

Lecture 22 - Gravitational Instability

11/09/17

Guest Lecturer: Dr. Mark Swisdak

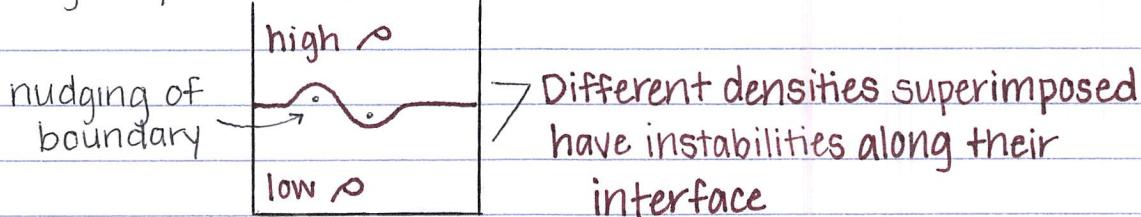
Rayleigh-Taylor Instability

- a.k.a. gravitational instability

Rayleigh-Taylor (RT) is the instability of the interface between two fluids of different densities superimposed one over the other

From ASTR680 - High Energy Astrophysics:

{ Taught by Cole Miller, no textbook }



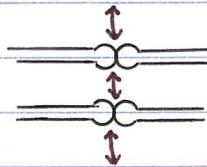
Magnetically, this means it is energetically favorable for matter to nudge the lines around than to try to break through the lines.

• side view:



It's hard to push here - that is, it's very difficult for matter to break through lines

• top view:



It's much easier to push here - that is, it takes much less energy to nudge these lines around

(returning to PHYS761...)

Examples:

- Mushroom cloud
- Supernova remnants



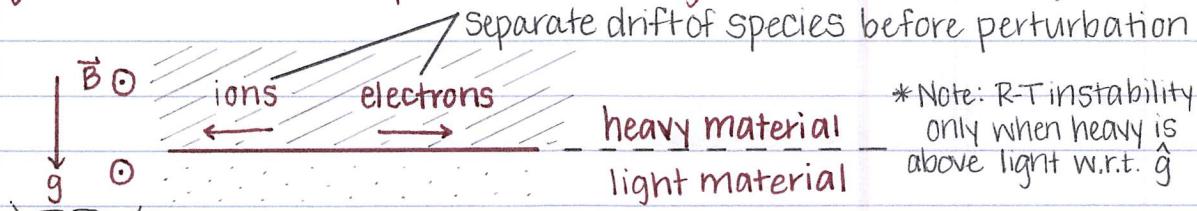
dense ISM

star

Hot gas

observed R-T instability @ density gradient interface

Rosenbluth & Longmire (1957) showed a plasma in an [effective] gravitational field experiences Rayleigh-Taylor instability.



plasma layer can be supported against gravity by a \vec{B} -field
(dependent on \vec{B} -field orientation)

Electron and Ion drift:

$$\vec{V} = \frac{C}{qB^2} \vec{F}_\perp \times \vec{B} \quad \text{gravity}$$

* Similar to \vec{V}_\perp from Lec. #17;
 $\vec{B} \times (q/C) \underbrace{\vec{V}_\perp \times \vec{B}}_{= -\vec{F}_\perp} = -\vec{F}_\perp$

- charge determines direction of particle drift

\vec{J}_k along \hat{b} does not affect the development of R-T instability

- this balances out to lowest order

$$0 = \rho \vec{g} + \frac{1}{c} (\vec{J} \times \vec{B}) \\ = n \text{ (Net Force)}$$

\vec{B} -field plays a larger role in supporting plasma against gravity in regions of higher density

$$\Rightarrow \vec{J} = \sigma_0 \frac{(\vec{q} \times \vec{B})}{B^2}$$

Orientation of \vec{B} with respect to \vec{g} determines current within the plasma

