

Linear Differential Equations with Constant Coefficients Arfken Chapter 7

Consider an n th order equation of the following form

$$y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_0 y^{(0)} = b(x)$$

$$\Rightarrow L(y) = b(x)$$

with $y^{(j)}$ the j th derivative of y with respect to x . Take a_0, a_1, \dots, a_n , indep. of x .

Consider first $b(x) = 0 \Rightarrow$ homogeneous eqn

Eqn. is linear since first order in y .

Consider some m solutions $\{Q_j\}$ of the eqn.
Then any combination

$$y = \sum c_j Q_j(x)$$

is a solution since

$$L(y) = \sum c_j L(Q_j) = 0$$

Exponential solutions

Look for solutions of the form $y = e^{kx}$

$$\frac{d^n}{dx^n} y = k^n e^{kx} = k^n y$$

$$f(y) = 0 \Rightarrow P(k) = \sum_{j=0}^n a_j k^j = 0$$

This is an n th order polynomial which has n solutions. Generally have n solutions of $f(y) = 0$ of the form

$$e^{k_1 x} e^{k_2 x} \cdots \cdots e^{k_n x}$$

what if have repeated roots?

$$P(k) = g(k)(k - k_0)^m$$

with $g(k_0) \neq 0$

$$f(e^{kx}) = g(k)(k - k_0)^m e^{kx}$$

Take the derivative with respect to k

$$\begin{aligned} \frac{d}{dk} f(e^{kx}) &= f(xe^{kx}) = m g(k)(k - k_0)^{m-1} \\ &\quad + g'(k)(k - k_0)^m \end{aligned}$$

Set $k = k_0$

$$f(xe^{k_0 x}) = 0$$

so $x e^{k_0 x}$ is a solution. Repeat to find

$e^{k_0 x} x e^{k_0 x} \dots x^{m-1} e^{k_0 x}$ are solutions.

Linear Independence

Consider a set of n solutions to $f_j(x)$.
 These solutions are linearly dependent if
 a linear combination can be found such that

$$\sum_i c_i f_i(x) = 0$$

over the interval x of interest with $c_j \neq 0$
 for at least some values of j . If the only
 solution is $c_j = 0$ for all j , the solutions
 are linearly independent.

Proof that the exponential solutions are linearly independent.

\Rightarrow assume no repeated roots

\Rightarrow proof by contradiction

Assume $\sum_i c_i e^{k_i x} = 0$ with at least

one value $c_q \neq 0$

$$\sum_{j=1}^n c_j e^{k_j x} = 0$$

Divide by $e^{k_1 x}$

$$\sum_{j=1}^n c_j e^{(k_j - k_1)x} = 0$$

Take x derivative $\Rightarrow j=1$ term goes away

$$\sum_{j=2}^n c_j (k_j - k_1) e^{(k_j - k_1)x} = 0$$

Continue for all $j \neq g$, and ~~are~~ left with

$$c_g (k_g - k_1)(k_g - k_2)(k_g - k_g + 1)(k_g - k_g + 1)$$

$$\times \dots (k_g - k_n) e^{k_g x} = 0$$

$\Rightarrow c_g = 0 \Rightarrow$ contradicts assumption

\Rightarrow only solution is for $c_j = 0$ for all j

\Rightarrow the exponential solutions are linearly independent.

Initial Value Problem

Consider the operator $L(y) = 0$. Suppose that $y(x)$ and its first $n-1$ derivatives are specified at x_0 .

$$y(x_0) = \alpha_0$$

$$y^{(1)}(x_0) = \alpha_1$$

$$y^{(n-1)}(x_0) = \alpha_{n-1}$$

The solution y is uniquely defined.

Uniqueness Theorem

Consider the initial value problem as defined above. There exists at most one solution satisfying these equations.

