# **HOMEWORK#9 SOLUTION**

# [Chap28]

# \*1

**Determine the Concept** We know that the magnetic flux (in this case the magnetic field because the area of the conducting loop is constant and its orientation is fixed) must be changing so the only issues are whether the field is increasing or decreasing and in which direction. Because the direction of the magnetic field associated with the clockwise current is into the page, the changing field that is responsible for it must be either increasing out of the page (not included in the list of possible answers) or a decreasing field directed into the page. (d) is correct.

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(*a*) False. The induced emf in a circuit is proportional to *the rate of change of* the magnetic flux through the circuit.

(b) True.

(c) True.

(*d*) False. The inductance of a solenoid is determined by its length, cross-sectional area, number of turns per unit length, and the permeability of the matter in its core.

## \*24 ••

**Picture the Problem** We can use the hint to set up the element of area *dA* and express the flux  $d\phi_m$  through it and then carry out the details of the integration to express  $\phi_m$ .

( <i>a</i> ) Express the flux through the strip of area <i>dA</i> :	$d\phi_{\rm m} = BdA$ where $dA = bdx$ .
Express $B$ at a distance $x$ from a long, straight wire:	$B = \frac{\mu_0}{4\pi} \frac{2I}{x} = \frac{\mu_0}{2\pi} \frac{I}{x}$
Substitute to obtain:	$d\phi_{\rm m} = \frac{\mu_0}{2\pi} \frac{I}{x} b dx = \frac{\mu_0 I b}{2\pi} \frac{dx}{x}$
Integrate from $x = d$ to $x = d + a$ :	$\phi_{\rm m} = \frac{\mu_0 I b}{2\pi} \int_d^{d+a} \frac{dx}{x} = \boxed{\frac{\mu_0 I b}{2\pi} \ln \frac{d+a}{d}}$

(b) Substitute numerical values and evaluate  $\phi_{\rm m}$ :

$$\phi_{\rm m} = \frac{(4\pi \times 10^{-7} \text{ N/A}^2)(20 \text{ A})(0.1 \text{ m})}{2\pi} \ln\left(\frac{7 \text{ cm}}{2 \text{ cm}}\right) = 5.01 \times 10^{-7} \text{ Wb}$$

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**Picture the Problem** We can find the induced emf by applying Faraday's law to the loop. The application of Ohm's law will yield the induced current in the loop and we can find the rate of joule heating using  $P = I^2 R$ .

(*a*) Apply Faraday's law to express the induced emf in the loop in terms of the rate of change of the magnetic field:

Substitute numerical values and  $|\mathcal{E}| = \pi (0.05 \,\mathrm{m})$ 

evaluate  $|\mathcal{E}|$ :

(*b*) Using Ohm's law, relate the induced current to the induced voltage and the resistance of the loop and evaluate *I*:

(c) Express the rate at which power is dissipated in a conductor in terms of the induced current and the resistance of the loop and evaluate *P*:

$$\left|\mathcal{E}\right| = \frac{d\phi_{\rm m}}{dt} = \frac{d}{dt} \left(AB\right) = A\frac{dB}{dt} = \pi R^2 \frac{dB}{dt}$$

$$|\mathcal{E}| = \pi (0.05 \,\mathrm{m})^2 (40 \,\mathrm{mT/s}) = 0.314 \,\mathrm{mV}$$

$$I = \frac{\mathcal{E}}{R} = \frac{0.314 \,\mathrm{mV}}{0.4\Omega} = \boxed{0.785 \,\mathrm{mA}}$$

$$P = I^{2}R = (0.785 \text{ mA})^{2}(0.4 \Omega)$$
$$= 0.247 \,\mu\text{W}$$

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**Picture the Problem** Because the speed of the rod is constant, an external force must act on the rod to counter the magnetic force acting on the induced current. We can use the motional-emf equation  $\mathcal{E} = vB\ell$  to evaluate the induced emf, Ohm's law to find the current in the circuit, Newton's 2<sup>nd</sup> law to find the force needed to move the rod with constant velocity, and P = Fv to find the power input by the force.

