

# Plowing with Multiple Plows

## A Variant of the Windy Postman Problem

May 22, 2012 – ODYSSEUS 2012

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# Overview

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# Background

## Chinese Postman Problem (CPP)

- ❖ Consider a graph  $G=\{V,A\}$  where
  - ▶  $V=\{v_i\}$  is the set of vertices
  - ▶  $A=\{(v_i,v_j) \mid v_i, v_j \in V, i < j\}$  is the set of arcs
  - ▶  $c_{ij}$  = Cost of traversing arc  $(v_i,v_j)$
  - ▶  $C_{ij} = C_{ji}$
- ❖ Goal: Construct a least-cost cycle that visits all arcs in  $A$  at least once



# Background

## Windy Postman Problem (WPP)

- ❖ A variant of the Chinese Postman Problem
- ❖ The graph is windy, i.e., it is harder to traverse in one direction on an arc as opposed to the other direction
- ❖ Goal: Construct a least-cost cycle that visits all arcs in  $A$  at least once
- ❖ Key Difference: Costs are not symmetric



# Background

## Downhill Plow Problem (DPP)

- ❖ A variant of the Windy Postman Problem that incorporates four costs:
  - The costs of plowing uphill and downhill
  - The costs of deadheading uphill and downhill
- ❖ The plow can deadhead at any time
  - When considering a street that is not plowed, the plow has the option to deadhead the street or to plow the street



# Background

## Methodology for the CPP, WPP, and DPP

- ❖ Key observation: If a graph is Eulerian, then an optimal cycle can be produced by Fleury's Algorithm
- ❖ Therefore, it is sufficient to convert the instance graph to an Eulerian graph in an optimal way
- ❖ Possible methods
  - ▶ Integer programming
  - ▶ Add least-cost paths between odd-degree nodes



# Background

## DPP - IP Formulation

- ❖ Adapt IP formulation from the Windy Postman Problem
- ❖ Essential variables:
  - ▶  $x_{ij}$  = the number of times  $(v_i, v_j)$  is plowed
  - ▶  $y_{ij}$  = the number of times  $(v_i, v_j)$  is deadheaded
- ❖ Essential constraints:
  - ▶ Plow each street twice
  - ▶ Degree matching for each node
- ❖ While the DPP is NP-hard (since it is a generalization of the WPP), the IP is easily solved by commercial solvers



# Literature Review

- ❖ Arc routing is well studied. There are many survey articles including
  - ▶ Assad and Golden (1995)
  - ▶ Eiselt et al. (1995a, 1995b)
  - ▶ Dror (2000)
- ❖ Perrier et al. (2006, 2007) provide a four-part survey of winter road maintenance covering
  - ▶ System Design
  - ▶ Models and Algorithms
  - ▶ Vehicle Routing and Depot Location
  - ▶ Vehicle Routing and Fleet Sizing



# Literature Review

- ❖ Min-Max k-CPP
  - Frederickson et al (1978)
  - Ahr and Reinelt (2002)
  - Arh (2004)
- ❖ Min-Max k-WRPP
  - Benavent (2009, 2010, 2011, 2012)
- ❖ Don't incorporate four costs like the DPP



# Introduction to MDPP

- ❖ Generalization of the Downhill Plow Problem
- ❖ Min-Max Multiple Plow Downhill Plowing Problem (Min-Max  $k$ -DPP)
  - ▶  $k$  Plows
  - ▶ Objective: Minimize the maximum route length
- ❖ Key attributes:
  - ▶ Minimizing cumulative route length and route balancing are competing objectives
  - ▶ If multiple plows traverse a street, there is a decision regarding which plows clear the street



# Problem Statement

- ❖ Consider a graph  $G=\{V,A\}$  where
  - ▶  $V=\{v_i\}$  is the set of vertices
  - ▶  $A=\{(v_i, v_j) \mid v_i, v_j \in V\}$  is the set of arcs
  - ▶  $c_{ij}^+ = \text{Cost of plowing arc } (v_i, v_j)$
  - ▶  $c_{ij}^- = \text{Cost of deadheading arc } (v_i, v_j)$
  - ▶  $c_{ij}^+ \gg c_{ji}^+ \gg c_{ij}^- \geq c_{ji}^-$
- ❖ Goal: To construct  $k$  cycles, each beginning and ending at a depot, that collectively visit all streets in  $A$  at least twice (once for each side of the street) so that the length of the longest cycle is minimized
  - ▶ Plowing each street an arbitrary number of times (as opposed to twice) is easily handled