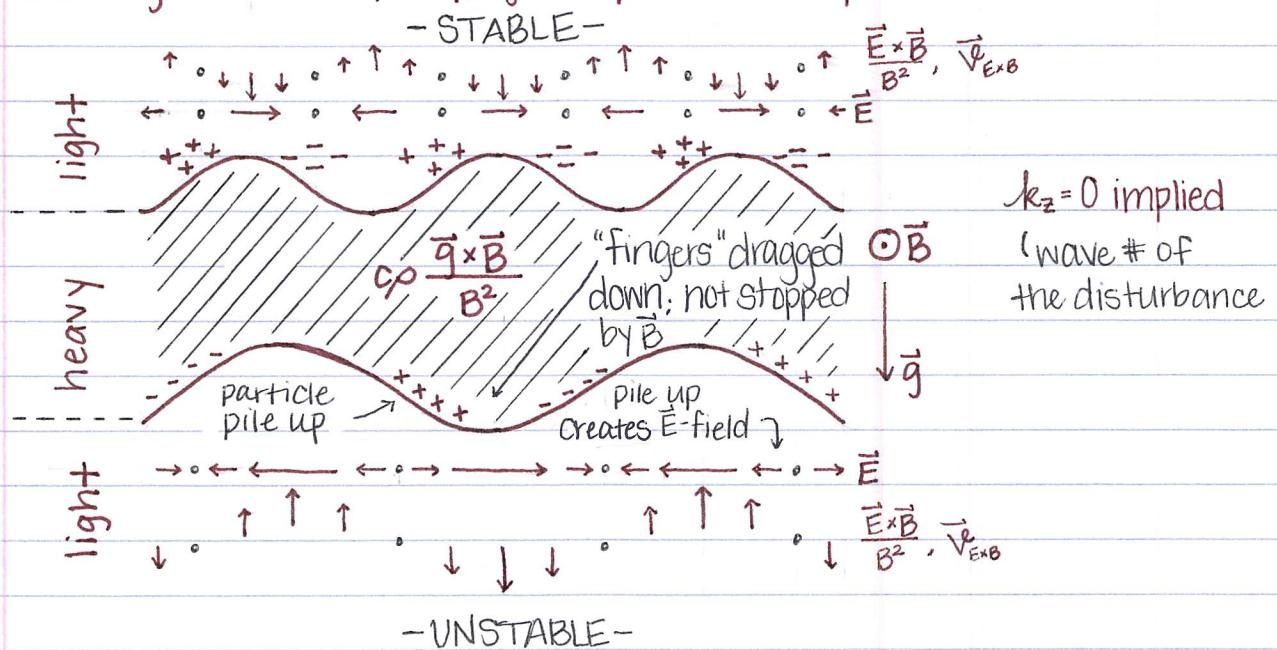
heavy
light $\Theta \vec{B}$ Same result as no \vec{B} -field
 \vec{k} chosen to be $\perp \vec{B}$ here

heavy
light $\rightarrow \vec{B}$ Instability still can occur
a different \vec{k} must be chosen in order
not to perturb \vec{B}

* Note: A rotating / twisting \vec{B} -field is the only arrangement that allows stabilization

KLE

We can visualize the geometry for a simple physical description of the gravitational / Rayleigh-Taylor instability:



Equilibria

To analyze stability, we must start with an equilibrium and then linearize our equations around that equilibrium

→ We will give several examples

$$\begin{aligned}
 & \hat{y} \uparrow \\
 & \hat{z} \text{ (Earth)} \quad \hat{x} \\
 & \uparrow \nabla \rho \quad \downarrow g \\
 & \vec{B} = B_0(y) \hat{z} \\
 & \rho = \rho_0(y) \\
 & P = P_0(y), \text{ where } \frac{dP}{dy} = -\rho g \text{ in hydrostatic equilibrium in the absence of } \vec{B}
 \end{aligned}$$

Force Balance

To 0th order — momentum conservation in the vertical direction (\hat{y})

$$0 = -\frac{\partial}{\partial y} \left(P_0 + \frac{B_0^2}{8\pi} \right) - \rho_0 g$$

