

Shock Waves

We have shown earlier that disturbances in plasmas tend to steepen. In the presence of dissipation (viscosity etc) the steepening will halt to form a propagating discontinuity in which ~~some~~ ~~is localized~~ ~~parameters~~ jump across the discontinuity. Dissipative processes are highly localized

⇒ called a shock

⇒ jump in parameters can be obtained by integrating across the shock

⇒ Rankine-Hugoniot conditions

⇒ broadly important

~~Basic MHD equations~~

~~$$\nabla \times \underline{B} = \frac{4\pi}{c} \underline{J} + \frac{1}{c} \frac{\partial \underline{E}}{\partial t}$$~~

Basic MHD Eqs

$$\frac{1}{c} \frac{\partial \underline{B}}{\partial t} + \nabla \times \underline{E} = 0$$

$$\nabla \times \underline{B} = \frac{4\pi}{c} \underline{J} + \frac{1}{c} \frac{\partial \underline{E}}{\partial t}$$

$$\nabla \cdot \underline{B} = 0$$

① ~~*~~ $\frac{\partial n}{\partial t} + \nabla \cdot \underline{n \underline{v}} = 0$ continuity

$m n \frac{d \underline{v}}{dt} = - \nabla P + \frac{1}{c} \underline{J} \times \underline{B}$

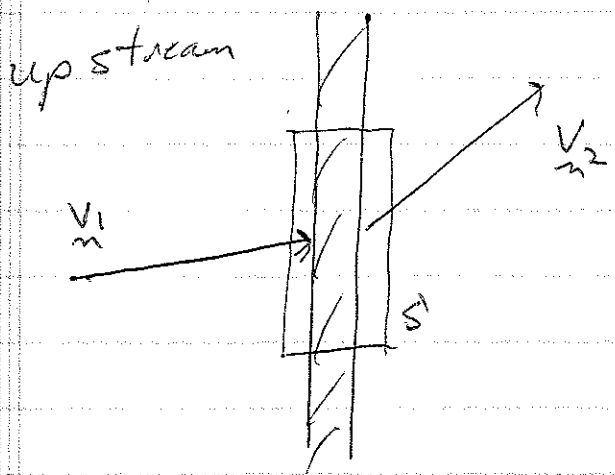
$\underline{E} + \frac{\underline{v} \times \underline{B}}{c} = 0$ $\frac{\partial P}{\partial t} + \underline{v} \cdot \nabla P + \nabla \cdot \underline{P \underline{v}} = 0$

$\frac{d}{dt} \left(\frac{P}{n \Gamma} \right) = 0$ $\frac{d}{dt} = \frac{\partial}{\partial t} + \underline{v} \cdot \nabla$

⇒ write equations in conservation form

$\frac{\partial \mathcal{Q}}{\partial t} + \nabla \cdot \underline{F} = 0$

~~in steady state~~



⇒ steady state

$\int_V \nabla \cdot \underline{F} = 0$

jump condition
 $[F_n] = 0$
 $(F_2 - F_1) \cdot \underline{n} = 0$

$\int_S dA \cdot \underline{F} = 0$
 $\int_S dA \underline{F} \cdot \underline{n} = 0$

Momentum

$$n \frac{d\vec{v}}{dt} = n \frac{\partial \vec{v}}{\partial t} + n \vec{v} \cdot \nabla \vec{v}$$

$$= \frac{\partial (n\vec{v})}{\partial t} + \nabla \cdot (n\vec{v}\vec{v})$$

⇒ using continuity

$$\frac{1}{c} \vec{J} \times \vec{B} = \frac{1}{4\pi} [(\nabla \times \vec{B}) \times \vec{B}]$$

$$= -\frac{1}{4\pi} [\nabla \left(\frac{B^2}{2} \right) - \vec{B} \cdot \nabla \vec{B}]$$

② $\frac{\partial}{\partial t} (m n \vec{v}) + \nabla \cdot [m n \vec{v} \vec{v} + \left(P + \frac{B^2}{8\pi} \right) \frac{\vec{I}}{c} + \frac{1}{4\pi} \vec{B} \vec{B}]$

