

Lecture 19 - Time Evolution of Orbits

1. Kepler's 3rd Law
2. r, θ as Functions of t
3. Constants of Motion
4. Scattering

1. Kepler's 3rd Law of Motion

Areal velocity, $\frac{dA}{dt} = \frac{1}{2} r^2 \dot{\theta} = \frac{l}{2m}$ constant

$\Rightarrow$ area of orbit, $A = \frac{lT}{2m} = \pi ab$ semimajor axis
semiminor axis
 $= \pi a^2 \sqrt{1-e^2}$

for the Kepler case:

$$e^2 = 1 + \frac{2El^2}{mk^2}, \quad a = -\frac{k}{2E}$$

$\rightarrow T = \text{orbital period} = 2\pi a^{3/2} \sqrt{\frac{m}{k}}$

3rd Law:

The square of the orbital period is proportional to the cube of the semimajor axis of the orbit.

Reference: Orbit Equation $r(\theta)$

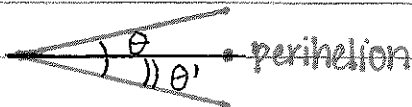
- derived from equation of motion

$$\frac{1}{r} = \frac{mk}{l^2} \left(1 + \underbrace{\sqrt{1 + \frac{2El^2}{mk^2}}}_{e} \cos(\theta - \theta') \right)$$

e - orbital eccentricity

using $a = -k/2E$

$$r(\theta) = \frac{a(1-e^2)}{1 + e \cos(\theta - \theta')}$$



2. r, θ as Functions of t

Formal solution:

$$(1) \quad t = \sqrt{\frac{m}{2}} \int_{r_0}^r dr \left[\frac{k}{r} - \frac{l^2}{2mr^2} + E \right]^{-1/2}$$

↳ invert to get $r(t)$

$$(2) mr^2\dot{\theta} = l$$

$$\Rightarrow dt = \frac{mr^2}{l} d\theta + r(\theta) \quad \text{just the orbit equation}$$

$$t = \frac{l^3}{mk^2_0} \int_{\theta_0}^{\theta} \frac{d\theta}{[1 + e\cos(\theta - \theta')]^2}$$

↳ invert to get $\theta(t)$

Orbital Cases:

① $e=1$, parabola

↳ $\theta' = 0$ here

$$1 + (e=1)\cos(\theta) = 2\cos^2(\theta/2)$$

→ plugging back into $t(\theta)$ →

$$t = \frac{l^3}{4mk^2_0} \int^{\theta} \sec^4\left(\frac{\theta}{2}\right) d\theta$$

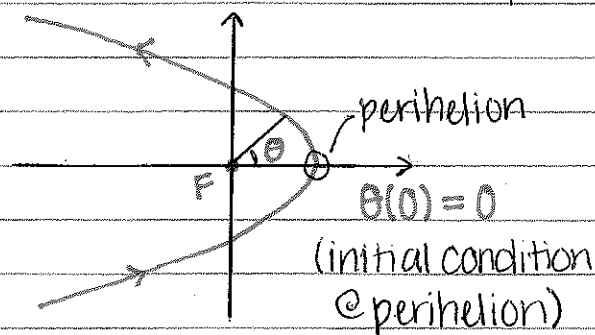
change of variables:

$$\text{let } x = \tan(\theta/2)$$

$$\rightarrow t = \frac{l^3}{2mk^2_0} \int^{\tan(\theta/2)} (1+x^2) dx$$

$$= \frac{l^3}{2mk^2_0} \left[\tan\left(\frac{\theta}{2}\right) + \frac{1}{3} \tan^3\left(\frac{\theta}{2}\right) \right]$$

requires us to solve a cubic equation for $\theta(t)$



Choose $\theta=0$ to be the perihelion

→ $\theta' = 0$ (to maximize r)

$$\begin{aligned} & t \rightarrow +\infty \\ & -\pi < \theta < \pi \\ & \hookrightarrow t \rightarrow -\infty \end{aligned}$$