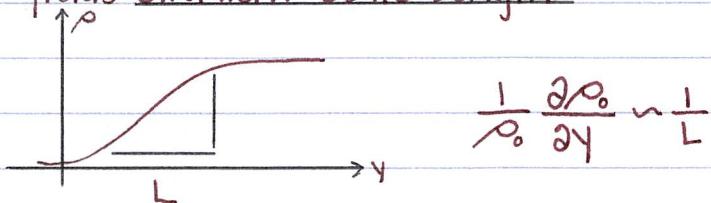
where the full momentum conservation equation here is

$$\underbrace{\rho \left(\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \nabla \vec{u} \right)}_{\vec{u} = 0 \text{ for ideal equilibria (no flow)}} = -\nabla \left(P + \frac{B^2}{8\pi} \right) + \frac{1}{4\pi} (\vec{B} \cdot \nabla) \vec{B} - \rho g$$

where $(\vec{B} \cdot \nabla) \vec{B} = B^2 \vec{R}$ (from Lec. #1a), but $\vec{R} = 0$ for our straight field lines.

How does our density change with height?

↳ yields Gradient Scale Length



such that we may make the scaling/dimensional argument

$$\nabla \sim 1/L$$

• System timescales:

- from the quantities L, g , we have 3 system timescales

$$\gamma_{\text{growth rate}} = \gamma_g \sim \sqrt{\frac{g}{L}}$$

this is just w for a simple pendulum!

$$\gamma_{\text{sound waves}} = \gamma_s \sim \frac{c_s}{L}$$

✓ fast-mode propagation time

$$\gamma_{\text{fast mode}} = \gamma_f \sim \frac{c_f}{L}, \quad c_f^2 = c_a^2 + c_s^2$$

where the fast mode is a combination of both magnetic and plasma pressure

** If possible, this mode should be used primarily over γ_s

Assume $\gamma_g \ll \gamma_s, \gamma_g \ll \gamma_f$ (weak gravitation)

⇒ This is the Boussinesq Approximation

- {from Wiki} In the field of buoyancy-driven flow/natural convection, it ignores density differences except where they appear in terms multiplied by \vec{g} . The essence of the Boussinesq approximation is that the differences in inertia between two fluids is negligible but gravity is sufficiently strong to make the specific

weights appreciably different → Sound waves are impossible/
neglected when the Boussinesq
approximation is used since sound waves
move via density variations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = 0$$

continuity eq. for conservation of mass

If density variations are ignored via the Boussinesq approximation,
this reduces to:

$\nabla \cdot \vec{u} \approx 0 \rightarrow$ nearly incompressible motion!

The MHD Equations: (a recap for moving forward)

① Conservation of momentum

$$\rho \frac{\partial \vec{u}}{\partial t} + \rho (\vec{u} \cdot \nabla) \vec{u} = - \nabla \left(P + \frac{B^2}{8\pi} \right) + \underbrace{\frac{1}{4\pi} (\vec{B} \cdot \nabla) \vec{B}}_{\text{This term is very large compared to the others and needs to be annihilated}} - \rho \vec{g}$$

This term is very large compared to the others and needs to be annihilated

② Faraday's Law

$$\frac{\partial \vec{B}}{\partial t} - \nabla \times (\vec{u} \times \vec{B}) = 0$$

(\vec{E} -field eqn. already substituted in)

③ Conservation of energy (the pressure/energy eqn.)

$$\frac{\partial P}{\partial t} + (\vec{u} \cdot \nabla) P + \Gamma P (\nabla \cdot \vec{u}) = 0$$

Ratio of specific heats

$$\Gamma = (n_f + 2)/n_f \quad \# \text{D.O.F.}$$

④ Conservation of mass

$$\frac{\partial \rho}{\partial t} + (\vec{u} \cdot \nabla) \rho + \rho (\nabla \cdot \vec{u}) = 0$$

Linearized Equations

The above equations are what we want to linearize about our equilibrium.

$$\rho = \rho_0 + \rho_1$$

$$\rho_1(x, y, t) = \operatorname{Re}\{\hat{\rho}(y) e^{ikx - iwt}\}$$

complex amplitude

only variation in x ; $\frac{\partial}{\partial z} = 0$

$$\vec{B} = \vec{B}_0 + \vec{B}_1$$

$$\text{assumed } \vec{B}_1 = \operatorname{Re}\{\hat{\vec{B}}(y) e^{ikx - iwt}\}$$

$$\hat{k} = k\hat{i}$$

$$\text{from this, } \vec{B}_1 = B_1(x, y) \hat{z}$$

$$\underbrace{(\vec{B}_1 \cdot \nabla) \vec{B}_0}_{\hat{z}} \text{, where } \frac{\partial}{\partial z} = 0, = 0$$