Energy

$$n \vec{v} \cdot \frac{d}{dt} \vec{v} = n \left(\frac{\partial}{\partial t} \frac{v^2}{2} + \vec{v} \cdot \nabla \frac{v^2}{2} \right)$$

$$+ \frac{v^2}{2} \left(\frac{\partial n}{\partial t} + \nabla \cdot n \vec{v} \right)$$

$$= \frac{\partial}{\partial t} \frac{n v^2}{2} + \nabla \cdot \left(\frac{n v^2}{2} \vec{v} \right)$$

$$\frac{\partial P}{\partial t} + (1-\Gamma) \vec{v} \cdot \nabla P + \Gamma \nabla \cdot P \vec{v} = 0$$

$$\underline{v} \cdot \nabla P = \frac{1}{\Gamma-1} \left(\frac{dP}{dt} + \Gamma \nabla \cdot P \underline{v} \right)$$

$$\frac{1}{c} \underline{v} \cdot (\underline{v} \times \underline{B}) = -\frac{1}{c} (\underline{v} \times \underline{B}) \cdot \underline{J}$$

$$= \underline{E} \cdot \frac{c}{4\pi} \nabla \times \underline{B}$$

$$= -\frac{c}{4\pi} \left[\nabla \cdot (\underline{E} \times \underline{B}) - \underline{B} \cdot \nabla \times \underline{E} \right]$$

$$= -\frac{c}{4\pi} \nabla \cdot (\underline{E} \times \underline{B}) \rightarrow -\frac{1}{8\pi} \frac{\partial}{\partial t} (\underline{B}^2)$$

$$\frac{d}{dt} \left(\frac{1}{2} m n v^2 + \frac{P}{\Gamma-1} + \frac{B^2}{8\pi} \right)$$

$$+ \nabla \cdot \left[\frac{1}{2} m n v^2 \underline{v} + \frac{\Gamma}{\Gamma-1} P \underline{v} + c \frac{\underline{E} \times \underline{B}}{4\pi} \right] = 0$$

Jump Conditions

$$\frac{1}{4\pi} \underline{B} \times (\underline{v} \times \underline{B})$$

$$\frac{1}{4\pi} (\underline{B}^2 \underline{v} - \underline{v} \cdot \underline{v} \underline{B})$$

continuity : from ①

$$\textcircled{4} \quad [n v_n] = 0$$

energy : from ③

$$\textcircled{5} \quad \left[\frac{1}{2} m n v^2 v_n + \frac{\Gamma}{\Gamma-1} P v_n + \frac{1}{4\pi} B^2 v_n - \frac{1}{4\pi} \underline{B} \cdot \underline{v} \underline{B}_n \right] = 0$$

momentum: from (2) normal

$$(6) \quad [m n v_n^2 + p + \frac{B_t^2}{8\pi}] = 0 \quad B_t = B \text{ tangent to plane of shock}$$

$$[B_n] \Rightarrow = -\hat{n} \times (\hat{n} \times \underline{B})$$

from (2) tangent

$$(7) \quad [m n v_n v_{nt} - \frac{1}{4\pi} B_n B_{nt}] = 0$$

Electromagnetic conditions:

from $\nabla \cdot \underline{B} = 0$

$$(8) \quad [B_n] = 0$$

tangential \underline{E} : $\underline{E} = -\frac{1}{c} \underline{v} \times \underline{B}$

$$[\hat{n} \times (\underline{v} \times \underline{B})] = 0 \quad B_n v_n - v_n B_n = 0$$

$$(9) \quad \Rightarrow [v_n B_{nt} - v_{nt} B_n] = 0$$

\Rightarrow total of 8 conditions

Classes of solutions:

