

Lecture 4 - Formations of Lagrangians.

09/10/15

Today:

1. Finish up conservation laws
2. Noether's Theorem

1. Conservation.

For cyclic coordinate q_j ; ($\frac{\partial \mathcal{L}}{\partial q_j} = 0$) $\Rightarrow p = \frac{\partial \mathcal{L}}{\partial \dot{q}_j}$ is conserved

canonical/conjugate momentum

Last lecture: General coordinate q_j ; chosen such that dq_j is a small uniform translation of the entire closed system:

$$\mathcal{L} = \sum_i \frac{1}{2} m \dot{\vec{r}}_i^2 - V(|\vec{r}_i - \vec{r}_j|)$$

- p is linear total momentum of all the particles
in the closed system

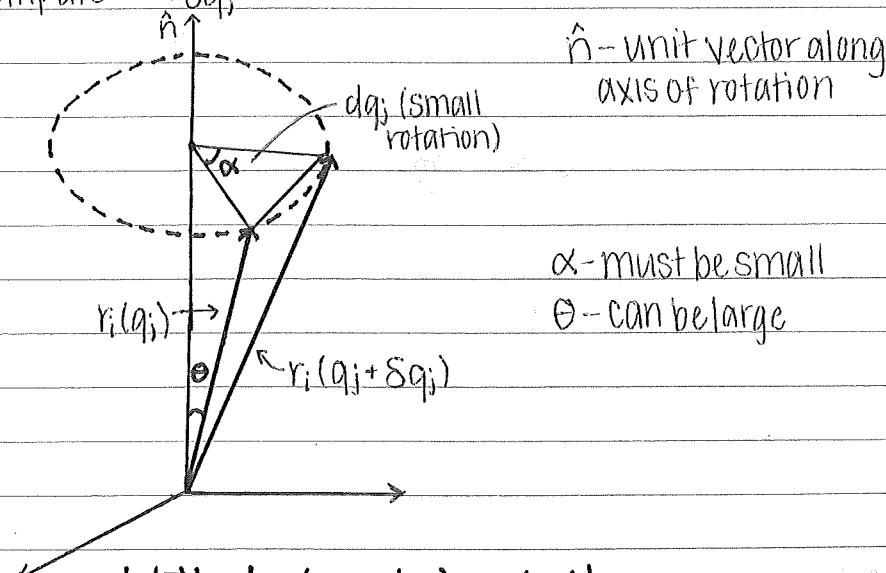
Ex: What else is conserved for $\mathcal{L} = \sum_i \frac{1}{2} m \dot{\vec{r}}_i^2 - V(|\vec{r}_i - \vec{r}_j|)$?

Angular momentum is conserved!

(At least in this case. Whether or not it is conserved for all cases depends on the form of the potential.)

Choose q_j such that dq_j is a small rotation of the entire system about some axis

... compute $\frac{\partial \vec{r}_i}{\partial q_j}$



α - must be small

Θ - can be large

$$|d\vec{r}_i| = |\vec{r}_i(q_j + dq_j) - \vec{r}_i(q_j)|$$
$$= r_i \sin(\theta) dq_j$$

↑ magnitude of the two position vectors is nonzero

$$\left| \frac{\partial \vec{r}_i}{\partial q_j} \right| = r_i \sin(\theta) \quad \text{direction is perpendicular}$$

to both \vec{r}_i and \hat{n}

$$\Rightarrow \frac{\partial \vec{r}_i}{\partial q_j} = \hat{n} \times \vec{r}_i$$

... compute the canonical momentum to this new coordinate, q_j :

$$① P_j = \frac{\partial \mathcal{L}}{\partial \dot{q}_j} = \sum_i (m_i \vec{v}_i) \cdot \left(\frac{\partial \vec{r}_i}{\partial q_j} \right) \quad \begin{matrix} \text{time derivatives here cancel out} \\ (\text{do not need to write}) \end{matrix}$$

U only dependent on \vec{r} , not on $\vec{\dot{r}}$

$$= \sum_i (m_i \vec{v}_i) \cdot (\hat{n} \times \vec{r}_i) \quad \text{angular momentum}$$

$$= \sum_i \hat{n} \cdot [\vec{r}_i \times (m_i \vec{v}_i)] = \hat{n} \cdot \sum_i \vec{L}_i = \hat{n} \cdot \vec{L} \quad \begin{matrix} \text{total orbital angular momentum} \\ \text{along axis of rotation (direction } \hat{n} \text{)} \end{matrix}$$

$$② \text{ Use } V(|\vec{r}_i - \vec{r}_j|) \quad \text{assumed sum over all values}$$

i.e. the fact that it's only dependent on \vec{r}

$\Rightarrow q_j$ is cyclic

↑ form of the potential is unchanged (because it takes the magnitude), so that small change is cyclic

→ Energy is conserved ← may or may not be explicitly time dependent + energy "function", $h(q, \dot{q}, t)$

for n independent variables

$$h = \sum_j (q_j \frac{\partial \mathcal{L}}{\partial \dot{q}_j} - \mathcal{L})$$

h constant if Lagrangian is independent of time ($\frac{\partial \mathcal{L}}{\partial t} = 0$)

$$\frac{dh}{dt} = \sum \left[\ddot{q}_j \frac{\partial \mathcal{L}}{\partial q} + \dot{q}_j \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}_j} \right) - \dot{q}_j \frac{\partial \mathcal{L}}{\partial \dot{q}_j} - \frac{\partial \mathcal{L}}{\partial q} \ddot{q}_j \right]$$

last term cancels with first

$$= \sum \left\{ \ddot{q}_j \frac{\partial \mathcal{L}}{\partial q} + \dot{q}_j \left[\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}_j} \right) - \frac{\partial \mathcal{L}}{\partial q} \right] - \frac{\partial \mathcal{L}}{\partial q} \ddot{q}_j \right\}$$

