t) = c_1 e^{4t} + c_2 t e^{4t}.$$

The initial condition $g(0) = 0$ implies that $c_1 = 0$. Because

$$g'(t) = 4c_2 t e^{4t} + c_2 e^{4t},$$

the initial condition $g'(0) = 1$ implies that $c_2 = 1$. Therefore the Green function is

$$g(t) = t e^{4t}.$$

(7) [8] Solve the initial-value problem

$$v'' - 8v' + 16v = \frac{e^{4t}}{1+t}, \quad v(0) = v'(0) = 0.$$

Solution. By the previous problem the Green function for this problem is $g(t) = t e^{4t}$. Because this equation is in normal form, the solution to this initial-value problem is given by the Green function formula

$$\begin{aligned} v(t) &= \int_0^t g(t-s)f(s) \, ds = \int_0^t (t-s)e^{4(t-s)} \frac{e^{4s}}{1+s} \, ds \\ &= t e^{4t} \int_0^t \frac{1}{1+s} \, ds - e^{4t} \int_0^t \frac{s}{1+s} \, ds. \end{aligned}$$

Because

$$\begin{aligned} \int_0^t \frac{1}{1+s} \, ds &= [\log(1+s)] \Big|_{s=0}^t = \log(1+t), \\ \int_0^t \frac{s}{1+s} \, ds &= \int_0^t \left(1 - \frac{1}{1+s}\right) \, ds = [s - \log(1+s)] \Big|_{s=0}^t = t - \log(1+t), \end{aligned}$$

we find that

$$\begin{aligned} v(t) &= t e^{4t} \log(1+t) - e^{4t}(t - \log(1+t)) \\ &= e^{4t}((1+t) \log(1+t) - t). \end{aligned}$$

(8) [8] Find a particular solution $x_P(t)$ of the equation $x'' - x = 4e^t$.

Solution. This is a constant coefficient, nonhomogeneous, linear equation. Its characteristic polynomial is

$$p(z) = z^2 - 1 = (z + 1)(z - 1),$$

which has two simple real roots -1 and 1 . The forcing $4e^t$ has degree $d = 0$ and characteristic $\mu + i\nu = 1$, which is a root of $p(z)$ of multiplicity $m = 1$. Therefore we can use either Key Identity Evaluations or Undetermined Coefficients to find a particular solution $x_P(t)$.

Key Identity Evaluations. Because $m = 1$ and $m + d = 1$ for the forcing term, we only need the first derivative of the Key Identity. The Key Identity and its first derivative are

$$L(e^{zt}) = (z^2 - 1)e^{zt},$$

$$L(te^{zt}) = (z^2 - 1)te^{zt} + 2ze^{zt}.$$

By evaluating the derivative of the Key identity at $z = 1$ we obtain

$$L(te^t) = 2 \cdot 1 \cdot e^{1 \cdot t} = 2e^t.$$

Because the forcing is $4e^t$, we see that a particular solution is $x_P(t) = 2te^t$.

Undetermined Coefficients. Because $\mu + i\nu = 1$ and $m + d = m = 1$ for the forcing term $2e^t$, we *seek* a particular solution in the form

$$x_P(t) = At e^t.$$

Because

$$x'_P(t) = At e^t + Ae^t, \quad x''_P(t) = At e^t + 2Ae^t,$$

we obtain

$$Lx_P(t) = [At e^t + 2Ae^t] - [At e^t] = 2Ae^t.$$

By setting $Lx_P(t) = 4e^t$, we see that $2A = 4$, whereby $A = 2$. Therefore, a particular solution is $x_P(t) = 2te^t$.

Remark. A general solution is

$$x(t) = c_1 e^t + c_2 e^{-t} + 2te^t.$$

- (9) [10] Let L be a linear ordinary differential operator with constant coefficients. Suppose that all the roots of its characteristic polynomial (listed with their multiplicities) are $-2 + i4$, $-2 + i4$, $-2 - i4$, $-2 - i4$, $i3$, $-i3$, -7 , -7 , -7 , 0 , 0 .

(a) Give the order of L .

(b) Give a general real solution of the homogeneous equation $Ly = 0$.

Solution (a). There are 11 roots listed above, so the degree of the characteristic polynomial is 11, whereby the order of L is also 11.