(a) contact or tangential discontinuity

no mass flux through surface

$$v_{n1} = 0, v_{n2} = 0, \underline{B_n = 0}$$

(b) non-compressible shock

no density jump $\Rightarrow n_1 = n_2$

non-zero mass flux (in shock frame)

$$v_{in} = v_{2n}$$

(c) compressible shock

\Rightarrow density jump $n_1 \neq n_2$

$$v_{in}, v_{2n} \neq 0$$

From (4), (5), (9)

$$[v_{nt}] = \frac{1}{4\pi} \frac{B_n}{mnv_n} [B_t] \Rightarrow$$

$$\frac{1}{B_n} [v_n B_{nt}] = [v_t]$$

$$[v_n B_{nt}] = \frac{B_n^2}{4\pi mn v_n} [B_t]$$

~~From~~

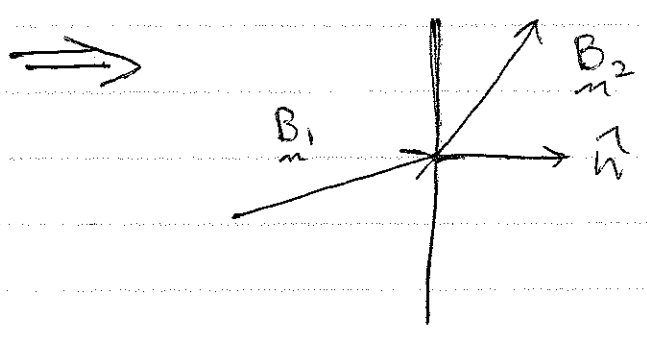
$$[\underline{B}_t] = \alpha [V_n \underline{B}_t] \quad \alpha = \frac{4\pi \mu n V_n}{B_n^2}$$

$$\underline{B}_{t2} - \underline{B}_{t1} = \alpha (V_{n2} \underline{B}_{t2} - V_{n1} \underline{B}_{t1})$$

$$\underline{B}_{t2} (1 - \alpha V_{n2}) = \underline{B}_{t1} (1 - \alpha V_{n1})$$

$$\underline{B}_{t2} = \underline{B}_{t1} \left(\frac{1 - \alpha V_{n1}}{1 - \alpha V_{n2}} \right)$$

⇒ \underline{B}_{t2} in same direction as \underline{B}_{t1}



\hat{n} , \underline{B}_1 , \underline{B}_2 are in same plane

$$\hat{n} \cdot (\underline{B}_1 \times \underline{B}_2) = 0$$

co-planarity theorem

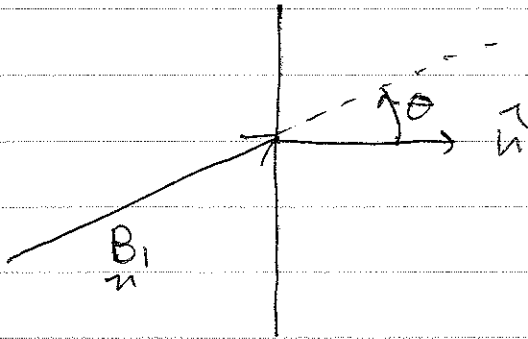
⇒ not true for contact discontinuity where $B_n = 0$

Choose shock frame in which

$$V_{n1} = 0$$

⇒ inflow is parallel to \hat{n}

⇒ free choice.



$$r = \frac{n_2}{n_1}$$

$$M_A = \frac{V_1}{V_{1A}}$$

$$V_{1A} = \frac{B_1^2}{4\alpha m n_1}$$

~~BYC~~

From (4) $n_2 v_{n2} = n_1 v_1$

comes later to form eq for v_2

From (3)

$$n_1 v_1 \left[\frac{1}{2} m n_1 v_1^2 v_{n2} + \frac{\Gamma}{\Gamma-1} P_2 v_{n2} + \frac{B_2^2}{4\pi} v_{n2} - \frac{1}{4\pi} B_2^2 v_2 B_n \right]$$

$$= \frac{1}{2} m v_1^3 n_1 + \frac{\Gamma}{\Gamma-1} P_1 v_1 + \frac{B_1^2}{4\pi} v_1 - \frac{1}{4\pi} B_n^2 v_1$$

From (6)

$$\frac{n_1 v_1^2 m v_{n2}}{n} + P_2 + \frac{B_{t2}^2}{8\pi} = m n_1 v_1^2 + P_1 + \frac{B_1^2 \sin^2 \theta}{8\pi}$$

