

Problem 2.11 Kepler orbits

$$L = m r^2 \dot{\phi}$$

$$E = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\phi}^2) - k/r$$

$$\Rightarrow \frac{1}{2} m \dot{r}^2 = E + \frac{k}{r} - \frac{1}{2} \frac{L^2}{m r^2}$$

$$\frac{dr}{d\phi} = \frac{\dot{r}}{\dot{\phi}} \Rightarrow \frac{1}{2} \frac{L^2}{m r^4} \left(\frac{dr}{d\phi} \right)^2 = E + \frac{k}{r} - \frac{1}{2} \frac{L^2}{m r^2}$$

$$\frac{1}{r} \left(\frac{dr}{d\phi} \right)^2 = \frac{dr}{du} \left(\frac{du}{d\phi} \right) = -\frac{1}{u^2} \left(\frac{du}{d\phi} \right), \quad u \equiv \frac{1}{r}$$

$$\Rightarrow \frac{1}{2} \frac{L^2}{m} \left(\frac{du}{d\phi} \right)^2 = E + k u - \frac{1}{2} \frac{L^2}{m} u^2$$

$$\left(\frac{du}{d\phi} \right)^2 = \frac{2mE}{L^2} + \frac{2mk}{L^2} u - u^2$$

$$\int \frac{du}{\sqrt{\frac{2mE}{L^2} + \frac{2mk}{L^2} u - u^2}} = \int d\phi$$

agrees with Eq (3.50), Goldstein

$$\Rightarrow \left[\frac{1}{r} = \frac{mk}{L^2} \left(1 + \sqrt{1 + \frac{2EL^2}{mk^2}} \cos(\phi - \phi_1) \right) \right]^{Eq (3.55)}$$

2.24

L-R-L Vector

$$(a) \quad \vec{A} = \vec{p} \times \vec{L} - km\vec{r}/r, \text{ for } \vec{V} = -\frac{GMm}{r}$$

$$\dot{\vec{A}} = \dot{\vec{p}} \times \vec{L} - \frac{km\dot{\vec{v}}}{r} + \frac{km}{r^2} \vec{r} \dot{r}$$

we $\dot{\vec{p}} = -k\vec{r}/r^3$

$$\Rightarrow \dot{\vec{A}} = -\frac{k}{r^3} \underbrace{\vec{r} \times (\vec{r} \times \vec{p})}_{\vec{r} \cdot \vec{p} \vec{r} - r^2 \vec{p}} - \frac{k\dot{\vec{v}}}{r} + \frac{km}{r^3} \vec{r} \dot{r}$$

$\vec{r} \cdot \vec{p} \vec{r} - r^2 \vec{p} \leftarrow \text{cancel}$

$$= -k \frac{\vec{r} \cdot \vec{p} \vec{r}}{r^3} + \frac{km}{r^3} \vec{r} \dot{r}$$

$$= 0$$

using $\vec{r} \cdot \dot{\vec{v}} = r \dot{r}$

$$(b) \quad \dot{\vec{p}} = -k\vec{r}/r^3, \quad \vec{r} \times \dot{\vec{p}} = (\vec{r} \times \dot{\vec{p}}) = 0$$

$$\Rightarrow \dot{\vec{L}} \times \dot{\vec{p}} = (\dot{\vec{L}} \times \dot{\vec{p}}) = -\frac{k \dot{\vec{L}} \times \vec{r}}{r^3}$$

$$\text{RHS} = -k \frac{(\vec{r} \times \dot{\vec{p}}) \times \vec{r}}{r^3} = -\frac{k\dot{\vec{p}}}{r} + \frac{k \vec{r} \cdot \dot{\vec{p}} \vec{r}}{r^3}$$

$$= -k \frac{\dot{\vec{p}}}{r} + \frac{k \vec{r} \cdot \dot{\vec{p}} \vec{r}}{r^3} = -km \left(\frac{\dot{\vec{r}}}{r} \right)$$

$$\Rightarrow \frac{d\dot{\vec{A}}}{dt} = 0, \quad \dot{\vec{A}} = \dot{\vec{L}} \times \dot{\vec{p}} + km\dot{\vec{r}}/r$$