# Problem Statement

- ❖ Undirected arcs allow plowing against the flow of traffic
  - ▶ Practically, streets are closed for plowing
- ❖ Good solutions will attempt to plow downhill on both sides of the street
- ❖ If multiple plows traverse a street, there is a decision regarding which plows clear the street
  - ▶ Ad hoc assignment of clearing duties might make the longest route longer



# Solution Methodology

## Overview

- ❖ Construct a “solution framework” using the solution to the Downhill Postman Problem
  - Solution to the IP gives a number of traversals for each arc
  - Solution serves as a lower bound
- ❖ Use solution framework to construct an initial grand cycle using Fleury’s Algorithm
- ❖ Split grand cycle into  $k$  routes
- ❖ Perform local search on a grand cycle (not split grand cycle) to improve solution
  - Reinitialize and repeat local search



# Solution Methodology

## Initial Grand Cycle

- ❖ A grand cycle can be produced by the solution framework using Fleury's Algorithm
- ❖ This grand cycle is guaranteed to traverse (and hence plow) each street twice
- ❖ DPP formulation is modified to guarantee that a grand cycle can be split into  $k$  feasible routes
  - ▶ Require that the number of times a grand cycle leaves the depot is greater than  $k$



# Solution Methodology

## Grand Cycle Splitting

- ❖ A grand cycle is guaranteed to return to the depot  $k$  times
- ❖ Consider following example with 2 plows and unit costs:  
 $\{0,1,2,3,2,0,3,0,1,2,0\}$

Plow 1:

Plow 2:



# Solution Methodology

## Grand Cycle Splitting

- ❖ A grand cycle is guaranteed to return to the depot  $k$  times
- ❖ Consider following example with 2 plows and unit costs:

Plow 1:

Plow 2:



# Solution Methodology

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Plow 1:

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- ❖ A grand cycle is guaranteed to return to the depot  $k$  times
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Plow 2:



# Solution Methodology

## Grand Cycle Splitting

- ❖ A grand cycle is guaranteed to return to the depot  $k$  times
- ❖ Consider following example with 2 plows and unit costs:

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Plow 1:  $\{0,1,2,3,2,0\}$

Plow 2:  $\{0,3,0\}$



# Solution Methodology

## Grand Cycle Splitting

- ❖ A grand cycle is guaranteed to return to the depot  $k$  times
- ❖ Consider following example with 2 plows and unit costs:

Plow 1:  $\{0, 1, 2, 3, 2, 0\}$

Plow 2:  $\{0, 3, 0\} \{0, 1, 2, 0\}$



# Solution Methodology

## Grand Cycle Splitting

- ❖ A grand cycle is guaranteed to return to the depot  $k$  times
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# Solution Methodology

## Grand Cycle Splitting

- ❖ A grand cycle is guaranteed to return to the depot  $k$  times
- ❖ Consider following example with 2 plows and unit costs:

Plow 1:  $\{0, 1, 2, 3, 2, 0\}$

Plow 2:  $\{0, 3, 0, 1, 2, 0\}$



# Solution Methodology

## Local Search

- ❖ We explore the set of all grand cycles that obey the solution framework
- ❖ Search nearby grand cycles to find a better one
- ❖ Need to
  - ▶ Define nearby
  - ▶ Specify a fitness function - gives the quality of a grand cycle



# Solution Methodology

## Local Search - Neighborhood

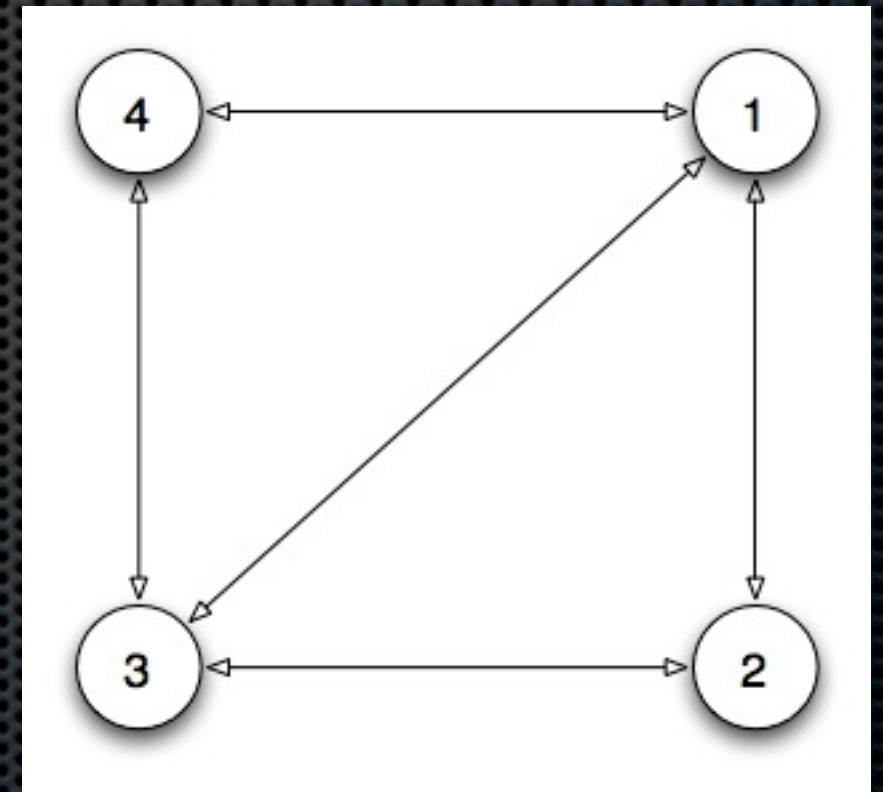
- ❖ Similar to the procedure presented in Plowing with Precedence (Dussault et al. ROUTE 2011)
- ❖ All grand cycles (which are Eulerian cycles) can be decomposed into sub-cycles
- ❖ Definition of neighborhood around a grand cycle  $s$ ,  $N(s)$ , is the set of all grand cycles that can be obtained by permuting sub-cycles of the grand cycle