From (7)

$$4\pi m n_1 v_1 v_{t2} - \frac{1}{4\pi} B_n B_{t2} = -\frac{1}{4\pi} B_n B_{t1}$$

From (9)

$$n_2 v_{n2} B_{t2} - v_{t2} B_n = v_1 B_{t1}$$

$$B_{t2} = \frac{4\pi m n_1 v_1}{B_n} v_{t2} + B_{t1}$$

$$M_{An}^2 = \frac{V_1^2}{B_n^2 / 4\pi m n_1}$$

$$r \frac{V_1}{V_2} \left[\frac{4\pi m n_1 V_1^2}{B_n^2} \frac{V_{t2}}{V_1} + \frac{B_{t1}}{B_n} \right] - B_n \frac{V_{t2}}{V_1} = \frac{B_{t1}}{B_n}$$

$$\Rightarrow \frac{V_{t2}}{V_1} \left(\frac{M_{An}^2}{r} - 1 \right) = \frac{B_{t1}}{B_n} \left(1 - \frac{1}{r} \right)$$

$$B_{t2} = \frac{4\pi m n_1 V_1}{B_n} \left(\frac{V_1}{r} \frac{B_{t2}}{B_n} - V_1 \frac{B_{t1}}{B_n} \right) + B_{t1}$$

$$\Rightarrow B_{t2} \left(1 - \frac{M_{An}^2}{r} \right) = B_{t1} \left(1 - M_{An}^2 \right)$$

$$\frac{|V_{t2}|}{V_1} = \frac{B_1 \sin^2 \theta}{B_1 \cos^2 \theta} \left(1 - \frac{1}{r} \right) \frac{1}{\frac{M_A^2}{r \cos^2 \theta} - 1}$$

$$\frac{|V_{t2}|}{V_1} = \frac{(r-1) \sin^2 \theta \cos^2 \theta}{M_A^2 - r \cos^2 \theta}$$

$$\frac{|B_{t2}|}{|B_{t1}|} = \frac{r (M_A^2 - \cos^2 \theta)}{M_A^2 - r \cos^2 \theta}$$

From jump conditions (energy and momentum)

$$\left(\frac{a M_A^2}{r} - \beta \right) \left(\frac{M_A^2}{r} - \cos^2 \theta \right)^2 - \frac{M_A^2}{r} \sin^2 \theta \left\{ \frac{M_A^2}{r} \left(\frac{a}{r} - \frac{1-\omega}{2} \right) - a \cos^2 \theta \right\} = 0$$

$$a = \frac{\Gamma + 1 - (\Gamma - 1)r}{2}$$

$$r = \frac{n_2}{n_1} \quad M_A = \frac{v_1}{c_{A1}}$$

$$\beta = \frac{c_{s1}^2}{c_{A1}^2}$$

$$c_s^2 = \frac{\Gamma P}{m n}$$

note that this equation is related to the ~~linear~~ dispersion relation for small amplitude MHD waves

$$\Rightarrow \text{take } r=1 \Rightarrow a=1$$

$$M_A = \frac{\omega}{k c_A}$$

$$\left(\frac{\omega^2}{k^2 c_A^2} - \beta \right) \left(\frac{\omega^2}{k^2 c_A^2} - \cos^2 \theta \right)^2 - \frac{\omega^2}{k^2 c_A^2} \sin^2 \theta \left(\frac{\omega^2}{k^2 c_A^2} - \cos^2 \theta \right) = 0$$

Generally has three solutions:

$$\omega = k c_A \cos \theta \quad \text{intermediate or Alfvén wave}$$

$$\left(\frac{\omega^2}{k^2 c_A^2} - \beta \right) \left(\frac{\omega^2}{k^2 c_A^2} - \cos^2 \theta \right) = \frac{\omega^2}{k^2 c_A^2} \sin^2 \theta$$