(c) Show that $\vec{A} \cdot \vec{L} = 0$ identically

$$\vec{A} = \vec{p} \times \vec{L} - km\vec{r}/r = \text{constant vector}$$

$$\vec{A} \cdot \vec{L} = -km\vec{r} \cdot \vec{L} / r = 0$$

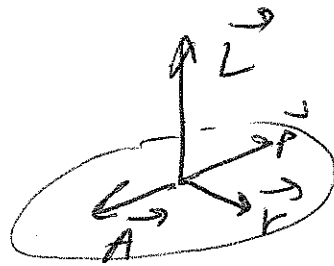
So this component yields $0=0$.

Show that A^2 is made up from L and \mathcal{E}

$$A^2 = |\vec{p} \times \vec{L}|^2 + (km)^2 - 2km\frac{\vec{r} \cdot \vec{p} \times \vec{L}}{r}$$

$$|\vec{p} \times \vec{L}|^2 = p^2 L^2$$

$$\vec{r} \cdot \vec{p} \times \vec{L} = L^2$$



$$\therefore A^2 = p^2 L^2 + k^2 m^2 - 2km \frac{L^2}{r}$$

$$\frac{A^2}{2mL^2} = \frac{p^2}{2m} + \frac{k^2 m}{2L^2} - \frac{k}{r}$$

$$\text{But } \mathcal{E} = \frac{p^2}{2m} - \frac{k}{r}$$

$$\Rightarrow \boxed{\frac{A^2}{2mL^2} = \mathcal{E} + \frac{\hbar^2 m}{2L^2}} \quad A = A(L, \mathcal{E})$$

(d) Take \vec{r} at $\phi=0$ to be parallel to \vec{A}

$$\Rightarrow \text{fix } \phi = 0$$

$$\begin{aligned} \Rightarrow \vec{A} \cdot \vec{r} &= A r \cos \phi, \quad A \geq 0 \\ &= \vec{r} \cdot (\vec{p} \times \vec{L}) - k m r \\ &= L^2 - k m r \end{aligned}$$

$$\Rightarrow \boxed{\frac{L^2}{r} = k m + A \cos \phi} \quad \begin{array}{l} A \geq 0 \\ r > 0 \end{array}$$

$$\Rightarrow r(\phi)$$

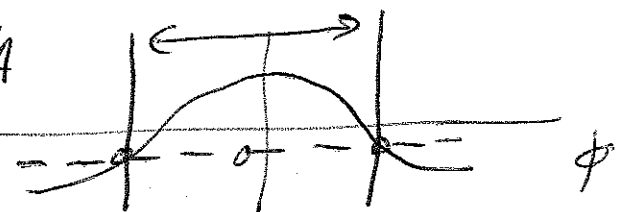
• $A = 0 \Rightarrow r = \text{const} \Rightarrow \text{circle}$

• $A < k m \Rightarrow \text{ellipse since RHS always } > 0 \text{ but wobbles}$

• $k m < A \Rightarrow \text{only certain } \phi \text{ allowed, i.e., } \cos \phi \geq -k m / A$

Note: as $\cos \phi \rightarrow -k m / A$

$\Rightarrow \text{RHS} \rightarrow 0 \Rightarrow r \rightarrow \infty$



• $A \rightarrow \infty \Rightarrow \phi_0 = \pm \pi/2$
 $\Rightarrow \text{hyperbola with asymptotes } \cos \phi_0 \rightarrow -k m / A$