Equation ①

$$\rho_0 \frac{\partial}{\partial t} \vec{U} + \rho (\vec{U} \cdot \nabla) \vec{U} = -\nabla (P + \frac{1}{8\pi} B^2) + \frac{1}{4\pi} (\vec{B} \cdot \nabla) \vec{B} - \rho \vec{g}$$

$$\text{where } (\vec{U} \cdot \nabla) \vec{U} = U_y \frac{\partial}{\partial y} \vec{U} = 0$$

linearizing...

$$\underbrace{\rho_0 \frac{\partial \vec{U}_1}{\partial t}}_{\text{Perturbation}} = - \left(P_1 + \frac{\vec{B}_0 \cdot \vec{B}_1}{4\pi} \right) + \frac{1}{4\pi} \left[(\vec{B}_1 \cdot \nabla) \vec{B}_0 + (\vec{B}_0 \cdot \nabla) \vec{B}_1 \right] - \rho \vec{g}$$

Perturbation is 1st order only; equilibrium terms like \vec{U}_0 are gone

$$\rho_0 \frac{\partial \vec{U}_1}{\partial t} = -\nabla \left(P_1 + \frac{\vec{B}_0 \cdot \vec{B}_1}{4\pi} \right) - \rho \vec{g}$$

Equation ②

$$\frac{\partial}{\partial t} \vec{B} - \nabla \times (\vec{U} \times \vec{B}) = \underbrace{U_y \frac{\partial \vec{B}_0}{\partial y}}$$

$$\frac{\partial \vec{B}_1}{\partial t} - \nabla \times (\vec{U}_1 \times \vec{B}_0) = 0 = \frac{\partial \vec{B}_1}{\partial t} - (\vec{B}_1 \cdot \nabla) \vec{U}_1 + (\vec{U}_1 \cdot \nabla) \vec{B}_0 + \vec{B}_0 (\nabla \cdot \vec{U}_1) - \vec{U}_1 (\nabla \cdot \vec{B}_0)$$

$$\frac{\partial}{\partial t} \vec{B}_0 = 0$$

 $\vec{B}_1 \cdot \nabla$ must = 0 for $(\vec{B}_1 \cdot \nabla) \vec{B}_0 = 0$ to hold true for all values of \vec{B}_0 .

$$\frac{\partial \vec{B}_1}{\partial t} + \vec{B}_0 (\nabla \cdot \vec{U}_1) + U_y \frac{\partial}{\partial y} \vec{B}_0 = 0$$

- **Equation ③**

$$\frac{\partial}{\partial t} P + (\vec{U} \cdot \nabla) P + \Gamma P (\nabla \cdot \vec{U}) = 0$$

$= U_N \underbrace{\frac{\partial P}{\partial Y}}_{P_0}$

$$\frac{\partial P_i}{\partial t} + (\vec{U}_i \cdot \nabla) P_i + \Gamma P_i (\nabla \cdot \vec{U}_i) = 0$$

$\underbrace{\frac{\partial}{\partial t} P_i}_{= 0} = 0$

$$\frac{\partial P_i}{\partial t} + U_N \underbrace{\frac{\partial P_i}{\partial Y}}_{P_0} + \Gamma P_i (\nabla \cdot \vec{U}_i) = 0$$

- **Equation ④**

$$\frac{\partial}{\partial t} \rho + (\vec{U} \cdot \nabla) \rho + \rho (\nabla \cdot \vec{U}) = 0$$

$= U_N \underbrace{\frac{\partial \rho}{\partial Y}}_{\rho_0}$

$$\frac{\partial \rho_i}{\partial t} + (\vec{U}_i \cdot \nabla) \rho_i + \rho_i (\nabla \cdot \vec{U}_i) = 0$$