\Rightarrow fast and slow modes

$$\theta = 0$$

$$\omega^2 = \beta k^2 c_A^2 \Rightarrow \text{sound wave}$$

$$\omega^2 = k^2 c_A^2 \Rightarrow \text{Alfvén wave}$$

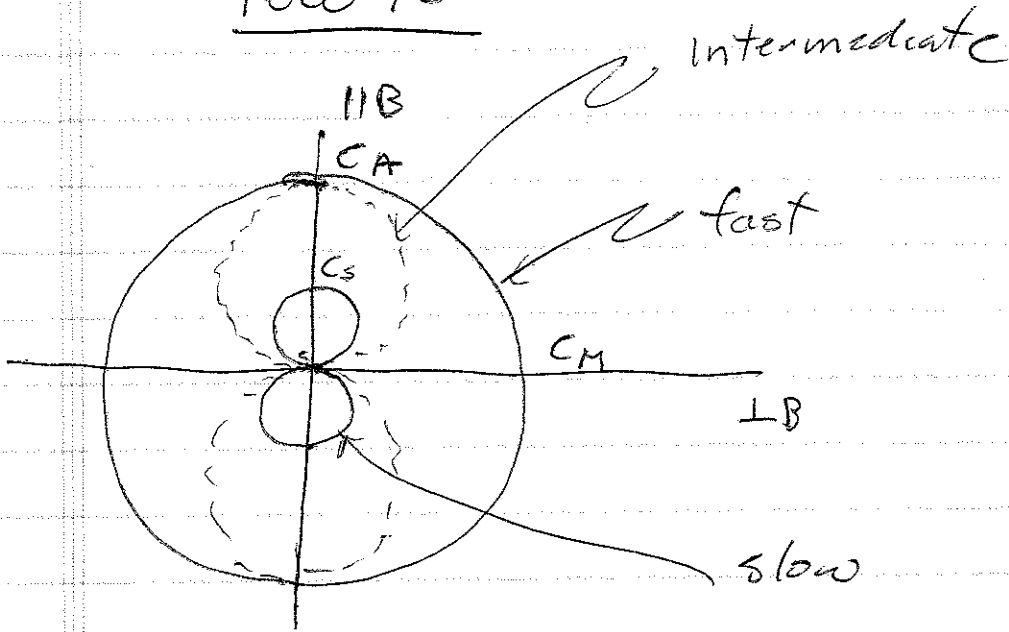
$$\theta = \frac{\pi}{2}$$

$$\omega^2 = 0 \Rightarrow \text{slow mode}$$

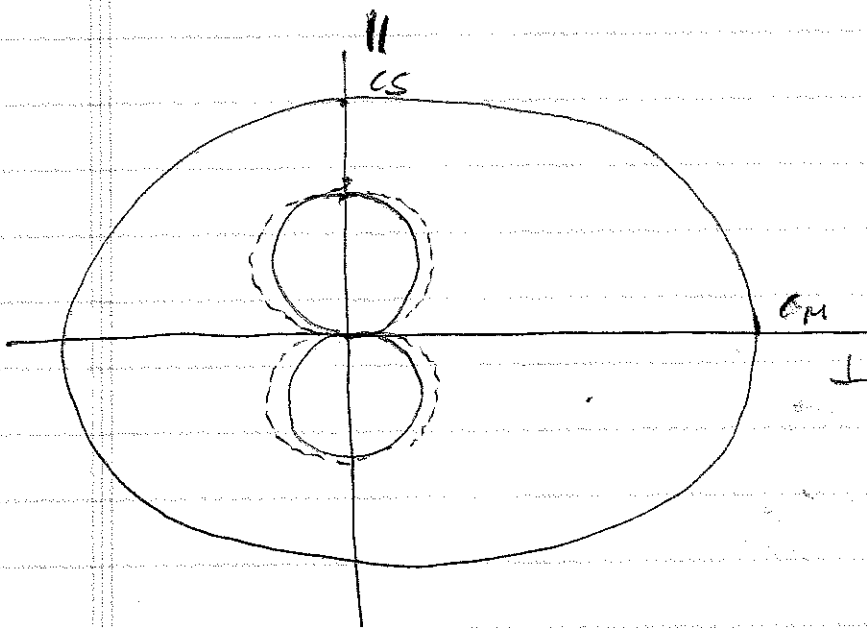
$$\omega^2 = k^2 c_A^2 (1 + \beta) \Rightarrow \text{fast magnetosonic mode.}$$

Friedrichs diagrams

low β



high β



Shock solutions

Generally have three classes of solutions ~~and~~ analagous to waves.

