

Approximating Contour Integrals

Saddle Point Methods \Rightarrow require a large parameter

$$\Gamma(p) = \int_0^\infty dz e^{-z} z^{p-1} \Rightarrow \text{gamma function}$$

\Rightarrow defined for

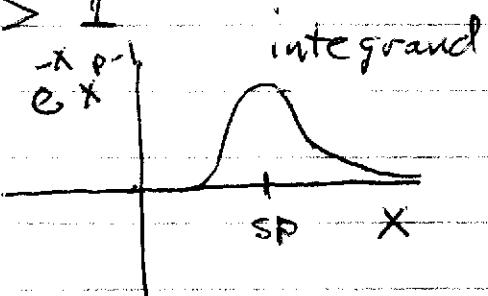
$$\Gamma(p) = (p-1)\Gamma(p-1) \quad \text{Re}(p) > 0$$

$$\Gamma(n) = (n-1)! \text{ for } n \text{ integer. why?}$$

Take p to be real

for simplicity and take $p \gg 1$

$$\Gamma(p) = \int_0^\infty dz e^{-z + (p-1)\ln z}$$



$$\text{Let } h(z) = (p-1)\ln(z) - z$$

Integrand peaks where

$$h'(z) = 0 = (p-1) \frac{1}{z} - 1$$

$$z_{sp} = p-1$$

\Rightarrow How do we know that z_{sp} must be a saddle point?

$$h'' = -\frac{p-1}{z^2} \Rightarrow h''(z_{sp}) = -\frac{(p-1)}{(p-1)^2} = -\frac{1}{p-1}$$

Near the saddle point expand h in a Taylor series

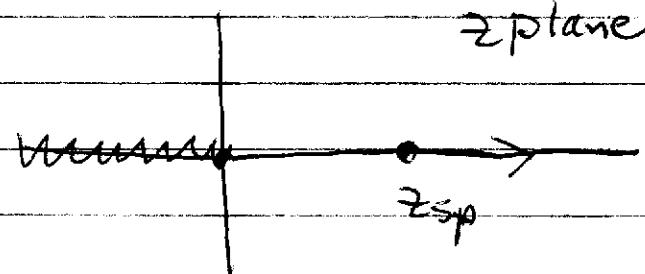
(57)

$$h(z) \approx h(z_{sp}) + \frac{1}{2} h''(z_{sp}) (z - z_{sp})^2$$

$$\text{Let } \Delta z = z - z_{sp}$$

$$h(z) \approx (p-1)/\ln(p-1) - (p-1) - \frac{1}{2} \frac{\Delta z^2}{p-1}$$

$$\text{Near } z_{sp}: e^{h(z)} \approx (p-1)^{p-1} e^{-(p-1)} e^{-\frac{1}{2} \frac{\Delta z^2}{p-1}}$$



note: $h(z)$ goes to zero away from S.P. along the real axis

B.C. needed because p might not be an integer

$h(z)$ increases away from S.P. along y axis

$$\Rightarrow \Delta z = i \Delta y$$

\Rightarrow as expected for S.P.

Approximate $\Gamma(p)$ as

$$\Gamma(p) \approx (p-1)^{p-1} e^{-(p-1)} \int_{-\infty}^{\infty} dz e^{-\frac{1}{2} \frac{\Delta z^2}{p-1}}$$

\Rightarrow where extend integral over Δz to $\pm \infty$
since when Taylor series breaks down,
the integrand is already small!

$$\Gamma(p) = (p-1)^{p-1} e^{-(p-1)} \sqrt{\pi} [2(p-1)]^{\frac{1}{2}}$$

$$\boxed{\Gamma(p) = \sqrt{2\pi} (p-1)^{p-\frac{1}{2}} e^{-(p-1)}}$$

Stirling's formula

\Rightarrow very accurate for large P .

Check: Is the next order term in the Taylor series small when

$$\frac{1}{2} h'' \Delta z^2 \sim 1 \Rightarrow \text{where}$$

$$\Delta z \sim (P-1)^{1/2} \quad e^{h(z)} \rightarrow 0$$

next term

$$\frac{1}{3!} h''' \Delta z^3 = \frac{1}{6} \frac{2(P-1)}{z_{sp}^3} \Delta z^3$$

$$\sim \frac{\Delta z^3}{(P-1)^2} \sim \frac{1}{(P-1)^{1/2}} \ll 1$$

\Rightarrow valid for

$$P-1 \gg 1$$

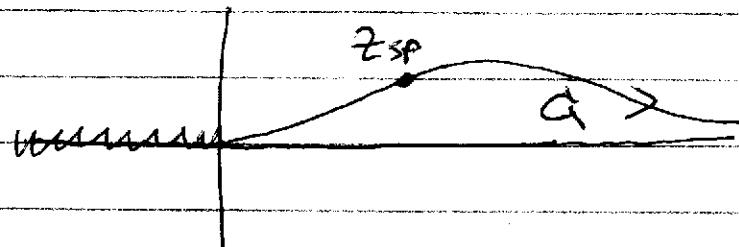
Now allow P to be complex.