$\underbrace{\frac{\partial}{\partial t} \rho_i}_{= 0} = 0$

$$\frac{\partial \rho_i}{\partial t} + U_N \underbrace{\frac{\partial \rho_i}{\partial Y}}_{\rho_0} + \rho_i (\nabla \cdot \vec{U}_i) = 0$$

We need to figure out how big this is
 (Want to show the $\nabla \cdot \vec{U} \approx 0$ approximation works here)

⇒ Use low frequency ordering

• from equation ③

say these two terms are comparable

$$\frac{\partial P_i}{\partial t} + U_N \underbrace{\frac{\partial P_i}{\partial Y}}_{P_0} + \Gamma P_i (\nabla \cdot \vec{U}_i) = 0$$

$\underbrace{\frac{\partial P_i}{\partial Y}}_{\approx \gamma} \rightarrow \frac{1}{L}$, the length scale of the instability
 $\underbrace{\frac{\partial}{\partial t} P_i}_{\approx \gamma t} \rightarrow \gamma_g$, the timescale of the instability

$\gamma_g P_i \ll U_i \frac{P_0}{L}$ Supports that $P_i + \frac{B_0 \cdot B_i}{4\pi}$ is large.

→ then, comparing the left-hand-side & P_i term in equation ①

$$\rho_i \frac{\partial \vec{U}_i}{\partial t} = -\nabla \left(P_i + \frac{B_0 \cdot B_i}{4\pi} \right) - \rho_i g$$

$\underbrace{\rho_i g}_{\text{small}} \quad \underbrace{\text{same order as } P_i}_{\text{as previously stated}}$

$$\rho_0 \gamma_g U_i \sim \frac{1}{L} P_i \left(\frac{\gamma_g}{\gamma_s} \right) \sim \gamma_g P_i = U_i P_0 / L$$

$$\rho_0 \gamma_g U_i \sim \frac{1}{L} \frac{U_i}{L} \frac{P_0}{\gamma_g}$$

$$\gamma_g^2 \sim \frac{P_0}{\rho_0 L^2} \sim \gamma_s$$

$\gamma_g^2 \sim \gamma_s^2 \rightarrow$ implies that $P_i + \frac{B_0 \cdot B_i}{4\pi}$ is huge

To lowest order

$$\rightarrow P_i + \frac{B_0 \cdot B_i}{4\pi} \approx 0$$

The pressure from the plasma & the \vec{B} -field must balance / very nearly cancel out because the other terms are small

NOW: Add $(B_0/4\pi)(2) + (3)$

\rightarrow gives equations for B_i & P_i , yields above combination

$$\left(\frac{\vec{B}_0}{4\pi} \right) \left[\frac{\partial \vec{B}_i}{\partial t} + \vec{B}_0 (\nabla \cdot \vec{U}_i) + U_{iN} \frac{\partial \vec{B}_0}{\partial y} \right] + \left[\frac{\partial P_i}{\partial t} + U_{iN} \frac{\partial P_0}{\partial y} + \Gamma P_0 (\nabla \cdot \vec{U}_i) \right]$$

use pressure balance

$$\begin{aligned} &= \frac{\partial}{\partial t} \left(P_i + \frac{\vec{B}_0 \cdot \vec{B}_i}{4\pi} \right) + U_{iN} \underbrace{\left[\frac{\partial P_0}{\partial y} + \frac{\partial}{\partial y} \left(\frac{B^2}{8\pi} \right) \right]}_{= \frac{\partial}{\partial y} (P_0 + B^2/8\pi)} + (\nabla \cdot \vec{U}_i) \left[\frac{B_0^2}{4\pi} + \Gamma P_0 \right] = 0 \end{aligned}$$

the 0th order momentum conservation eq.