# Solution Methodology

## Local Search - Neighborhood

{1,2,3,1,2,3,4,1,3,4,1}

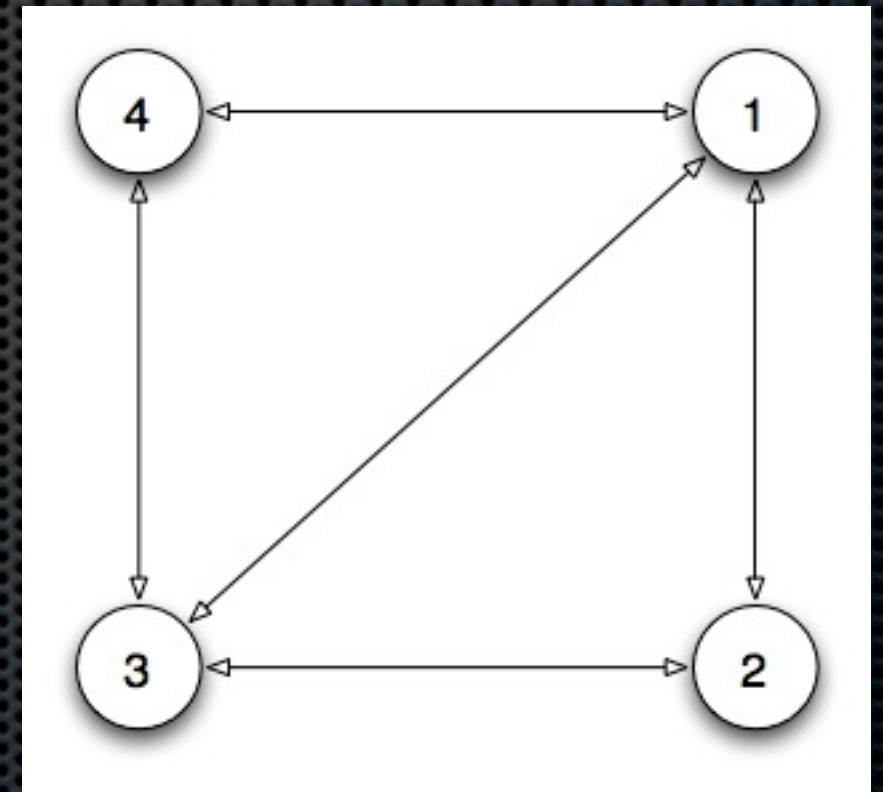




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