

Solns P54

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Phys 410/F16

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5.2H

See notes posted under "Misc"

5.42

$$Q \equiv \omega_0 / 2\beta$$

$e^{-\beta t}$  is damping

$\omega_0$  is angular freq of osc

o Swings for many hours. let decay time = 8hr  
 $\Rightarrow \frac{1}{\beta} \approx 8 \text{ hrs} = 8 \times 60 \times 60 \text{ secs}$

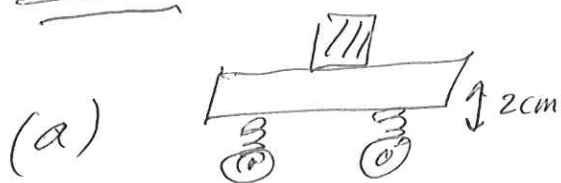
$$l = 30 \text{ m}, \quad \omega_0 = \sqrt{\frac{g}{l}} \approx \sqrt{\frac{10}{30}} = \sqrt{\frac{1}{3}}$$

$$Q = \sqrt{\frac{1}{3}} \frac{1}{2} \times 8 \times 60 \times 60$$

$$Q \approx 8300$$

5.43

( $2\pi$ 's may not be in right places)

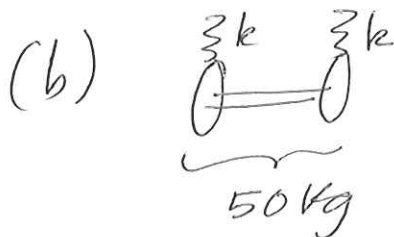


$$4Mg = 4k \Delta x$$

$$Mg = k \Delta x \Rightarrow k$$

$$M = 80$$

$$k = 40,000$$



$$M\omega^2 \Delta x = 2k \Delta x$$

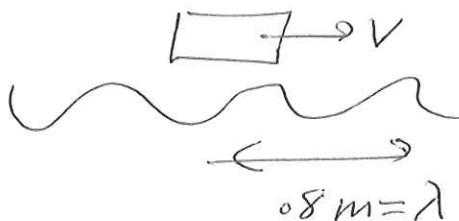
$$\Rightarrow \omega^2 = \frac{2k}{M}$$

$$\omega = 2\pi f \Rightarrow f^2 = \frac{2k}{M_{50}} \frac{1}{(2\pi)^2}$$

$$M = 50$$

$$\Rightarrow f \approx 6.4/s$$

(c)



$$\frac{v 2\pi}{\lambda} = 2\pi f$$

$$\Rightarrow v = \lambda f \Rightarrow v$$

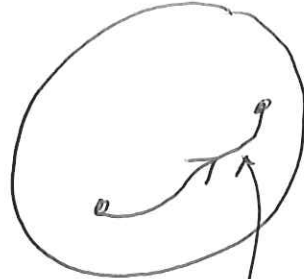
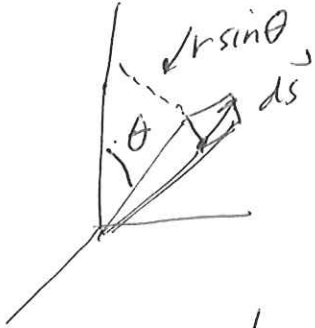
$$v = \lambda f = \frac{\lambda}{2\pi} \left( \frac{2k}{M_{50}} \right)^{1/2} = \frac{\lambda}{2\pi} \left( \frac{2}{M_{50}} \right)^{1/2} \left( \frac{M_{80} g}{0.02} \right)^{1/2}$$

$$\Rightarrow v = (0.8)(6.4) \text{ m/s}$$

$$v \approx \frac{5 \text{ m}}{\text{s}} \sim 10 \text{ mph/h}$$

6.1 Shortest path between 2 points  
on a sphere

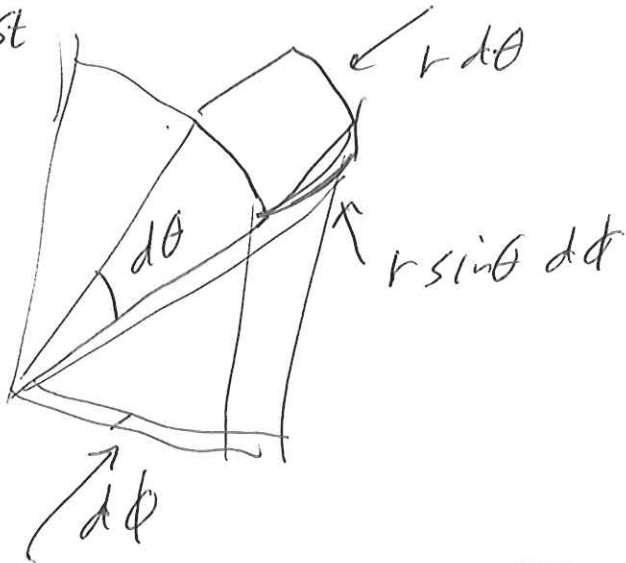
Use spherical coordinates



$\phi(\theta)$   
 $r = \text{const}$

$$ds^2 \Big|_{\text{on surface}} \Big|_{r = \text{const}} = (r \sin \theta d\phi)^2 + (r d\theta)^2$$