\downarrow Solve for $\nabla \cdot \vec{U}_i$, \downarrow

$$(\nabla \cdot \vec{U}_i) \left[\frac{B_0^2}{4\pi} + \Gamma P_0 \right] = U_{iN} \rho_0 g - \frac{\partial}{\partial t} \left(P_i + \frac{\vec{B}_0 \cdot \vec{B}_i}{4\pi} \right)$$

$$\nabla \cdot \vec{U}_i = \frac{U_{iN} \rho_0 g - \frac{\partial}{\partial t} \left(P_i + \frac{\vec{B}_0 \cdot \vec{B}_i}{4\pi} \right)}{\left[\frac{B_0^2}{4\pi} + \Gamma P_0 \right]} \quad \text{small}$$

As stated above, these large terms must approximately cancel each other out (to first order)

$$\nabla \cdot \vec{U}_1 = U_{1x} \frac{\rho_0}{(B_0^2/4\pi + \Gamma P_0)} = \frac{U_{1x} \bar{g}}{C_A^2 + C_S^2} \sim \frac{U_{1x}}{L} \frac{\bar{g}^2}{\gamma_f^2}$$

$C_S^2 = \frac{\Gamma P_0}{\rho_0}$

$$C_A^2 = \frac{B_0^2}{4\pi \rho_0}$$

for $\gamma_g \ll \gamma_f$

$$\left[\frac{U_{1x}}{L} \frac{\bar{g}^2}{\gamma_f^2} \right] \ll \frac{U_{1x}}{L}$$

$\nabla \cdot \vec{U}_1 \ll \frac{U_{1x}}{L} \Rightarrow$ Nearly incompressible!

From this we know it is valid under these conditions to use the Boussinesq appx., $\nabla \cdot \vec{U} \approx 0$

We must annihilate the pressure term in Eq. ①

Operate with $\hat{z} \cdot \nabla \times$

$$\hat{z} \cdot \nabla \times \left[\rho_0 \frac{\partial \vec{U}_1}{\partial t} \right] = \hat{z} \cdot \nabla \times \left[-\nabla \left(P_i + \frac{\vec{B}_0 \cdot \vec{B}_1}{4\pi} \right) - \rho_0 \bar{g} \right]$$

$$\nabla^2 \left(P_i + \frac{\vec{B}_0 \cdot \vec{B}_1}{4\pi} \right) = 0 \quad \text{- taking the curl is the only way to guarantee annihilation of this large pressure term}$$

$$\hat{z} \cdot \nabla \times \left(\rho_0 \frac{\partial \vec{U}_1}{\partial t} \right) = -\hat{z} \cdot \nabla \times (\rho_0 g \hat{y})$$

$$= -g \frac{\partial \rho_0}{\partial x}$$

$$\hat{z} \cdot \nabla \times \left(\rho_0 \frac{\partial \vec{U}_1}{\partial t} \right) = \underbrace{\frac{\partial}{\partial x} \left(\rho_0 \frac{\partial U_{1y}}{\partial t} \right)}_{\partial/\partial x \rightarrow ik} - \underbrace{\frac{\partial}{\partial y} \left(\rho_0 \frac{\partial U_{1x}}{\partial t} \right)}_{\partial/\partial t \rightarrow -iw} = -g \frac{\partial \rho_0}{\partial x}$$

$$ik(-iw) \rho_0 \hat{U}_{1y} + iw \frac{\partial}{\partial y} \left(\rho_0 \hat{U}_{1x} \right) = -g_{ik} \hat{o}$$

- Use eq. ④ with $\nabla \cdot \vec{U} = 0$

$$\frac{\partial}{\partial t} \rho_0 + \hat{U}_{1y} \frac{\partial}{\partial y} \rho_0 + \rho_0 (\nabla \cdot \vec{U}) \stackrel{0}{=} 0$$

$$iw\rho_i = \hat{U}_{iy} \frac{\partial}{\partial y} \rho_i$$

↓ plugging into our expression from eq. ① ↓

$$kw\rho_0 \hat{U}_{iy} + iw \frac{\partial}{\partial y} (\rho_0 \hat{U}_{ix}) = -gik \frac{\hat{U}_{iy} \frac{\partial}{\partial y} \rho_0}{iw}$$

$$w^2 \left[kw\rho_0 \hat{U}_{iy} + i \frac{\partial}{\partial y} (\rho_0 \hat{U}_{ix}) \right] = -gik \hat{U}_{iy} \frac{\partial}{\partial y} \rho_0$$

want to get everything in y-components

→ Linearize eq. ④

$$ik\hat{U}_{ix} + \frac{\partial}{\partial y} (\hat{U}_{iy}) = 0 \Rightarrow \hat{U}_{ix} = -\frac{1}{ik} \frac{\partial}{\partial y} (\hat{U}_{iy})$$