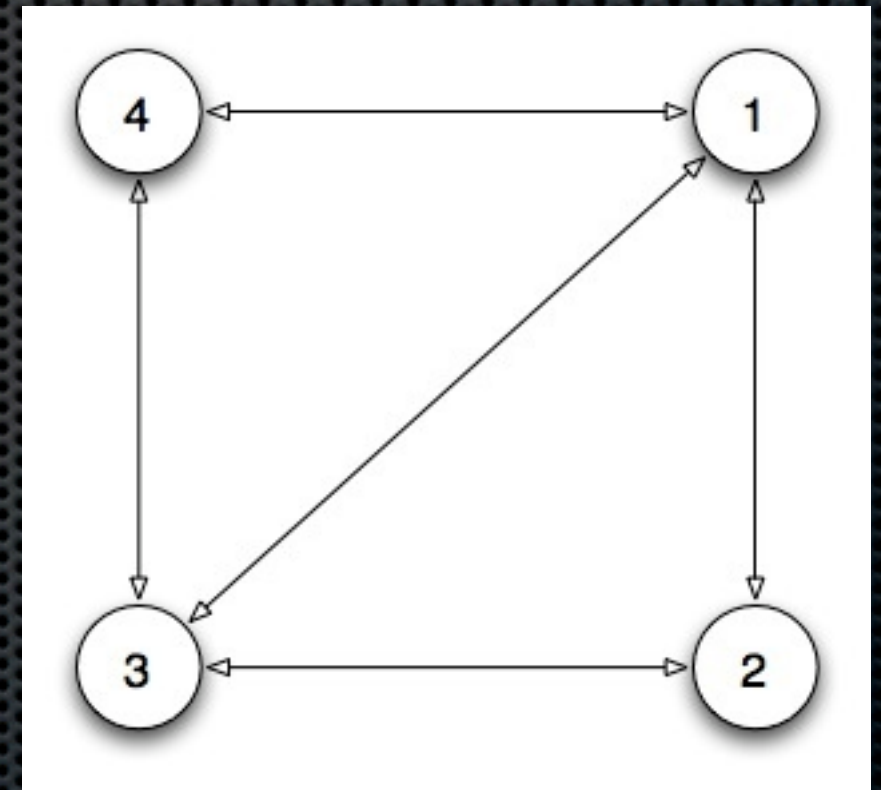




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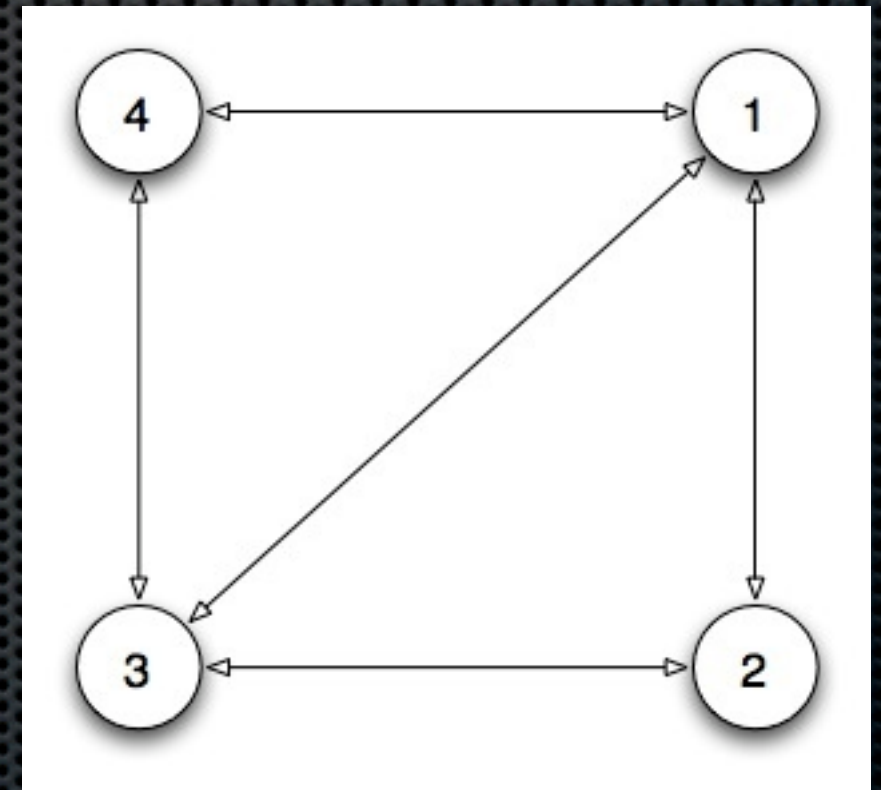