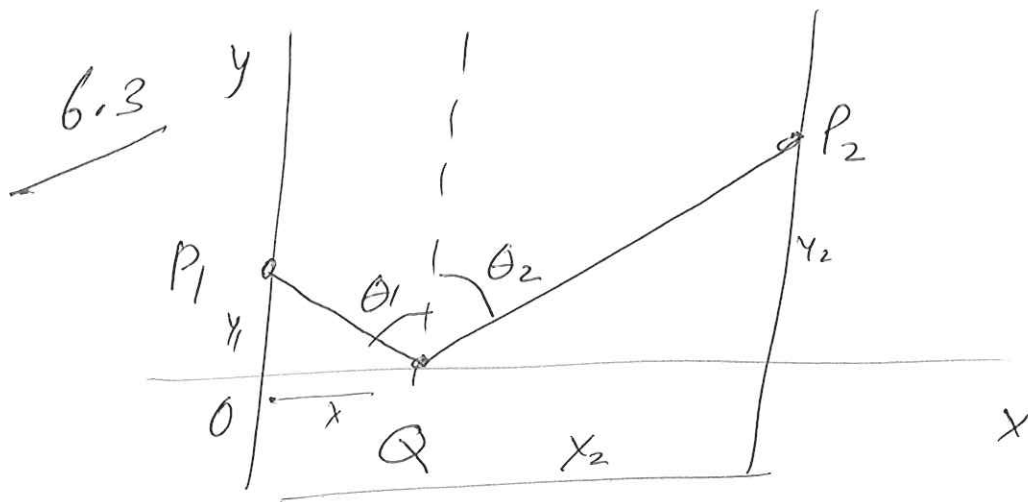
$$ds^2 = d\theta^2 r^2 \sqrt{1 + \sin^2 \theta \phi'^2}$$



$$r = R$$

$$\Rightarrow \frac{L}{R} = \int_{\theta_1, \phi_1}^{\theta_2, \phi_2} d\theta \sqrt{1 + \sin^2 \theta \phi'(\theta)^2}$$

Note  $L = L(\phi', \theta)$   $L \neq L(\phi)$



$$P_1 = (0, y_1, 0)$$

$y_1$  given

$$P_2 = (x_2, y_2, 0)$$

$x_2, y_2$  given

$$Q = (x, 0, z)$$

$x, z$  unknown

• For both rays, speed = const.

$\Rightarrow$  straight paths,

$$\Rightarrow \text{travel time} = \frac{\text{length of path}}{c}$$

$$L_1^2 = x^2 + y_1^2 + z^2$$

$$L_2^2 = (x_2 - x)^2 + y_2^2 + z^2$$

$$T = \frac{L_1}{c} + \frac{L_2}{c}$$

Note  $T = T(x, z)$

Need  $\frac{\partial T}{\partial x} = 0, \frac{\partial T}{\partial z} = 0$

$$\frac{\partial T}{\partial z} = \frac{z}{L_1 c} + \frac{z}{L_2 c} = 0$$

$$\Rightarrow \boxed{z = 0}$$

$$\frac{\partial T}{\partial x} = \frac{x}{L_1 c} - \frac{(x_2 - x)}{L_2 c} = 0$$

For  $z = 0$

$$\frac{x}{L_1} = \sin \theta_1, \quad \frac{x_2 - x}{L_2} = \sin \theta_2$$

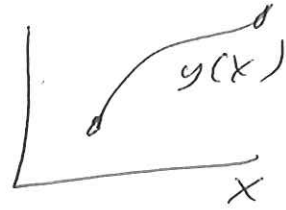
$$\Rightarrow \boxed{\begin{array}{l} \sin \theta_1 = \sin \theta_2 \\ \theta_1 = \theta_2 \end{array}} \quad \boxed{d\theta_2 - \theta_2 = 0}$$

Snell's law

6.9

$$S = \int_{0,0}^{1,1} (y'^2 + yy' + y^2) dx$$

Make  $S$  stationary  
for some  $y(x)$ .