(*a*) Relate the induced emf in the circuit to the speed of the rod, the magnetic field, and the length of the rod:

$$\mathcal{E} = vB\ell = (10 \text{ m/s})(0.8 \text{ T})(0.2 \text{ m})$$
  
= 1.60 V

(*b*) Using Ohm's law, relate the current in the circuit to the induced emf and the resistance of the circuit:

(c) Because the rod is moving with constant velocity, the net force acting on it must be zero. Apply Newton's  $2^{nd}$  law to relate F to the magnetic force  $F_m$ :

(*d*) Express the power input by the force in terms of the force and the velocity of the rod:

(*e*) The rate of Joule heat production is given by:

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**Picture the Problem** Let *m* be the mass of the rod and *F* be the net force acting on it due to the current in it. We can obtain the equation of motion of the rod by applying Newton's  $2^{nd}$  law to relate its acceleration to *B*, *I*, and  $\ell$ . The net emf that drives *I* in this circuit is the emf of the battery minus the emf induced in the rod as a result of its motion.

(a) Letting the direction of motion  
of the rod be the positive x  
direction, apply 
$$\sum F = ma$$
 to where

direction, apply  $\sum F_x = ma_x$  to the rod:

Substitute to obtain:

$$\frac{dv}{dt} = \boxed{\frac{B\ell}{mR} (\mathcal{E} - B\ell v)}$$

(b) Express the condition on dv/dt when the rod has achieved its terminal speed:

$$\frac{B\ell}{mR} \left( \mathcal{E} - B\ell v_{\rm t} \right) = 0$$

 $I = \frac{\mathcal{E} - B\ell v}{R}$ 

$$I = \frac{\mathcal{E}}{R} = \frac{1.6 \,\mathrm{V}}{2 \,\Omega} = \boxed{0.800 \,\mathrm{A}}$$

Note that, because the rod is moving to the right, the flux in the region defined by the rod, the rails, and the resistor is increasing. Hence, in accord with Lenz's law, the current must be counterclockwise if its magnetic field is to counter this increase in flux.

$$\sum F_x = F - F_m = 0$$
  
and  
$$F = F_m = BI\ell$$
  
$$= (0.8 \text{ T})(0.8 \text{ A})(0.2 \text{ m}) = \boxed{0.128 \text{ N}}$$

$$P = Fv = (0.128 \text{ N})(10 \text{ m/s}) = 1.28 \text{ W}$$

$$P = I^2 R = (0.8 \text{ A})^2 (2 \Omega) = 1.28 \text{ W}$$

(1)

(2)

Solve for  $v_t$  to obtain:

$$v_{\rm t} = \boxed{\frac{\mathcal{E}}{B\ell}}$$

(c) Substitute  $v_t$  for v in equation (2) to obtain:

$$I = \frac{\mathcal{E} - B\ell}{R} \frac{\mathcal{E}}{B\ell} = \boxed{0}$$

## 46 ••

**Picture the Problem** The diagram shows the square loop being pulled from the magnetic field  $\vec{B}$  by the constant force

 $\vec{F}$ . The time required to pull the loop out of the magnetic field depends on the terminal speed of the loop. We can apply Newton's 2<sup>nd</sup> law and use the expressions for the magnetic force on a moving wire in a magnetic field to obtain the equation of motion for the loop and, from this equation, an expression for the terminal speed of the loop.

Apply  $\sum \vec{F} = m\vec{a}$  to the square loop to obtain:

The magnetic force is given by:

$$F - F_{\rm m} = m \frac{dv}{dt} \tag{1}$$

$$F_{\rm m} = I\ell B = \frac{\mathcal{E}\,\ell\,B}{R}$$

where *R* is the resistance of the loop.