\Rightarrow still require $\operatorname{Re}(P) > 0$

$$\text{S.P. as before: } z_{sp} = (P-1) = g \\ = |g| e^{i\beta}$$

S.P. in the complex plane

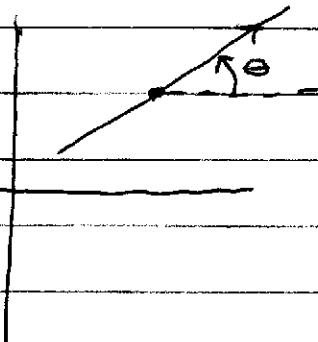
\Rightarrow move the contour to a path through the S.P.



Again expand $h(z)$ around z_{sp}

$$\Gamma(p) = \int_C dz e^{-\frac{(z-z_{sp})^2}{2(p-1)}} (p-1)^{p-1} e^{h(z)}$$

What is the angle of C through the S.P.?



$$dz = s e^{i\theta}$$

with s real

Choose θ so that

$\frac{(z-z_{sp})^2}{2(p-1)}$ is real and positive

$$\Rightarrow \frac{e^{2i\theta}}{p-1} \sim \frac{e^{2i\theta}}{e^{i\beta}} = e^{i(2\theta-\beta)}$$

$$\Rightarrow \theta = \frac{\beta}{2} = \frac{1}{2} \operatorname{Arg}(p-1)$$

This defines the path of steepest descent

$\Rightarrow PSD$

\Rightarrow path along which $e^{h(z)}$ goes to zero the fastest

$$e^{h(z)} \approx (p-1)^{p-1} e^{-(p-1)} e^{-\frac{s^2}{16T} \frac{1}{2}}$$

$$|G| = |p-1|$$

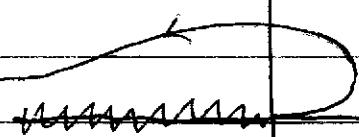
$$\begin{aligned}
 \Gamma(p) &= (p-1)^{p-1} e^{-(p-1)} \int_{-\infty}^{\infty} e^{-\frac{s^2}{2(p-1)}} ds e^{is} \\
 &= (p-1)^{p-1} e^{-(p-1)} \underbrace{\sqrt{2\pi} |p-1|^{1/2}}_{(p-1)^{1/2}} e^{i\frac{1}{2}\operatorname{Arg}(p-1)} \\
 &= \sqrt{2\pi} (p-1)^{p-\frac{1}{2}} e^{-(p-1)}
 \end{aligned}$$

\Rightarrow same as before

Asymptotic form of the Hankel function

$$H_{\nu}^{(1)}(s) = \frac{1}{\pi i} \int_0^{-\infty} dz e^{\frac{s}{2}(z - \frac{1}{z})} z^{\nu+1}$$

\mathbb{z} plane



Have a cut beginning at the RP at $z=0$ when $\nu \neq$ integer.

Want to evaluate $H_{\nu}^{(1)}$ for s real and large and $\nu \approx 1$.

Basic idea: The integrand remains small over most of the path of integration if it is deformed to pass through a saddle point and follows the PSD through the S.P.

\Rightarrow contribution over the S.P. dominates the integral.