$$\frac{\delta S}{\delta y} = 0 \Rightarrow \frac{\partial f}{\partial y} = \frac{d}{dx} \left( \frac{\partial f}{\partial y'} \right)$$

$$\frac{\partial f}{\partial y} = y' + 2y, \quad \frac{\partial f}{\partial y'} = 2y' + y$$

$$\Rightarrow 2y'' + y' = y' + 2y$$

$$\Rightarrow y'' = y \Rightarrow y \sim \begin{cases} \sinh x \\ \cosh x \end{cases}$$

$$\Rightarrow \boxed{y = \frac{\sinh(x)}{\sinh(1)}}$$

$$\begin{aligned} y(0) &= 0 \\ y(1) &= 1 \end{aligned}$$



6.10

$$S = \int_1^2 dx f(y', y, x)$$

Suppose  $f = f(y', x)$ ,  
i.e. indep of  $y$

Then  $\frac{\partial f}{\partial y} = \frac{d}{dx} \left( \frac{\partial f}{\partial y'} \right)$

$$\Rightarrow \frac{d}{dx} \left( \frac{\partial f}{\partial y'} \right) = 0$$

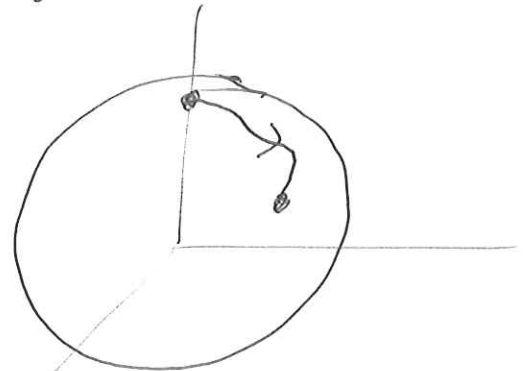
$$\Rightarrow \boxed{\frac{\partial f}{\partial y'} = \text{const}} + \text{apply B.C.'s}$$

$\Rightarrow$  one integral done easily

6.16 The sphere is completely symmetric,  
 i.e., we can pick  $\theta_1 = 0$  and  
 $(\theta_2, \phi_2)$  as the end pt.

i.e. we let the  $z$ -axis cutting sphere,  
 the North Pole, as starting point.  
 No generality is lost.

Now we go from  
 North pole to  $(\theta_2, \phi_2)$ .



Might as well pick  $\phi_2 = 0$ .

Also,  $\theta = 0$  is a point which could have  
 any  $\phi$ , so pick  $\phi_1 = 0$ .

so Minimize  $\frac{L}{R} = \int_0^{\theta_2} d\theta \sqrt{1 + \sin^2 \theta \phi'(\theta)^2}$

$$\frac{\partial L}{\partial \phi} = 0 \quad \frac{\partial L}{\partial \phi'} = \frac{\phi' \sin^2 \theta}{\sqrt{1 + \sin^2 \theta \phi'^2}}$$

so  $\frac{\partial L}{\partial \phi} = \frac{d}{d\theta} \frac{\partial L}{\partial \phi'}$  is  $E-L \Rightarrow \frac{\partial L}{\partial \phi'} = \text{const}$

$$\Rightarrow \frac{\phi' \sin^2 \theta}{\sqrt{1 + \sin^2 \theta \phi'^2}} = \text{const}$$

This must be true for all  $\phi(\theta)$

But also true at  $\theta = 0 \Rightarrow \left. \frac{\phi' \sin^2 \theta}{\sqrt{1 + \sin^2 \theta \phi'^2}} \right|_{\theta=0} = \text{const}$

$$\Rightarrow \text{const} = 0$$

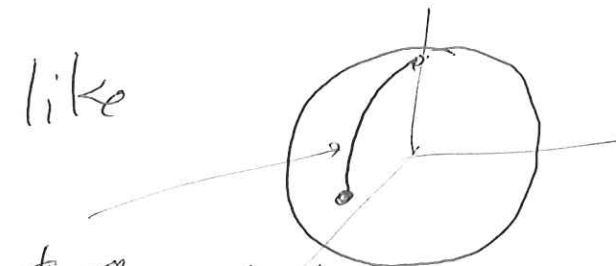
$$\Rightarrow \frac{\phi' \sin^2 \theta}{\sqrt{1 + \sin^2 \theta \phi'^2}} = 0 \quad \forall \theta$$

$$\Rightarrow \phi' = 0 \quad \forall \theta$$

$$\Rightarrow \phi = \text{const}$$

$$\phi(0) = 0 \Rightarrow \boxed{\phi = 0} \text{ from } \theta = 0 \text{ to } \theta_2$$

This looks like



$\phi = 0$  coordinate

$\theta = [0, \theta_2]$

It's along a longitude, i.e., a great circle.  $\leftarrow$  Path of shortest distance