2.34

EM energy density

$$m_i \vec{v}_i = q_i (\vec{E}_i + \vec{v}_i \times \vec{B}_i)$$

$$\vec{E}_i \rightarrow \vec{E}(\vec{r}_i, t), \text{ etc}$$

$$\vec{v}_i \cdot m_i \vec{v}_i = \frac{d}{dt} (T_i), \quad T = \sum_i T_i$$

$$\Rightarrow \frac{dT}{dt} = \sum_i q_i \vec{v}_i \cdot \vec{E}(\vec{r}_i, t)$$

$$\text{RHS} \rightarrow \int d^3r \vec{j} \cdot \vec{E}$$

$$\text{From ME, } \vec{\nabla} \times \vec{B} = \vec{j} + \partial_t \vec{E}$$

$$\Rightarrow \text{RHS} = \int d^3r \vec{E} \cdot \left[\underbrace{\vec{\nabla} \times \vec{B}}_{\textcircled{1}} - \underbrace{\partial_t \vec{E}}_{\textcircled{2}} \right]$$

$$\textcircled{1} = \int d^3r \left[-\vec{\nabla} \cdot (\vec{E} \times \vec{B}) + \vec{B} \cdot \vec{\nabla} \times \vec{E} \right]$$

$$= -\int d\vec{s} \cdot \vec{E} \times \vec{B} - \int d^3r \vec{B} \cdot \partial_t \vec{B}$$

$$\text{using } \vec{\nabla} \times \vec{E} = -\partial_t \vec{B}$$

$$= -\int d\vec{s} \cdot \vec{E} \times \vec{B} - \int d^3r \partial_t (B^2/2)$$

$$= -\int d\vec{s} \cdot \vec{E} \times \vec{B} - \frac{d}{dt} \int d^3r \frac{1}{2} B^2$$

$$\textcircled{2} = \int d^3r \vec{E} \cdot (-\partial_t \vec{E}) = -\frac{d}{dt} \int d^3r \frac{1}{2} E^2$$

$$\Rightarrow \frac{d}{dt} \left[T + \int d^3r \frac{1}{2} (E^2 + B^2) \right] = - \int d\vec{s} \cdot \vec{E} \times \vec{B}$$

For closed box,

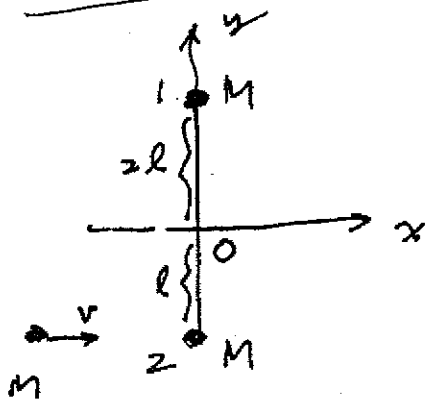
$$T + \int d^3r \frac{1}{2} (E^2 + B^2) = \text{const}$$

assuming $\int_{\text{box}} d\vec{s} \cdot \vec{E} \times \vec{B} = 0$

"Poynting
Flux"



2.1Q



$$a) \quad x_{cm} = (vt + 0 + 0)M / 3M = \frac{vt}{3}$$

$$y_{cm} = \frac{2l - l - l}{3M} = 0$$

x_{cm}, y_{cm} is the same before & after the collision

$$b) \quad \vec{L} = \vec{r} \times \vec{p} = -l \hat{j} \times m \vec{v} \quad \dots \text{before}$$

$$= mlv \hat{k}$$

same for after collision.

c) In CMS, we have pure rotation about CM.

$$L = I\omega, \quad I = M(2l)^2 + 2m \cdot l^2$$

$$= 6Ml^2$$

$$L = mlv$$

$$\therefore \omega = \frac{v}{6l}$$

d) In lab frame, the motion is the CM with pure rotation about CM.

$$\therefore \begin{cases} x_1 = \frac{vt}{3} - 2l \sin \omega t, & y_1 = 2l \cos(\omega t) \\ x_2 = \frac{vt}{3} + l \sin \omega t, & y_2 = -l \cos \omega t \end{cases}$$

($\omega = v/6l$)