Solution (b). A general solution is

$$y(t) = c_1 e^{2t} \cos(4t) + c_2 e^{2t} \sin(4t) + c_3 t e^{2t} \cos(4t) + c_4 t e^{2t} \sin(4t) \\ + c_5 \cos(3t) + c_6 \sin(3t) + c_7 e^{-7t} + c_8 t e^{-7t} + c_9 t^2 e^{-7t} + c_{10} + c_{11} t.$$

Here the fundamental set of solutions is generated as follows:

- the double conjugate pair $2 \pm i4$ yields

$$e^{2t} \cos(4t), \quad e^{2t} \sin(4t), \quad t e^{2t} \cos(4t), \quad \text{and} \quad t e^{2t} \sin(4t);$$

- the single conjugate pair $\pm i3$ yields $\cos(3t)$ and $\sin(3t)$;
- the triple real root -7 yields e^{-7t} , $t e^{-7t}$, and $t^2 e^{-7t}$;
- the double real root 0 yields 1 and t .

- (10) [10] The functions t^2 and t^3 are solutions of the homogeneous equation

$$t^2 y'' - 4ty' + 6y = 0 \quad \text{over } t > 0.$$

(You do not have to check that this is true!)

(a) Show they are linearly independent.

(b) Give a general solution of the nonhomogeneous equation

$$t^2 y'' - 4ty' + 6y = \frac{t^3}{1+t^2} \quad \text{over } t > 0.$$

Solution (a). The Wronskian of t^2 and t^3 is

$$W[t^2, t^3](t) = \det \begin{pmatrix} t^2 & t^3 \\ 2t & 3t^2 \end{pmatrix} = t^2 \cdot 3t^2 - 2t \cdot t^3 = 3t^4 - 2t^4 = t^4.$$

Since $W[t^2, t^3](t) = t^4 \neq 0$ for $t > 0$, the functions t^2 and t^3 are linearly independent.

Solution (b). Because t^2 and t^3 are linearly independent, a general solution of the associated homogeneous problem is

$$y_H(t) = c_1 t^2 + c_2 t^3.$$

Because this problem has variable coefficients, you should use either the general Green Function method or Variation of Parameters to find a particular solution $y_P(t)$. Both of these methods require the equation to be put into its normal form, which is

$$y'' - \frac{4}{t} y' + \frac{6}{t^2} y = \frac{t}{1+t^2}.$$

General Green Function. The Green function $G(t, s)$ is given by

$$G(t, s) = \frac{1}{W[s^2, s^3](s)} \det \begin{pmatrix} s^2 & s^3 \\ t^2 & t^3 \end{pmatrix} = \frac{s^2 t^3 - t^2 s^3}{s^4} = \frac{t^3}{s^2} - \frac{t^2}{s}.$$

The Green function formula with $t_I = 1$ then yields the solution

$$\begin{aligned} y_P(t) &= \int_1^t G(t, s) f(s) ds = \int_1^t \left(\frac{t^3}{s^2} - \frac{t^2}{s} \right) \frac{s}{1+s^2} ds \\ &= t^3 \int_1^t \frac{1}{s(1+s^2)} ds - t^2 \int_1^t \frac{1}{1+s^2} ds. \end{aligned}$$

We can evaluate the above definite integrals as

$$\begin{aligned} \int_1^t \frac{1}{s(1+s^2)} ds &= \int_1^t \frac{1}{s} - \frac{s}{1+s^2} ds = \left(\log(s) - \frac{1}{2} \log(1+s^2) \right) \Big|_{s=1}^t \\ &= \log(t) - \frac{1}{2} \log(1+t^2) + \frac{1}{2} \log(2) = \frac{1}{2} \log \left(\frac{2t^2}{1+t^2} \right), \\ \int_1^t \frac{1}{1+s^2} ds &= \tan^{-1}(s) \Big|_{s=1}^t = \tan^{-1}(t) - \tan^{-1}(1) = \tan^{-1}(t) - \frac{\pi}{4}. \end{aligned}$$

Therefore a general solution is

$$y(t) = c_1 t^2 + c_2 t^3 + \frac{1}{2} t^3 \log \left(\frac{2t^2}{1+t^2} \right) - t^2 \left(\tan^{-1}(t) - \frac{\pi}{4} \right).$$