* Fast and slow shocks are true shocks.

* Alfvén or intermediate wave does not steepen

⇒ no compression

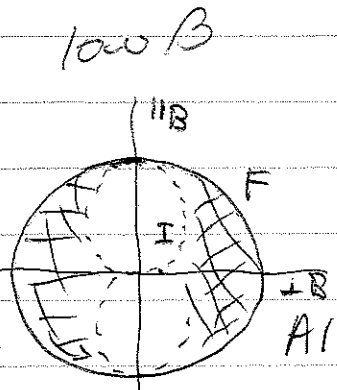
⇒ plasma must compress across shock corresponding to an increase in the entropy.

⇒ increase in entropy defines shock.

Existence conditions

fast shock → upstream ^{normal} velocity must exceed fast wave speed.

downstream normal velocity must fall below down speed fast wave speed and above intermediate speed.



Allowed downstream flow speeds.

(over)

Intermediate or Alfvén solution

$n=1, a=1 \Rightarrow$ no compression

$(M_A^2 - \beta)(M_A^2 - \cos^2 \theta)^2 - M_A^2 \sin^2 \theta [M_A^2 - \cos^2 \theta] = 0$

$\Rightarrow M_A^2 = \cos^2 \theta, \quad M_{An} = 1 \quad v_1 = \frac{B_n}{4\pi m n}$

\Rightarrow equation for B_{t2} ambiguous

\Rightarrow use (6) $\Rightarrow [B_{t2}] = 0$ for $[P] = 0$

Look for solution with

$B_{t2} = -B_{t1}$

no compression

~~$v \cdot \nabla P + \Gamma P \nabla \cdot v =$~~

~~$[P] = 0$~~

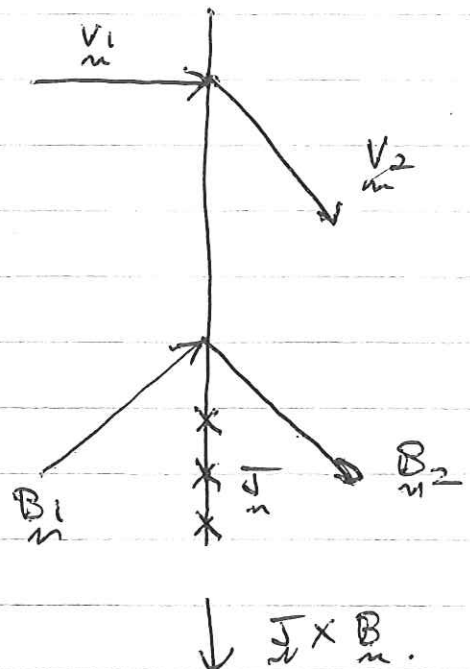
From (7)