② $0 < e < 1$, ellipse

$\int dr$ will be a little bit easier than $\int d\theta$

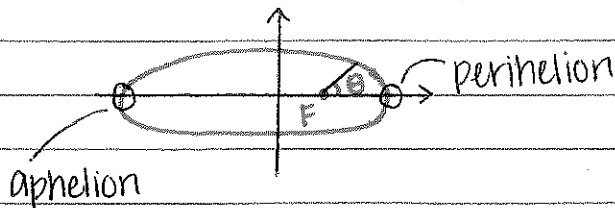
$$r = a(1 - e\cos(\psi)) = \frac{a(1-e^2)}{1+e\cos(\theta)}$$

↳ $\psi \equiv$ eccentric anomaly

* One complete cycle in θ = one complete cycle in ψ

$$\theta = 0 \rightarrow r = a(1-e) \rightarrow \text{perihelion}$$

$$\theta = \pi \rightarrow r = a(1+e) \rightarrow \text{aphelion}$$



$$t = \sqrt{\frac{m}{2}} \int_{r_0}^r dr \left[\frac{k}{r} - \frac{l^2}{2mr^2} + E \right]^{-1/2}$$

→ Replace l and E with expressions for the semimajor axis →

$$E = -k/2a, \quad l^2 = mka(1-e^2)$$

$$t = \sqrt{\frac{m}{2k}} \int_{r_0}^r r dr \left[r - \frac{r^2}{2a} - \frac{a}{2}(1-e^2) \right]^{-1/2}$$

r_0 initial position @ perihelion (assumed)

→ Use eccentric anomaly expression $r(\psi)$ →

$$t = \sqrt{\frac{ma^3}{k}} \int_0^\psi (1 - e \cos(\psi)) d\psi$$

$$\tau = \int_0^{2\pi} \dots d\psi \quad \begin{array}{l} \text{special case for one full period /} \\ \text{one complete orbit} \end{array}$$

τ orbital period

$$= 2\pi a^{3/2} \sqrt{\frac{m}{k}}, \text{ Kepler's 3rd law recovered}$$

• Want to find $\psi(t)$ for any ψ (not just the full period case)

→ plug into $r(\psi)$ to yield $r(t)$

Introduce orbital frequency:

$$\omega = \frac{2\pi}{\tau} = \sqrt{\frac{k}{ma^3}}$$

$$\omega t = \psi - e \sin(\psi) \Rightarrow \text{Kepler's Equation}$$

(a transcendental equation)

By comparing equations for $r(\theta)$ and $r(\psi)$:

$$\theta(\psi) \rightarrow \tan\left(\frac{\theta}{2}\right) = \sqrt{\frac{1+e}{1-e}} \tan\left(\frac{\psi}{2}\right)$$

3. Constants of Motion

- $\mathcal{L}, \theta', E, r, \theta(t_0)$, 4 total constants of motion

- 3 degrees of freedom (x, y, z) or (r, θ, φ) , etc.

$\Rightarrow$ We expect 10 constants of motion

(formed out of initial position and velocity)

Laplace-Runge-Lenz Vector is also a constant of motion!

$$\vec{A} = \vec{p} \times \vec{L} - mk \frac{\vec{r}}{r}$$

- Recall that previously we showed $\vec{A}$ to be a constant of motion using poisson brackets

$$\{\mathcal{H}, A\} = 0$$

$\hookrightarrow$ Show it now using equations of motion (i.e. $d\vec{A}/dt = 0$)

For a general central force, $f(r)$:

$$\dot{\vec{p}} = f(r) \frac{\vec{r}}{r} \leftarrow \text{Newton's 2nd law}$$

$$\begin{aligned} \dot{\vec{p}} \times \vec{L} &= \frac{mf(r)}{r} [\vec{r} \times (\vec{r} \times \dot{\vec{r}})] \\ &= \frac{mf(r)}{r} [\underbrace{\vec{r}(\vec{r} \cdot \dot{\vec{r}})}_{\frac{1}{2} \frac{d}{dt}(\vec{r} \cdot \vec{r}) = r\dot{r}} - r^2 \dot{\vec{r}}] \end{aligned}$$