Variation of Parameters. We seek a solution in the form

$$y(t) = u_1(t)t^2 + u_2(t)t^3.$$

where $u_1'(t)$ and $u_2'(t)$ satisfy the linear algebraic system

$$u_1'(t)t^2 + u_2'(t)t^3 = 0, \quad u_1'(t)2t + u_2'(t)3t^2 = \frac{t}{1+t^2}.$$

The solution of this system is

$$u_1'(t) = -\frac{1}{1+t^2}, \quad u_2'(t) = \frac{1}{t(1+t^2)}.$$

Alternatively, because $W[t^2, t^3](t) = t^4$, the formulas from the book yield

$$u_1'(t) = -\frac{t^3}{t^4} \frac{t}{1+t^2} = -\frac{1}{1+t^2}, \quad u_2'(t) = \frac{t^2}{t^4} \frac{t}{1+t^2} = \frac{1}{t(1+t^2)}.$$

No matter how they are obtained, you integrate these equations to find

$$\begin{aligned} u_1(t) &= -\int \frac{1}{1+t^2} dt = c_1 - \tan^{-1}(t), \\ u_2(t) &= \int \frac{1}{t(1+t^2)} dt = \int \frac{1}{t} - \frac{t}{1+t^2} dt \\ &= c_2 + \log(t) - \frac{1}{2} \log(1+t^2) = c_2 + \frac{1}{2} \log \left(\frac{t^2}{1+t^2} \right). \end{aligned}$$

Therefore a general solution is

$$\begin{aligned} y(t) &= (c_1 - \tan^{-1}(t)) t^2 + \left(c_2 + \frac{1}{2} \log \left(\frac{t^2}{1+t^2} \right) \right) t^3 \\ &= c_1 t^2 + c_2 t^3 + \frac{1}{2} t^3 \log \left(\frac{t^2}{1+t^2} \right) - t^2 \tan^{-1}(t). \end{aligned}$$

(11) [10] The vertical displacement of an unforced mass on a spring is given by

$$h(t) = -4 \cos(\pi t) - 3 \sin(\pi t).$$

- (a) Is this system undamped, under damped, critically damped, or over damped? (Give your reasoning!)
- (b) Express $h(t)$ in the amplitude-phase form $h(t) = A \cos(\pi t - \delta)$ with $A > 0$ and $0 \leq \delta < 2\pi$. Label the amplitude and phase. (The phase may be expressed in terms of an inverse trig function.)
- (c) Give the natural frequency and period of this spring-mass system.
- (d) If an external force $F_{ext}(t) = 5 \cos(\omega t)$ is applied, at what value of the driving frequency ω does resonance occur?

Solution (a). The system is undamped because the given displacement $h(t)$ comes from an underlying characteristic polynomial having the conjugate pair of roots $\pm i\pi$.

Solution (b). By comparing

$$A \cos(\pi t - \delta) = A \cos(\delta) \cos(\pi t) + A \sin(\delta) \sin(\pi t),$$

with $h(t) = -4 \cos(\pi t) - 3 \sin(\pi t)$, we see that

$$A \cos(\delta) = -4, \quad A \sin(\delta) = -3.$$

This shows that (A, δ) are the polar coordinates of the point in the plane whose Cartesian coordinates are $(-4, -3)$. Clearly A is given by

$$A = \sqrt{(-4)^2 + (-3)^2} = \sqrt{16 + 9} = \sqrt{25} = 5.$$

Because $(-4, -3)$ lies in the *third quadrant*, the phase δ satisfies $\pi < \delta < \frac{3}{2}\pi$. There are several ways to express δ . A picture shows that if we use π as a reference then

$$\sin(\delta - \pi) = \frac{3}{5}, \quad \tan(\delta - \pi) = \frac{3}{4}, \quad \cos(\delta - \pi) = \frac{4}{5},$$

and we can express the phase by any one of the formulas

$$\delta = \pi + \sin^{-1}\left(\frac{3}{5}\right), \quad \delta = \pi + \tan^{-1}\left(\frac{3}{4}\right), \quad \delta = \pi + \cos^{-1}\left(\frac{4}{5}\right),$$