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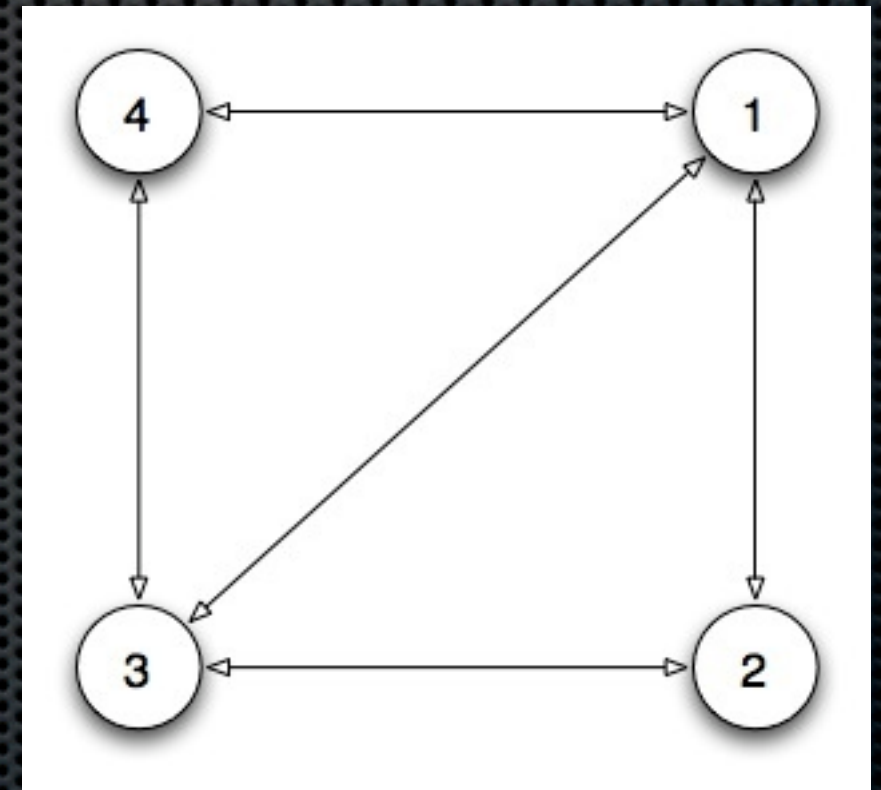