↓ substituting for \hat{U}_{ix} ↓

$$w^2 \left[kw\rho_0 \hat{U}_{iy} + i \frac{\partial}{\partial y} \left(\rho_0 \left(-\frac{1}{ik} \frac{\partial}{\partial y} \hat{U}_{iy} \right) \right) \right] = -gik \hat{U}_{iy} \frac{\partial}{\partial y} \rho_0$$

└ multiply through by $-k$

$$w^2 \left[\frac{\partial}{\partial y} \left(\rho_0 \frac{\partial}{\partial y} \hat{U}_{iy} \right) - k^2 \rho_0 \hat{U}_{iy} \right] = gk^2 \hat{U}_{iy} \frac{\partial \rho_0}{\partial y}$$

⇒ No dependence on the \vec{B} -field at all!

└ supports our statement that $\odot \vec{B}$ w.r.t. \vec{g} has the same effects as no field at all!

Limiting Solutions

We want to solve equation ⑤ under two limits:

• First take $kL \gg 1$

this is the short wavelength perturbation

$$\lambda_L \sim \frac{\partial}{\partial y} \text{ so } \frac{\partial}{\partial y} \ll k$$

Eqn. ⑤ then becomes

$$w^2 \left[\frac{\partial}{\partial y} \left(\rho_0 \frac{\partial}{\partial y} \hat{U}_{iy} \right) - k^2 \rho_0 \hat{U}_{iy} \right] = gk^2 \hat{U}_{iy} \frac{\partial \rho_0}{\partial y}$$

This term, with
two factors of $\frac{\partial}{\partial y}$, is
much SMALLER than

FIVE STAR.

FIVE STAR.

FIVE STAR.

FIVE STAR.

$$\rightarrow -w^2 k^2 \rho_0 \hat{U}_{Ny} = g k^2 \hat{U}_{Ny} \frac{\partial \rho_0}{\partial y}$$

$$w^2 = -\frac{g}{\rho_0} \frac{\partial \rho_0}{\partial y} \sim \frac{1}{L}, \text{ the gradient scale length}$$

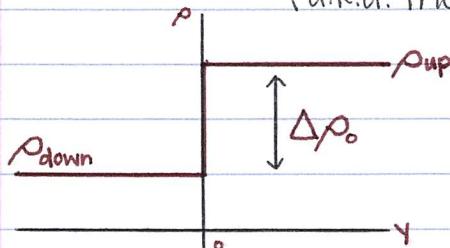
$$= -g/L = -\gamma_g^2$$

unstable if $\frac{\partial \rho_0}{\partial y} > 0$

(heavy fluid above light)

 \Rightarrow Heavy fluid falling in a gravitational field releases energy

$$\gamma^2 = \text{timescale of the instability} = \gamma_g^2$$

• Second, take $kL \ll 1$ this is the long wavelength perturbation
(a.k.a. the sharp boundary limit)

- Away from the boundary (jump)

$$\rho_0(y) = \rho_0 \rightarrow \frac{\partial \rho_0}{\partial y} = 0$$

Eqn. ⑤ then becomes

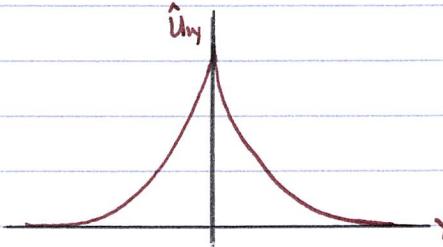
$$w^2 \left[\frac{\partial}{\partial y} \left(\rho_0 \frac{\partial}{\partial y} \hat{U}_{Ny} \right) - k^2 \rho_0 \hat{U}_{Ny} \right] = g k^2 \hat{U}_{Ny} \frac{\partial \rho_0}{\partial y} = 0$$

pull out

$$w^2 \rho_0 \left[\frac{\partial^2}{\partial y^2} \hat{U}_{Ny} - k^2 \hat{U}_{Ny} \right] = 0$$

$$w^2 \rho_0 \left[\frac{\partial^2}{\partial y^2} - k^2 \right] \hat{U}_{Ny} = 0$$

$$\rightarrow \hat{U}_{Ny} = \begin{cases} U_{Ny} e^{-iky}, & y > 0 \\ U_{Ny} e^{iky}, & y < 0 \end{cases}$$