$[v_{t2}] = \frac{B_n}{4\pi m n v_1} [B_{t2}]$

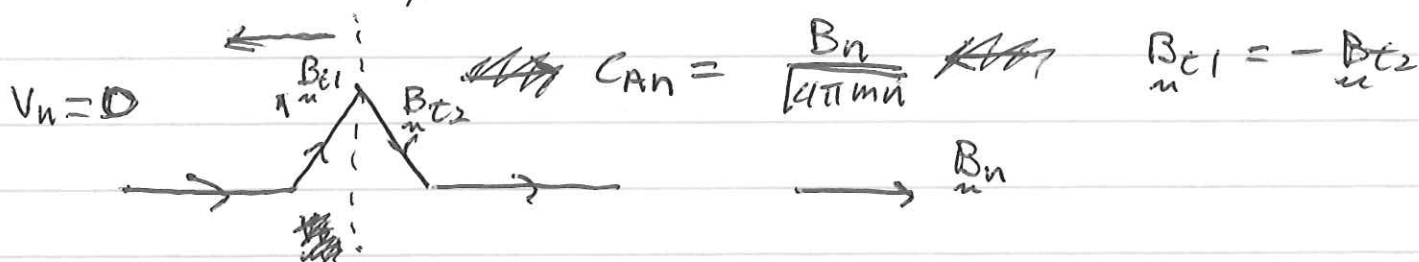
$[v_{z2}] = [C_{At2}]$

$v_{t2} = -2 C_{At2}$

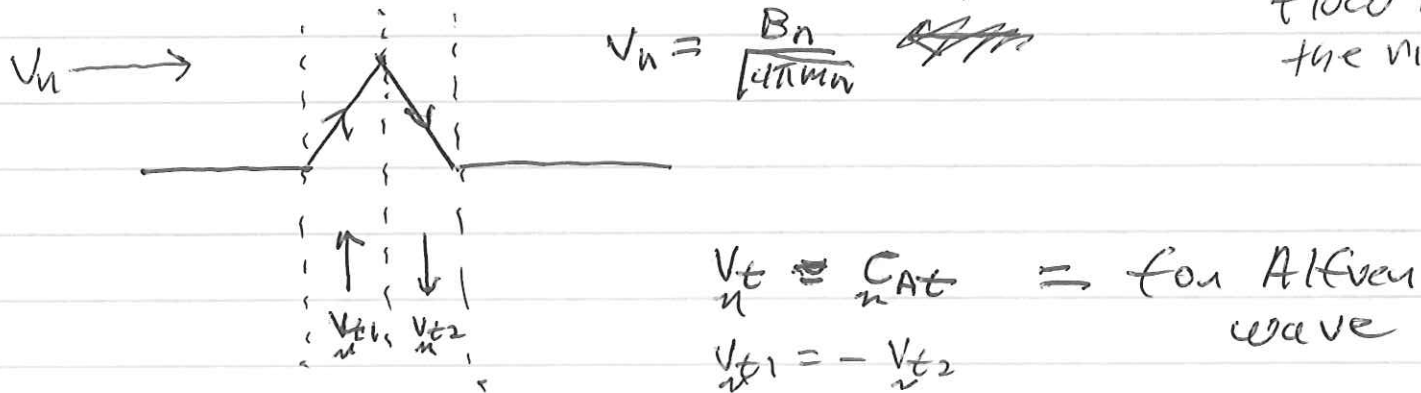
\Rightarrow rotational discontinuity



Consider an Alfvén kink



In wave frame \Rightarrow stationary $B_n \Rightarrow$ plasma flow to the right



Wave frame $V_n = V_{nt} + V_{nt} , B = B_n + B_t$

$$V_n \times B_n = C_{An} \times B_n + V_n \times B_t$$

$$= B_t \times V_n + V_n \times B_t = 0$$

$\Rightarrow V_n$ parallel with B_n

$\Rightarrow E = 0$

\Rightarrow de Hoffmann-Teller frame

How does this frame relate to the frame of our Alfvén solution?

\Rightarrow shift to frame moving with V_{t1}

$\Rightarrow V_{t1}' = 0 , V_{t2}' = -2 C_{At1} \Rightarrow$ our shock solution

Fast Mode Shock

⇒ consider low β

$$a \frac{M_A^2}{r} \left(\frac{M_A^2}{r} - \cos^2 \theta \right)^2 - \frac{M_A^2}{r} \sin^2 \theta \left\{ \frac{M_A^2}{r} \left(\frac{a}{r} - \frac{1-r}{2} \right) - a \cos^2 \theta \right\} = 0$$

$$a = \frac{\Gamma + 1 - (\Gamma - 1)r}{2}$$

$$r = \frac{n_2}{n_1}$$

$$\left(\frac{M_A^2}{r} - \cos^2 \theta \right)^2 - \sin^2 \theta \left\{ \frac{M_A^2}{r} \left(\frac{1}{r} - \frac{1-r}{2a} \right) - \cos^2 \theta \right\} = 0$$

consider what happens when M_A is very large ⇒ how large does r become?