$\rightarrow$ because $\vec{L}$ is a constant, we can write $\rightarrow$

$$\begin{aligned} \frac{d}{dt}(\vec{p} \times \vec{L}) &= -mf(r)r^2 \left(\frac{\dot{\vec{r}}}{r} - \frac{\vec{r}\dot{r}}{r^2} \right) \\ &= -mf(r)r^2 \frac{d}{dt} \left(\frac{\vec{r}}{r} \right) \end{aligned}$$

specify $f(r) = -k/r^2$; $V = -k/r$

$$\frac{d}{dt}(\vec{p} \times \vec{L}) = \frac{d}{dt} \left(\frac{mk\vec{r}}{r} \right)$$

$\Rightarrow$ For the Kepler problem there is a conserved vector $\vec{A}$

$$\vec{A} = \vec{p} \times \vec{L} - mk \frac{\vec{r}}{r}$$

$\hookrightarrow$ 3 conserved vectors at different positions in the orbit

- Now have $\vec{L}, \vec{E}, \vec{A} \dots$ 7 constants total

↳ One too many!

In this case, it must be that not all of the constants are independent relation:

$\vec{A} \cdot \vec{L} = 0$
 $\vec{L} = \vec{r} \times \vec{p}$

By the orthogonality of $\vec{A}$ to $\vec{L}$, $\vec{A}$ must be a fixed vector in the plane of the orbit
 ($\vec{L}$ is perpendicular to the orbital plane.)

1 relation $\rightarrow$ reduced to [the expected] 6 constants of motion

* BUT! * All of these constants are "global", that is they all provide information on the overall orbital properties

(none encode information about the initial position of the particle on the orbit - $r(t_0)$ or $\theta(t_0)$)

$\rightarrow$ One constant of motion must encode information about the initial position - brings us back to 7 constants

Need one more relation!

$\vec{A} = \text{constant} \Rightarrow$ the orbit is a conic section

$\rightarrow$ The conic equation as a function of $\vec{A}$ removes the extra constant and encodes information about the initial position

define:

$\theta \equiv$ the angle between $\vec{r}$ & $\vec{A}$

Where $\vec{A}$ is fixed/constant in both direction and magnitude

$$\vec{A} \cdot \vec{r} = \text{Arccos}(\theta) = \vec{r} \cdot (\vec{p} \times \vec{L}) - mkr$$

permutation of the terms of the triple dot-product:

$$\vec{r} \cdot (\vec{p} \times \vec{L}) = \vec{L} \cdot (\vec{r} \times \vec{p}) = l^2$$

$$\text{Arccos}(\theta) = \frac{l^2}{r} - mkr$$

$$\Rightarrow \frac{1}{r} = \frac{mk}{l^2} \left(1 + \frac{A}{mk} \cos(\theta) \right) \quad (1)$$

Confirmed: orbit is a conic section

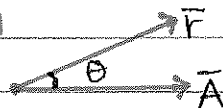
Where the earlier $r(\theta)$ found using EOM was:

$$\frac{1}{r} = \frac{mk}{l^2} \left(1 + \sqrt{1 + \frac{2El^2}{mk^2}} \cos(\theta - \theta') \right) \quad (2)$$