Substitute for *F*m in equation (1) to obtain:

The induced emf  $\varepsilon$  is related to the speed of the loop:

Substitute for in equation (2) to obtain the equation of motion of the loop:

When the loop reaches its terminal speed, dv/dt = 0 and:

$$F - \frac{\mathcal{E}\,\ell\,B}{R} = m\frac{dv}{dt} \tag{2}$$

 $\mathcal{E} = vB\ell$ 

$$F - \frac{\ell^2 B^2}{R} v = m \frac{dv}{dt}$$

$$F - \frac{\ell^2 B^2}{R} v_t = 0 \Longrightarrow v_t = \frac{R}{\ell^2 B^2} F$$

This result tells us that doubling *F* doubles the terminal speed  $v_t$ . Hence, doubling *F* will halve the time required to pull the loop from the magnetic field and (c) is correct.

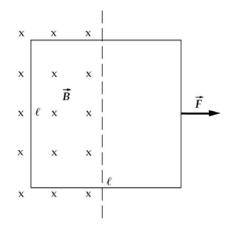
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$$F_{\rm m} = I\ell B = \frac{\mathcal{E}\,\ell\,B}{R}$$

where *R* is the resistance of the loop.

Substitute for  $F_{\rm m}$  in equation (1) to obtain:

The induced emf  $\varepsilon$  is related to the speed of the loop:

Substitute for in equation (2) to obtain the equation of motion of the loop:

When the loop reaches its terminal speed, dv/dt = 0 and:

$$F - \frac{\mathcal{E}\,\ell\,B}{R} = m\frac{dv}{dt} \tag{2}$$

$$\mathcal{E} = vB\ell$$

$$F - \frac{\ell^2 B^2}{R} v = m \frac{dv}{dt}$$

$$F - \frac{\ell^2 B^2}{R} v_t = 0 \Longrightarrow v_t = \frac{R}{\ell^2 B^2} F$$

This result tells us that halving *R* halves the terminal speed  $v_t$ . Hence, halving *R* will double the time required to pull the loop from the magnetic field and (*b*) is correct.

## [Honors section] ...

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**Picture the Problem** Consider an element of area dA = Ldr where  $r \le R$ . We can use its definition to express  $d\phi_m$  through this area in terms of B and Ampere's law to express B as a function of I. The fact that the current is uniformly distributed over the crosssectional area of the conductor allows us to set up a proportion from which we can obtain I as a function of r. With these substitutions in place we can integrate  $d\phi_m$  to obtain  $\phi_m/L$ .

Express the flux  $d\phi_{\rm m}$  through an area Ldr:

$$d\phi_{\rm m} = BdA = BLdr \tag{1}$$

Apply Ampere's law to the current contained inside a cylindrical region of radius r < R:

Using the fact that the current *I* is uniformly distributed over the crosssectional area of the conductor, express its variation with distance r from the center of the conductor:

Substitute and simplify to obtain:

Substitute in equation (1):

Integrate  $d\phi_{\rm m}$  from r = 0 to r = R to obtain:

Divide both sides of this equation by L to express the magnetic flux per unit length:

and  

$$B = \frac{\mu_0 I_C}{2\pi r}$$

$$I(r) = \pi r^2$$

 $\oint_C \vec{B} \cdot d\vec{\ell} = 2\pi r B = \mu_0 I_C$ 

or  

$$I(r) = I_{c} = I \frac{r^{2}}{R^{2}}$$

$$B = \frac{\mu_0 I}{2\pi r} \frac{r^2}{R^2} = \frac{\mu_0 I}{2\pi R^2} r$$

$$d\phi_{\rm m} = \frac{\mu_0 LI}{2\pi R^2} r dr$$

$$\phi_{\rm m} = \frac{\mu_0 LI}{2\pi R^2} \int_0^R r dr = \frac{\mu_0 LI}{4\pi}$$

$$\frac{\phi_{\rm m}}{L} = \boxed{\frac{\mu_0 I}{4\pi}}$$