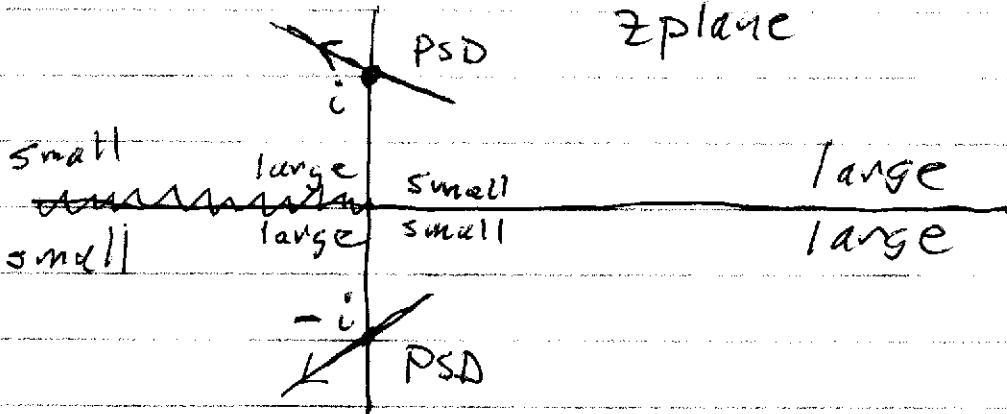
Essential point: Explore the structure of the integrand in the complex plane to determine whether the S.P.s dominate the integral and if so which S.P. is most important.

Locate the saddle points:

$$h(z) = \frac{s}{2} \left(z - \frac{1}{z} \right) \Rightarrow \text{ignore } \frac{1}{z^{\nu+1}}. \text{ Why?}$$

$$h' = \frac{5}{2} \left(1 + \frac{1}{z^2} \right) = 0 \Rightarrow z_{sp} = \pm i$$

$$\text{Topology of } e^{\frac{5}{2}(z - \frac{1}{z})} \quad h'' = -5 \frac{1}{z^3}$$



Move the contour Γ to pass through $z_{sp} = i$

Why is $z_{sp} = -i$ unimportant?

* Expand $h(z)$ around $z_{sp} = i$

$$h(z) \approx h(z_{sp}) + \frac{1}{2} h''(z_{sp})(z - z_{sp})^2$$

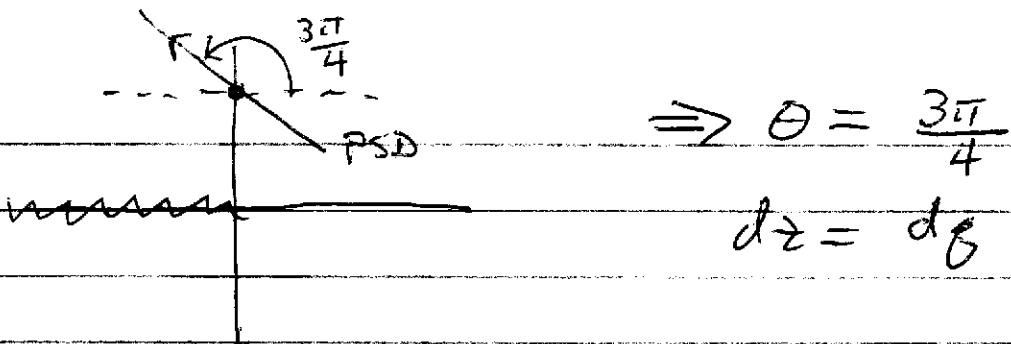
$$= \frac{5}{2}(i - \frac{1}{i}) + \frac{1}{2} \left(-5 \frac{1}{i^3} \right) (z - i)^2$$

$$= iS - i \frac{5}{2} (z - i)^2 \quad z - i = ge^{i\theta}$$

$$= iS - i \frac{5}{2} g^2 e^{2i\theta}$$

$$\text{PSD} \Rightarrow ie^{2i\theta} = 1$$

$$e^{2i\theta} e^{i\frac{\pi}{2}} = 1 \Rightarrow \theta = -\frac{\pi}{4}, \frac{3\pi}{4}$$



$$dz = dg e^{i\theta}$$

$$H_V^{(1)}(s) \simeq \frac{1}{\pi i} \int_{-\infty}^{\infty} dg e^{i\frac{3\pi}{4}} e^{-\frac{s}{2}g^2}$$

$$e^{i\rho+1} = e^{i\frac{\pi}{2}(\rho+1)} \Rightarrow z_{sp} = e^{i\frac{\pi}{2}}$$

\Rightarrow because of B.C.

$$H_V^{(1)}(s) \simeq \frac{1}{\pi i} e^{-i\frac{\pi}{2}(\rho+1)} e^{i\frac{3\pi}{4}} e^{-\frac{s}{2}g^2} \int_{-\infty}^{\infty} dg e$$

$$H_V^{(1)}(s) \simeq - \sqrt{\frac{2}{\pi s}} e^{\frac{3\pi i}{4}} e^{is} e^{-i\frac{\pi}{2}\rho}$$

$$\sqrt{\pi} \sqrt{\frac{2}{s}}$$

For $s \gg 1$