Proof: Suppose y_1 and y_2 are two solutions then $\varphi = y_1 - y_2$ satisfies $L(\varphi) = 0$ with

$$\varphi^{(i)}(x_0) = 0$$

for $i = 0, 1, \dots, n-1$. All derivatives vanish at x_0 . ~~Can expand~~ Calculate higher derivatives from the diff. eqns. Can expand $\varphi(x)$ in a Taylor series around x_0 . $\Rightarrow \varphi(x) = 0$ around x_0

valid until the closest singularity.

Wronskian

The Wronskian $W(\varphi_1, \dots, \varphi_n)$ of n functions $\varphi_1, \dots, \varphi_n$ having $n-1$ derivatives on some interval is defined as

$$W = \begin{vmatrix} \varphi_1 & \dots & \varphi_n \\ \varphi_1' & \dots & \varphi_n' \\ \vdots & & \vdots \\ \varphi_1^{(n-1)} & \dots & \varphi_n^{(n-1)} \end{vmatrix} \quad \text{determinant}$$

Theorem If $\varphi_1, \dots, \varphi_n$ are n solutions of $f(y) = 0$ on an ~~intervall~~ interval, they are linearly independent if and only if $W \neq 0$ for all x on the interval.

Proof: Suppose $W \neq 0$ for all x on interval.

→ assume linearly dependent and find contradiction.

Let c_1, c_2, \dots, c_n be constants such that

$$c_1\varphi_1(x) + c_2\varphi_2(x) + \dots + c_n\varphi_n(x) = 0$$

Then

$$c_1 \phi_1' + \dots + c_n \phi_n' = 0$$

$$c_1 \phi_1'' +$$

$$\vdots$$

$$c_1 \phi_1^{(n)} + \dots + c_n \phi_n^{(n)} = 0$$

what about

$$c_1 \phi_1^{(n)} + \dots + c_n \phi_n^{(n)} = ?$$

Is it an independent equation?

This is a set of linear homogeneous equations for c_1, \dots, c_n . The condition that they have a nonzero solution is that the determinant of the coefficients is zero.

But this is the Wronskian which is assumed to be nonzero. The only solution is $c_j = 0$ for all j .

\Rightarrow If $W \neq 0$ then the $\phi_j'(x)$ are linearly independent.

(Conversely) suppose ϕ_1, \dots, ϕ_n are linearly independent solutions to $f(y) = 0$.

\Rightarrow Suppose $W(x_0) = 0$ and prove contradiction

If $w(x_0) = 0$,

$$c_1 \varphi_1(x_0) + \dots + c_n \varphi_n(x_0) = 0$$

$$\vdots$$

$$c_1 \varphi_1^{(n-1)}(x_0) + \dots + \cancel{c_n \varphi_n^{(n-1)}(x_0)} = 0$$

has a solution with some $c_j \neq 0$.

$$\text{Consider } \psi = c_1 \varphi_1(x) + \dots + c_n \varphi_n(x)$$

$$\Rightarrow \psi'(x) = 0$$

$$\text{but } \psi(x_0) = 0, \psi'(x_0) = 0, \dots, \psi^{(n-1)}(x_0) = 0$$

$$\Rightarrow \psi(x) \text{ from earlier proof}$$

since Taylor series gives zero.

$\Rightarrow \varphi_1, \varphi_2, \dots, \varphi_n$ not linearly independent

\Rightarrow contradiction so $w(x_0) \neq 0$.

Existence Theorem for Initial Value Problems

Let x_0, x_1, \dots, x_{n-1} be any real constants and x_0 any real number. Then there exists a solution $f(y) = 0$ on $-\infty < x < \infty$ satisfying

$$y(x_0) = x_0$$

$$y'(x_0) = x_1$$

$$\vdots \\ y^{(n-1)}(x_0) = x_{n-1}$$

\Rightarrow initial value problems always have solutions

\Rightarrow All derivatives evaluated at a single x_0

Let $y(x) = c_1 \phi_1(x) + \dots + c_n \phi_n(x)$ where the ϕ_j 's are linearly indep. Want to solve for the c_j 's.

$$c_1 \phi_1(x_0) + \dots + c_n \phi_n(x_0) = x_0$$

$$\vdots \\ c_1 \phi_1^{(n-1)}(x_0) + \dots = x_{n-1}$$

The determinant of the matrix equation for the c_j 's is the Wronskian which is non zero. Therefore, the c_j 's have a unique solution $\Rightarrow y(x)$ satisfies the B.C.s.