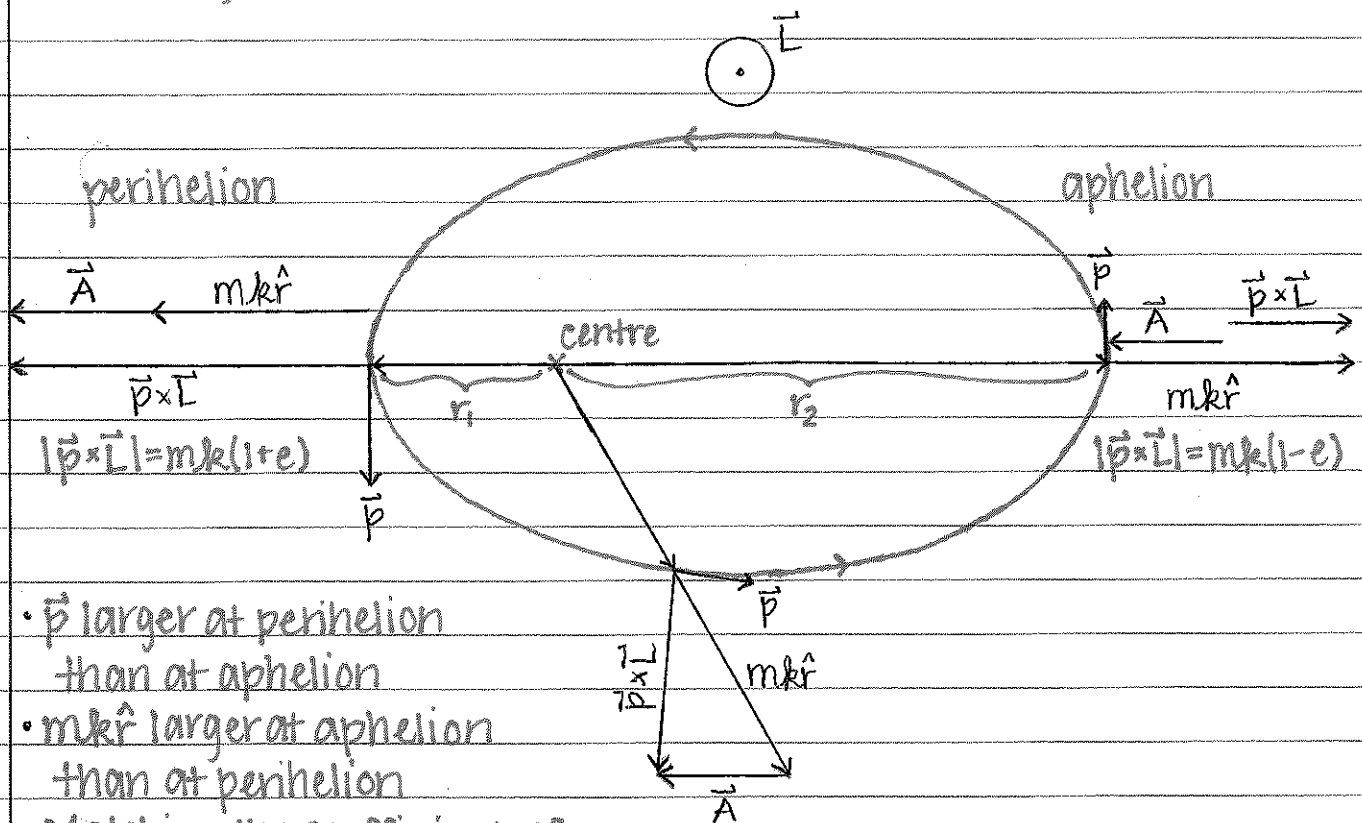
$\rightarrow$ Match (1) & (2) $\rightarrow$

$\vec{A}$ must point from centre to perihelion for this match to be true!

where θ here is with reference to the perihelion



Visualizing the vectors $\vec{p}$, $\vec{L}$, and $\vec{A}$ in a Keplerian orbit:



- $\vec{p}$ larger at perihelion than at aphelion
- $mk\hat{r}$ larger at aphelion than at perihelion
- Matching the coefficient of $\cos(\theta)$, $\vec{A}$ always points in the same direction with magnitude $A = mke$

→ expressing the eccentricity in terms of E and l →

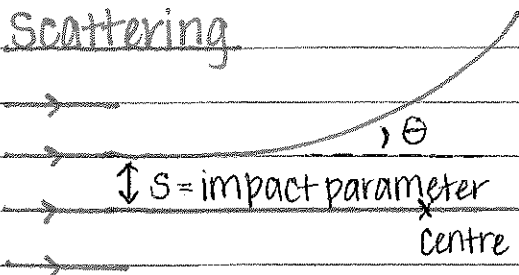
$$A^2 = m^2 k^2 + 2mEl^2$$

↳ of the seven constants we had before, only five are independent

We now have:

- 5 global constants
- 1 constant encoded with initial conditions (e.g. time @ perihelion, etc.)

4. Scattering



Repulsive force ($f \rightarrow 0$ as $r \rightarrow \infty$)

→ only focus on θ (ignore φ) due to azimuthal symmetry