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{1,2,3,4,1,3,4,1,2,3,1}



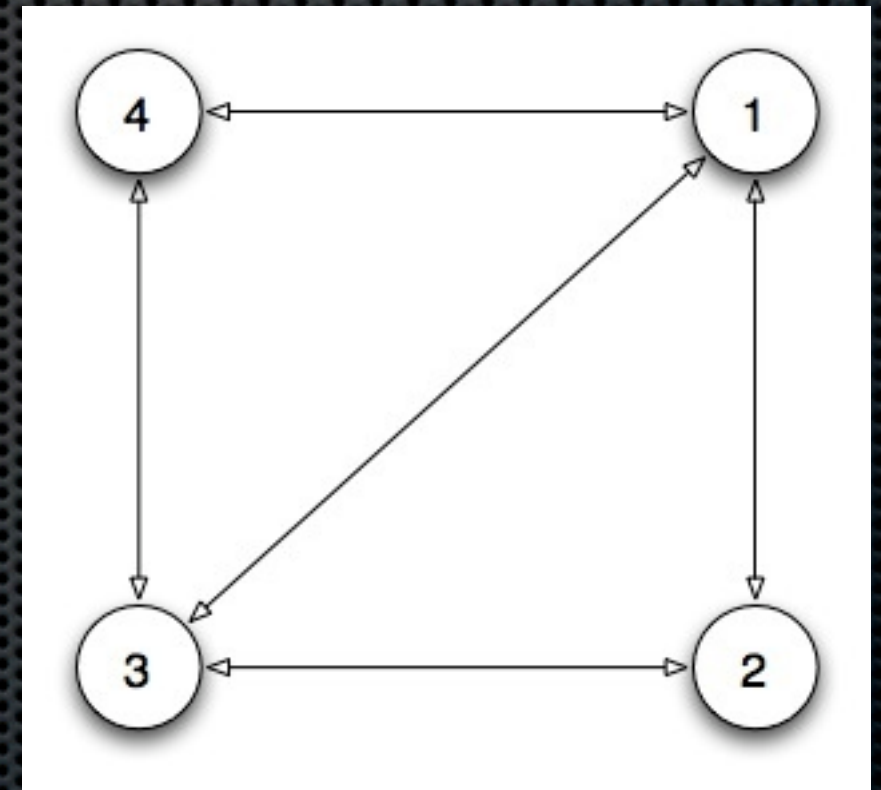


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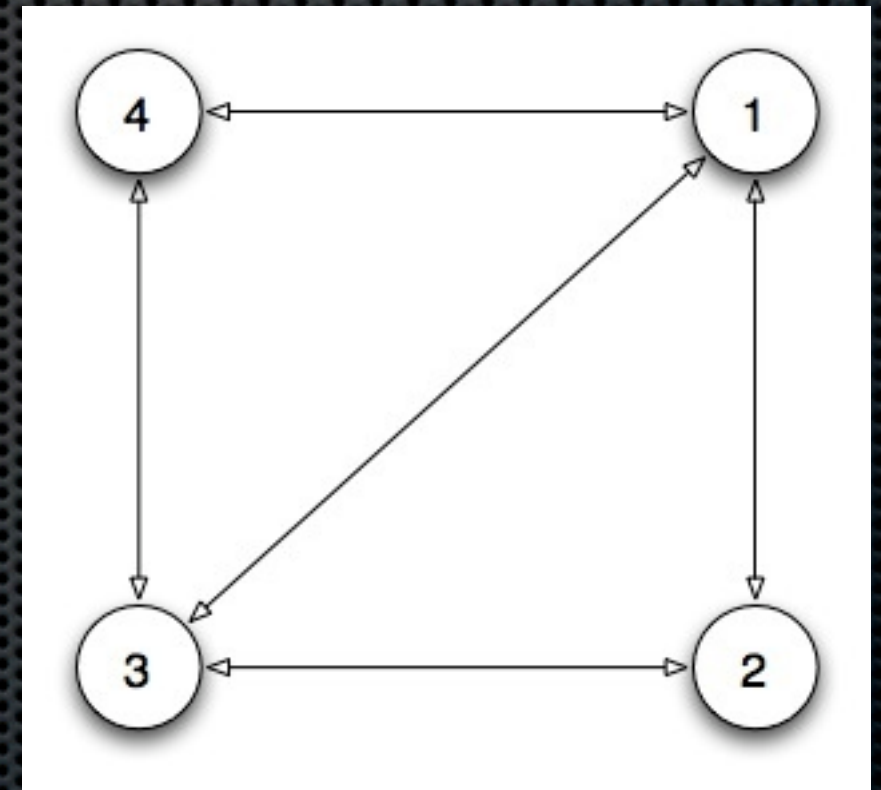


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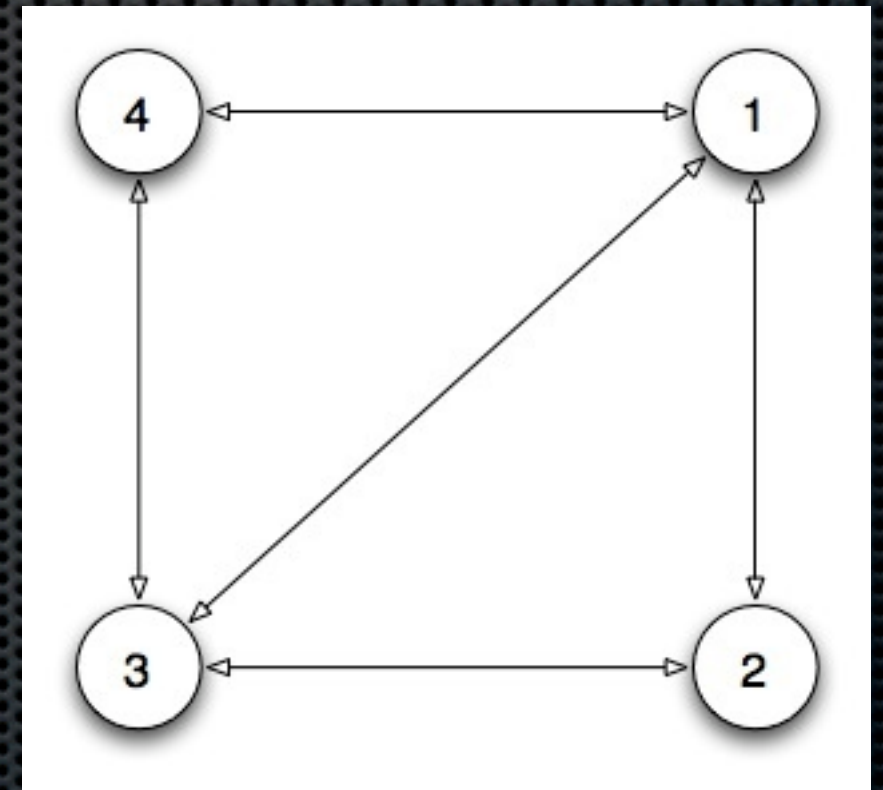