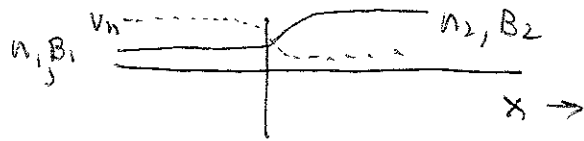
$$\left(\frac{M_A^2}{r} \right)^2 - \sin^2 \theta \frac{M_A^2}{r} \left(\frac{1}{r} - \frac{1-r}{2a} \right) = 0$$

$$\cancel{M_A^2} \quad M_A^2 - \sin^2 \theta \left(1 - \frac{(1-r)r}{2a} \right) = 0$$

Note that $a < 0$ for large r so second term ~~can't be~~ is positive and can't balance first.

⇒ must ~~that~~ have $a \rightarrow 0^+$ as $M_A \rightarrow \infty$

$$a \rightarrow 0 \Rightarrow r = \frac{\Gamma + 1}{\Gamma - 1} = \frac{\frac{5}{3} + 1}{\frac{5}{3} - 1} = 4 \quad (\text{over})$$



(14)

$$V_{2n} = \frac{V_{1n} n_1}{n_2} = \frac{V_{1n}}{4} = \frac{V_1}{4}$$

$$B_2 = (B_n^2 + B_{t2}^2)^{\frac{1}{2}} = (B_n^2 + 16 B_{t1}^2)^{\frac{1}{2}}$$

$$= B_1 \left(\cos^2 \theta + 16 \sin^2 \theta \right)^{\frac{1}{2}}$$

$$C_{A2} = C_{A1} \frac{B_2}{B_1} \sqrt{\frac{n_1}{n_2}}$$

$$\frac{V_{2n}}{C_{A2}} = \frac{V_1}{4 C_{A1} (\cos^2 \theta + 16 \sin^2 \theta)^{\frac{1}{2}}} \quad 2$$

$$= M_A \frac{1}{2 \sqrt{\cos^2 \theta + 16 \sin^2 \theta}}$$

$$= \frac{M_A}{2 \sqrt{1 + 15 \sin^2 \theta}} < 1$$

$$M_A < 2 \sqrt{1 + 15 \sin^2 \theta}$$

Limit $\theta = 0$

$$M_A^2 = v \cos^2 \theta \quad B_1 \sin \theta$$

$$\frac{|B_{t2}|}{|B_{t1}|} \rightarrow \infty \quad \text{but} \quad |B_{t1}| \rightarrow 0$$

$$\cos \theta = 0$$

$$\Rightarrow B_{t2} \neq 0$$

\Rightarrow switch-on shock.

Slow shocks

⇒ low β

take $M_A^2 \sim \beta$

v_1 must exceed projection of sound speed normal to shock.

$$\left(\frac{a}{v} M_A^2 - \beta\right) \cos^2 \theta + \frac{M_A^2}{v} \sin^2 \theta (1-a) \cos^2 \theta = 0$$

⇒ $\frac{v_1^2}{c_s^2 \cos^2 \theta} > 1$ for shock to form.

$$M_A^2 = \beta \cos^2 \theta \frac{v}{a}$$

⇒ $\theta = 0$ β drops out.

⇒ pure sound ~~wave~~ shock

$$\frac{|B_{t2}|}{|B_{t1}|} = \frac{\beta \frac{v}{a} - 1}{\beta \frac{v}{a} - 1} = \frac{1 - \beta \frac{v}{a}}{1 - \frac{\beta}{a}}$$

$$\approx 1 - \frac{\beta}{a}(v-1) < 1$$

$n_2 > n_1$

$B_2 < B_1$

~~Handwritten scribbles and crossed-out equations, including:~~

$$\frac{|B_{t2}|}{|B_{t1}|} \approx \frac{B_1 \sin \theta (1 - \frac{\beta}{a}(v-1))}{\frac{B_1 \sin \theta}{a} (1 - \frac{\beta}{a})}$$

⇒ pressure increases across shock

~~⇒~~ magnetic pressure decreases