0 by Lagrange's equation

$$\frac{dh}{dt} = 0 \quad \text{constant } h$$

Aside:

$H(q, p = \frac{\partial \mathcal{L}}{\partial \dot{q}}) \rightarrow$ a function of $2n$ independent variables

Hamiltonian

For a closed system:

$$h = \sum (\dot{r}_i \cdot m_i \dot{r}_i - \frac{1}{2} m_i \dot{r}_i^2 + V)$$

$$= \sum (+\frac{1}{2} m_i \dot{r}_i^2 + V) \quad \leftarrow$$

$$\mathcal{L} = \sum \frac{1}{2} m_i \dot{r}_i^2 - V(|\vec{r}_i - \vec{r}_j|) \quad \leftarrow$$

$h = \mathcal{L}$, energy is conserved

2. Noether's Theorem.

The succinctly uniform process of showing that energy and momentum are conserved.

→ Can also be used for electric charge, Baryon number, etc.

new coordinates $\xrightarrow{\text{small}}$

General transformation: $q_i(t) \rightarrow \tilde{q}_i(t) = q_i(t) + \alpha \Delta q_i(t)$

shift

continuous transformation

c.f. change of coordinates:

• $\Delta q_i(t)$ were functions of q_i & t ONLY

→ We will not be making this assumption for generalized Noether's Theorem

• Spatial translation - $\Delta q_i = \text{constant}$

→ Also not assuming here that $\Delta q_i(t)$ "vanishes at the endpoints (t_0 & t_f)";

c.f. variational principle where δ (vs. Δ) denoted that the change = 0 at the endpoints

• Such a transformation is symmetric ("a symmetry") if it leaves the final equations of motion unchanged

→ i.e. the physics is unchanged. But not just the form of the EOMs, their values must be unchanged, too!

- as opposed to our previous change to a rotating system...

Old EOM: $m \ddot{\vec{r}} = 0$

New EOM: $m \ddot{\vec{r}}' = [\text{centrifugal + Coriolis forces}] \quad \leftarrow$ final EOM changed

this is still Lagrange's equation

One possibility to satisfy these transformation conditions is to require that \mathcal{L} is unchanged.

- This is possible if \mathcal{L} shifts by a total time derivative

$$\mathcal{L} \rightarrow \mathcal{L} + \alpha \underbrace{\frac{dK}{dt}}_{\alpha \Delta \mathcal{L}} ; \quad I \rightarrow I + \alpha \underbrace{\int_{t_0}^{t_f} dt \frac{dK}{dt}}_{S, \text{action}} = \alpha [K(t_f) - K(t_0)]$$

if change is a total time derivative, then this term = 0 and the EOM is left unaltered

Compare this $\alpha \frac{dK}{dt}$ to a shift in $\mathcal{L}(q, \dot{q}, t)$ from transformation on q 's:

$$\frac{\partial \mathcal{L}}{\partial t} = 0$$

$$\alpha \frac{dK}{dt} = \left(\frac{\partial \mathcal{L}}{\partial q} \right) (\alpha \Delta q) + \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \right) (\alpha \Delta \dot{q}) \quad \left. \begin{array}{l} \text{Change in } \mathcal{L} \text{ due to} \\ \text{those in } q, \dot{q} \end{array} \right\}$$

indices neglected for simplicity

- Still a sum!

→ Use Lagrange's equation

$$\frac{\partial \mathcal{L}}{\partial q} = \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \right)$$

$$= \left(\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}} \right) (\alpha \Delta q) + \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \right) (\alpha \Delta \dot{q})$$

$$= \alpha \frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}} \Delta q \right)$$

$$\Rightarrow \frac{d}{dt} \left[\frac{\partial \mathcal{L}}{\partial \dot{q}_i} \Delta q_i - K \right] = 0 \quad \left. \begin{array}{l} \text{Noether's Theorem - simplest form} \\ \text{constant of motion} \end{array} \right\}$$

Example: Uniform translation

$$\Delta \vec{r}_i = \hat{n}$$

unit vector along the direction of translation

Lagrangian invariant $\rightarrow K = 0$

• Homogeneity of Space (linear momentum is conserved)

$$\text{conserved quantity} \approx \sum_i \frac{\partial \mathcal{L}}{\partial \dot{r}_i} \Delta \vec{r}_i = \sum_i m \dot{r}_i \cdot \hat{n}$$

Component of linear momentum in the direction of translation

• Isotropy of Space (angular momentum is conserved)

$$\Delta \vec{r}_i = -(\hat{n} \times \vec{r}_i)$$

• Homogeneity of Time (energy is conserved)

$$\underbrace{t'}_{\text{new time}} = t - \alpha \rightarrow q'(t') = q(t)$$

↑ Because we are only shifting time, the [new] position at the new-time is the same as it was at the old time (translation or not)

$$\Rightarrow q'(t - \alpha) = q(t)$$

$$q'(t) = q(t + \alpha) \approx q(t) + \alpha \dot{q}$$

Changing time results in a change in coordinates

* Conservation of energy is a change in time that results in a change in space rather than a direct change solely in space as with conservation of momentum

→ Time translation results in a change in the Lagrangian as well

$$\mathcal{L} \rightarrow \mathcal{L} + \alpha \frac{d\mathcal{L}}{dt} \sim K, \text{ now non-zero}$$

$$\text{conserved quantity} = \sum_i \left(\frac{\partial \mathcal{L}}{\partial \dot{r}_i} \right) (\dot{r}_i) - \mathcal{L}$$

↑ conservation of energy

K - extra term here compared to isotropy & homogeneity of space