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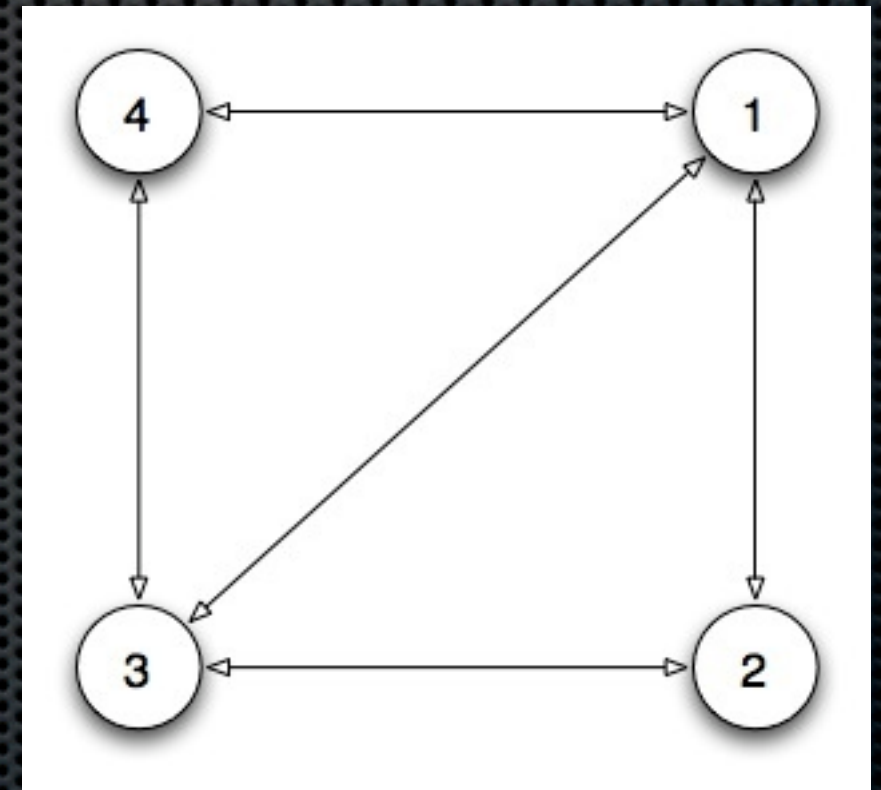


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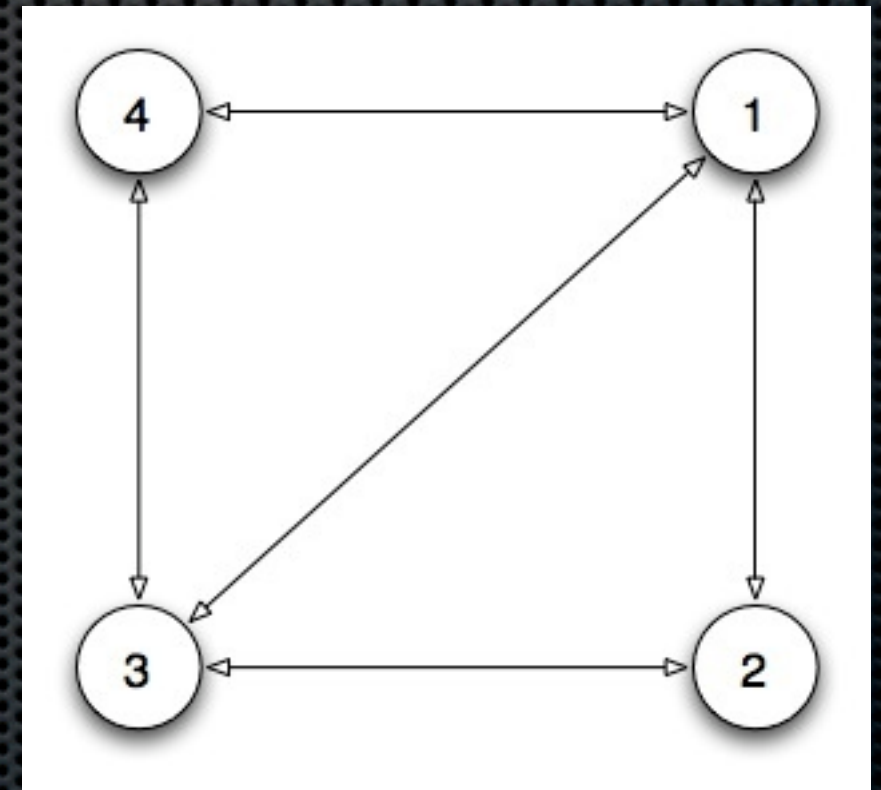