Explicit Equation for $W(x)$

$$w = \begin{vmatrix} Q_1 & \cdots & Q_n \\ \vdots & & \vdots \\ Q_1^{(n-1)} & \cdots & Q_n^{(n-1)} \end{vmatrix}$$

$$\frac{dw}{dx} = \begin{vmatrix} Q_1 & \cdots & Q_n \\ \vdots & & \vdots \\ Q_1^{(n-2)} & \cdots & Q_n^{(n-2)} \\ Q_1^{(n)} & \cdots & Q_n^{(n)} \end{vmatrix} \quad \text{Since derivatives
on other rows
would make
two rows
equal}$$

$$Q_1^{(n)} = -a_{n-1} Q_1^{(n-1)} - \cdots - a_0 Q_1^{(0)}$$

\Rightarrow other rows can be subtracted to
eliminate all but $Q_1^{(n-1)}$

$$\frac{dw}{dx} = -a_{n-1} \begin{vmatrix} Q_1 & \cdots & Q_n \\ \vdots & & \vdots \\ Q_1^{(n-1)} & \cdots & Q_n^{(n-1)} \end{vmatrix} = -a_{n-1} w$$

$$\boxed{\frac{dw}{dx} = -a_{n-1} w}$$

$$w \sim e^{kx}$$

$$ke^{kx} = -a_{n-1}e^{kx}$$

$$\Rightarrow k = -a_{n-1}$$

$$w = A e^{-a_{n-1}x}$$

Suppose know $w(x_0)$

$$w(x) = w(x_0) e^{-a_{n-1}(x-x_0)}$$

\Rightarrow If $w(x_0) \neq 0$ then $w(x) \neq 0$
anywhere (except ∞)

example

$$\frac{d^2y}{dx^2} + \alpha^2 y = 0 \Rightarrow y \sim e^{ikx}$$

$$(-k^2 + x^2) y = 0, \quad k = \pm \alpha$$

$$\varphi_1 = e^{ix}$$

$$\varphi_2 = e^{-ix}$$

$$w = \begin{vmatrix} e^{ix} & -e^{-ix} \\ e^{-ix} & e^{ix} \\ ix & -ix \\ ixe & -ixe \end{vmatrix}$$

$$= -2i\alpha$$

$\Rightarrow w \neq 0$ for $\alpha \neq 0$

$\Rightarrow e^{\pm i\alpha x}$ are linearly indep.

Suppose $\alpha = 0$, $\varphi_1 = \varphi_2 = 1 \Rightarrow w = 0$

\Rightarrow not linearly independent

\Rightarrow Degenerate case

\Rightarrow Other solution is x .

$$\varphi_1 = 1$$

$$\varphi_2 = x$$

$$w = \begin{vmatrix} 1 & x \\ 0 & 1 \end{vmatrix} = 1 \neq 0$$

φ_1, φ_2 linearly indep.

For $\lambda \neq 0$ can also choose

$$Q_1 = \sin \alpha x$$

$$Q_2 = \cos \alpha x$$

$$W = \begin{vmatrix} \sin \alpha x & \cos \alpha x \\ \alpha \cos \alpha x & -\alpha \sin \alpha x \end{vmatrix}$$

$$= -\alpha (\sin^2 \alpha x + \cos^2 \alpha x)$$

$$= -\alpha \neq 0$$

\Rightarrow linearly indepd.