The same picture shows that if we use $\frac{3}{2}\pi$ as a reference then

$$\sin\left(\frac{3}{2}\pi - \delta\right) = \frac{4}{5}, \quad \tan\left(\frac{3}{2}\pi - \delta\right) = \frac{4}{3}, \quad \cos\left(\frac{3}{2}\pi - \delta\right) = \frac{3}{5},$$

and we can express the phase by any one of the formulas

$$\delta = \frac{3}{2}\pi - \sin^{-1}\left(\frac{4}{5}\right), \quad \delta = \frac{3}{2}\pi - \tan^{-1}\left(\frac{4}{3}\right), \quad \delta = \frac{3}{2}\pi - \cos^{-1}\left(\frac{3}{5}\right).$$

Only one expression for δ is required.

Remark. It is incorrect to give the phase by one of the formulas

$$\delta = \sin^{-1}\left(-\frac{3}{5}\right), \quad \delta = \tan^{-1}\left(\frac{3}{4}\right), \quad \delta = \cos^{-1}\left(-\frac{4}{5}\right),$$

because, by our conventions for the range of the inverse trigonometric functions, $\sin^{-1}\left(-\frac{3}{5}\right)$ lies in $(-\frac{\pi}{2}, 0)$, $\tan^{-1}\left(\frac{3}{4}\right)$ lies in $(0, \frac{\pi}{2})$, while $\cos^{-1}\left(-\frac{4}{5}\right)$ lies in $(\frac{\pi}{2}, \pi)$.

Solution (c). The natural frequency ω_o is π , so the natural period T_o is given by

$$T_o = \frac{2\pi}{\omega_o} = \frac{2\pi}{\pi} = 2 \text{ sec.}$$

Solution (d). Resonance occurs when the driving frequency ω equals the natural frequency ω_o . Given the answer to part (c), resonance occurs when

$$\omega = \omega_o = \pi \quad 1/\text{sec}.$$

- (12) [8] When a 5 gram mass is hung vertically from a spring, at rest it stretches the spring 9.8 cm. (Gravitational acceleration is $g = 980 \text{ cm/sec}^2$.) At $t = 0$ the mass is displaced 7 cm below its rest position and is released with a downward velocity of 3 cm/sec. The medium imparts a damping force of 120 dynes (1 dyne = 1 gram cm/sec^2) when the speed of the mass is 2 cm/sec. Assume that the spring force is proportional to displacement, that the damping is proportional to velocity, and that there are no other forces.

- (a) Formulate an initial-value problem that governs the motion of the mass for $t > 0$. (DO NOT solve this initial-value problem, just write it down!)
- (b) What is the quasifrequency ν of this spring?

Solution (a). Let $h(t)$ be the displacement (in centimeters) of the mass from its rest position at time t (in seconds), with upward displacements being positive. The governing initial-value problem then has the form

$$mh'' + \gamma h' + kh = 0, \quad h(0) = -7, \quad h'(0) = -3,$$

where m is the mass, γ is the damping coefficient, and k is the spring constant. We are given that $m = 3$ grams. We obtain k by balancing the force applied by the spring when it is stretched 9.8 cm with the weight of the mass ($mg = 5 \cdot 980$ dynes). This gives $k \cdot 9.8 = 5 \cdot 980$, or

$$k = \frac{5 \cdot 980}{9.8} = 500 \text{ dynes/cm}.$$

We obtain γ by balancing the damping force when the speed of the mass is 2 cm/sec with 120 dynes. This gives $\gamma \cdot 2 = 120$, or

$$\gamma = \frac{120}{2} = 60 \text{ dynes sec/cm}$$

Therefore the governing initial-value problem is

$$5h'' + 60h' + 500h, \quad h(0) = -7, \quad h'(0) = -3.$$

Solution (b). The normal form of the governing equation is

$$h'' + 12h' + 100h.$$

Its characteristic polynomial is

$$p(z) = z^2 + 12z + 100 = (z + 6)^2 + 64 = (z + 6)^2 + 8^2.$$

This has conjugate roots $-6 \pm i8$. Therefore the quasifrequency is given by $\nu = 8$ 1/sec.