* the slope of \hat{u}_{1y} undergoes a jump but the magnitude of \hat{u}_{1y} does not

- Near the boundary (jump)

$$\frac{\partial}{\partial y} \gg k^2$$

Eqn. ⑤ then becomes

$$\omega^2 \left[\frac{\partial}{\partial y} \left(\rho_0 \frac{\partial}{\partial y} \hat{u}_{1y} \right) - k^2 \rho_0 \hat{u}_{1y} \right] = g k^2 \hat{u}_{1y} \frac{\partial \rho_0}{\partial y}$$

This term, with
two factors of $\frac{\partial}{\partial y}$, is
much LARGER than

$$\rightarrow \omega^2 \left[\frac{\partial}{\partial y} \rho_0 \frac{\partial}{\partial y} \hat{u}_{1y} \right] = g k^2 \frac{\partial \rho_0}{\partial y} \hat{u}_{1y}$$

Must integrate over
the boundary

$$-\epsilon \int_{-\epsilon}^{\epsilon} dy$$

$$\omega^2 \int_{-\epsilon}^{\epsilon} \left[\frac{\partial}{\partial y} \rho_0 \frac{\partial}{\partial y} \hat{u}_{1y} \right] dy = \omega^2 \rho_0 \frac{\partial}{\partial y} \hat{u}_{1y} \Big|_{-\epsilon}^{\epsilon}$$

use "away from boundary" solution

$$= \omega^2 \left[\rho_0^{\text{up}} (-k \hat{u}_{1y}) - \rho_0^{\text{down}} (k \hat{u}_{1y}) \right]_{y=0}$$

$$= -\omega^2 k \hat{u}_{1y}(0) [\rho_{\text{up}} + \rho_{\text{down}}]$$

$$-\epsilon \int_{-\epsilon}^{\epsilon} g k^2 \hat{u}_{1y} \frac{\partial \rho_0}{\partial y} dy = g k^2 \hat{u}_{1y}(0) [\rho_{\text{up}} - \rho_{\text{down}}]$$

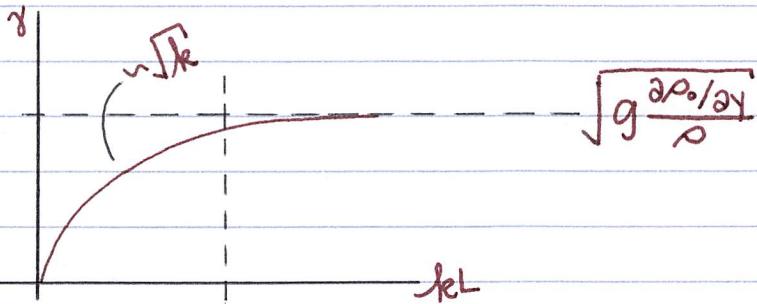
↓ putting this together ↓

$$-\omega^2 k \hat{u}_{1y}(0) [\rho_{\text{up}} + \rho_{\text{down}}] = g k^2 \hat{u}_{1y}(0) [\rho_{\text{up}} - \rho_{\text{down}}]$$

$$\omega^2 = -gk \underbrace{\frac{[\rho_{\text{up}} - \rho_{\text{down}}]}{[\rho_{\text{up}} + \rho_{\text{down}}]}}$$

IF $\rho_{\text{up}} > \rho_{\text{down}}$, there is an instability

$$\gamma^2 = \frac{gk \Delta \rho_0}{[\rho_{\text{up}} + \rho_{\text{down}}]}$$



* Notice that the magnetic field is not able to stop the growth of the instability. \vec{B}_0 is simply convected with the flow.

In "real life":

- ↳ including small-scale effects,
- surface tension
- viscosity