More than two solutions?

$$\sin \alpha x, e^{i\alpha x}, e^{-i\alpha x}$$

$$W = \begin{vmatrix} i\alpha x & -i\alpha x \\ \sin \alpha x & e^{i\alpha x} & e^{-i\alpha x} \\ \alpha \cos \alpha x & ie^{i\alpha x} & -ie^{-i\alpha x} \\ -\alpha^2 \sin \alpha x & -\alpha^2 e^{i\alpha x} & -\alpha^2 e^{-i\alpha x} \end{vmatrix}$$

$$= -\alpha^3 \begin{vmatrix} \sin \alpha x & e^{i\alpha x} & -e^{-i\alpha x} \\ \cos \alpha x & ie^{i\alpha x} & -ie^{-i\alpha x} \\ \sin \alpha x & e^{i\alpha x} & e^{-i\alpha x} \end{vmatrix} = 0$$

Top and bottom rows the same since 2nd derivative can always be expressed in terms of lower derivatives

\Rightarrow This is why an nth order eqn has only n solutions

\Rightarrow The Wronskian will always vanish since higher derivatives can always be expressed in terms of lower derivatives

\Rightarrow The bottom row will always be zero.

Example Initial Value Problem

$$\frac{d^2y}{dx^2} + \beta^2 y = 0 \quad y(0) = x_0 \\ y^{(1)}(0) = x_1$$

$$y = C_1 \cos(\beta x) + C_2 \sin(\beta x)$$

$$C_1 = x_0$$

$$y^{(1)}(0) = -\beta C_1 \sin(0) + \beta C_2 \cos(0) \\ = \beta C_2 = x_1$$

$$C_2 = \frac{x_1}{\beta}$$

$$y = x_0 \cos(\beta x) + \frac{x_1}{\beta} \sin(\beta x)$$

example Damped Oscillator

$$\ddot{y} + 2\beta \dot{y} + \omega^2 y = 0$$

BCS

$$\frac{dy}{dt} \Big|_{t=0} = 0$$

$$\dot{y} = \frac{dy}{dt}$$

$$y \Big|_{t=0} = 1$$

Assume a solution $y \sim e^{-i\omega t}$

$$-\omega^2 - i\omega 2\beta + \omega^2 = 0$$

$$\omega^2 + 2i\beta\omega - \omega^2 = 0$$

$$\omega = \frac{-i\beta \pm \sqrt{4\beta^2 + 4\omega^2}}{2}$$

$$\omega = -i\beta \pm \omega_0 \text{ with } \omega_0 = \sqrt{\beta^2 + \omega^2}$$

$$y \sim e^{-\beta t} e^{i\omega_0 t}$$

$$y = [A \cos \omega_0 t + B \sin \omega_0 t] e^{-\beta t}$$

$$y(0) = A = 1$$

$$\dot{y}(0) = -\beta A + \omega_0 B = 0$$

$$B = \frac{\beta}{\omega_0} \Rightarrow y = [\cos \omega_0 t + \frac{\beta}{\omega_0} \sin \omega_0 t] e^{-\beta t}$$

Example Boundary Value Problem (Dirichlet)

$$\frac{d^2y}{dx^2} + \beta^2 y = 0 \Rightarrow \text{specify } y \text{ at } x=0, 1$$

$$y = C_1 \cos \beta x + C_2 \sin \beta x$$

$$y(0) = x_0 \Rightarrow C_1 = x_0$$

$$y(1) = x_1 \Rightarrow y(1) = x_0 \cos \beta + C_2 \sin \beta \\ = x_1$$

$$C_2 = \frac{x_1 - x_0 \cos \beta}{\sin \beta}$$

Solution ok except $\beta = \pi$

$$y = C_1 \cos \pi x + C_2 \sin \pi x$$

$\Rightarrow \sin(\pi x)$ does not contribute at 0, 1
so only have solution for $x_0 = x_1$

\Rightarrow not all boundary value problems have solutions