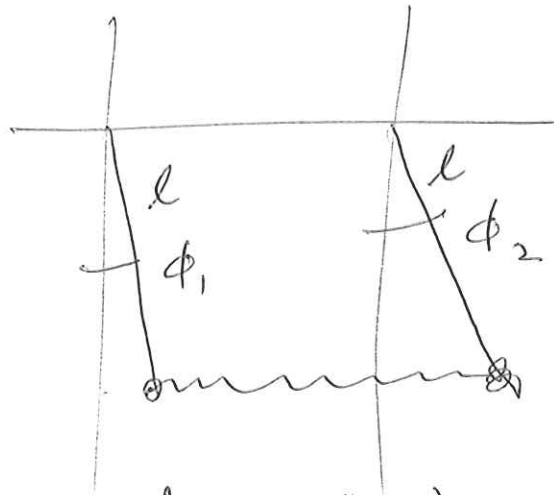


11.14

• $m_1 = m_2 = m$



$$T = \frac{1}{2} m l^2 (\dot{\phi}_1^2 + \dot{\phi}_2^2)$$

$$U_s = \frac{1}{2} k l^2 (\phi_2 - \phi_1)^2$$

$$U_g = \frac{1}{2} m g l (\phi_1^2 + \phi_2^2)$$

(A)

• let $m=1, l=1, k=1$

⇒ length normalized to l

⇒ time normalized to $(m/k)^{1/2}$

⇒ Energy normalized to $k l^2$

$$\Rightarrow T = \frac{1}{2} (\dot{\phi}_1^2 + \dot{\phi}_2^2)$$

$$U_s = \frac{1}{2} (\phi_2 - \phi_1)^2$$

$$U_g = \frac{1}{2} g (\phi_1^2 + \phi_2^2)$$

(B)

• Note Cannot set $g=1$.

(a) g has same dimensions as $l k/m$

(b) cannot set more than 3 things to unity.

$$\bullet \mathcal{L} = T - U_s - U_g$$

$$\frac{\partial \mathcal{L}}{\partial \dot{\phi}_1} = \dot{\phi}_1; \quad \frac{\partial \mathcal{L}}{\partial \phi_1} = (\phi_2 - \phi_1) - g\phi_1$$

$$\Rightarrow \begin{cases} \ddot{\phi}_1 = -g\phi_1 + (\phi_2 - \phi_1) \\ \ddot{\phi}_2 = -g\phi_2 - (\phi_2 - \phi_1) \end{cases}$$

System
Depends
only on
one parameter

g where

$$g \rightarrow \frac{mgl}{kl^2} = \frac{mg}{kl}$$

$$\Rightarrow \begin{cases} (g+1-\omega^2)\phi_1 = \phi_2 \\ (g+1-\omega^2)\phi_2 = \phi_1 \end{cases}$$

$$\bullet |\text{Det}| = 0 \Rightarrow (g+1-\omega^2)^2 = 1$$

$$g+1-\omega^2 = \pm 1$$

$$\textcircled{\#1} \quad \omega^2 = g \Rightarrow \phi_1 = \phi_2 \Rightarrow \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\textcircled{\#2} \quad \omega^2 = g+2 \Rightarrow \phi_1 = -\phi_2 \Rightarrow \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

• More systematic normalization

• Start from (A)

$$\text{let } \hat{U}_s = \frac{U_s}{kl^2}, \quad \hat{U}_g = \frac{U_g}{kl^2}, \quad \hat{T} = \frac{T}{kl^2}$$

$$\Rightarrow \hat{T} = \frac{1}{2} \frac{m}{k} (\dot{\phi}_1^2 + \dot{\phi}_2^2)$$

$$\hat{U}_s = \frac{1}{2} (\phi_2 - \phi_1)^2$$

$$\hat{U}_g = \frac{1}{2} \frac{mg}{kl} (\phi_1^2 + \phi_2^2)$$

• let $\hat{t} = t \left(\frac{k}{m} \right)^{1/2}$

$$\Rightarrow \frac{d\phi_1}{dt} = \frac{d\hat{t}}{dt} \frac{d\phi_1}{d\hat{t}} = \left(\frac{k}{m} \right)^{1/2} \frac{d\phi_1}{d\hat{t}}$$

$$\Rightarrow \frac{1}{2} \frac{m}{k} \left(\frac{d\phi_1}{dt} \right)^2 = \frac{1}{2} \left(\frac{d\phi_1}{d\hat{t}} \right)^2$$

$$\Rightarrow \hat{T} = \frac{1}{2} \left(\hat{\dot{\phi}}_1^2 + \hat{\dot{\phi}}_2^2 \right)$$

Drop all λ 's

\Rightarrow

$$T = \frac{1}{2} (\dot{\phi}_1^2 + \dot{\phi}_2^2)$$

$$U_s = \frac{1}{2} (\phi_2 - \phi_1)^2$$

$$U_g = \frac{1}{2} \left(\frac{mg}{kl} \right) (\phi_1^2 + \phi_2^2)$$

— exactly as our starting point (B)

setting $k=1, l=1, m=1$;

with single param $g \rightarrow \frac{mg}{kl}$