# Solution Methodology

## Local Search - Neighborhood

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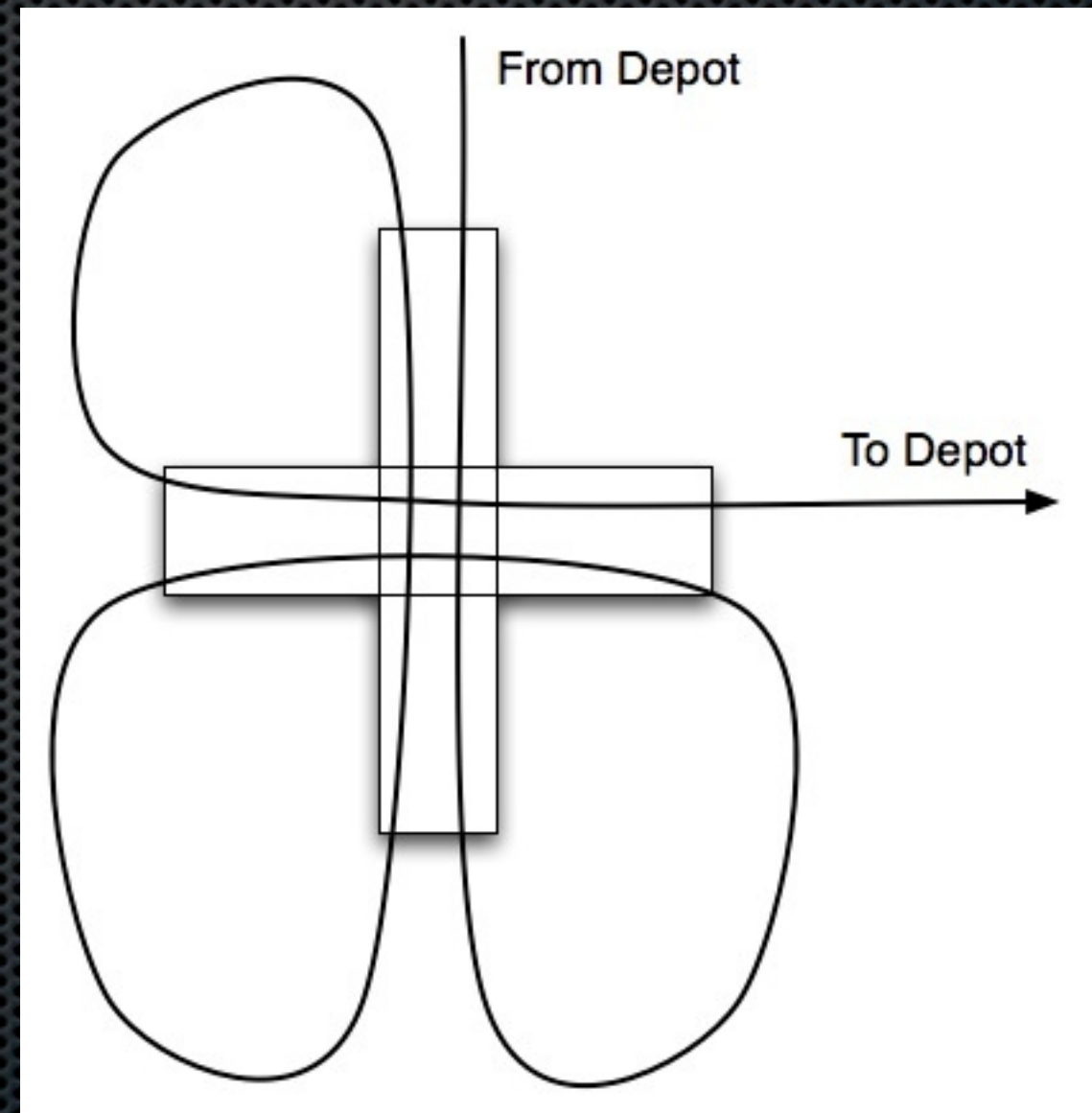




# Solution Methodology

## Local Search - Neighborhood

- ❖ The number of permutations is large:  $n!$  for  $n$  cycles
- ❖ To limit the size of the neighborhood, if  $n > 4$ , we limit the set of permutations to  $4! + n$  for linear growth
- ❖ Most intersections have four or fewer cycles





# Solution Methodology

## Local Search - Fitness

- ❖ For each arc, clearing duties must be assigned to the plows that traverse it
- ❖ Different grand cycles produce different routes when split, resulting in a different set of plows that traverse a given arc
- ❖ Optimal plowing assignment for a given split grand cycle is determined by using an IP
- ❖ IP is too computationally intensive for a local search
- ❖ Random allocation was found to produce near optimal solutions



# Solution Methodology

## Reinitialization

- ❖ Local search is deterministic and depends on the initial solution
- ❖ We reinitialize to produce new initial solutions for local search
- ❖ This is done by randomly permuting cycles around different nodes a large number of times
- ❖ Return the best solution produced in 15 runs of local search and reinitialization



# Solution Methodology

## Lower Bounds

- ❖ DPP in solution framework provides the length of an optimal route for a single plow
- ❖ The best scenario is for this optimal route to be split evenly amongst the  $k$  plows
- ❖ Computational results are compared against this lower bound
  - ▶ If we match the lower bound then we have obtained the optimal solution



# Computational Results

- ❖ We test our algorithm on 20 modified Windy Rural Postman Problems given in Corberan et al. (2007)
  - ▶ Remove Rural concept
  - ▶ Existing costs are interpreted as plowing costs
  - ▶ Randomly generate deadhead costs
- ❖ Instances are characterized by:
  - ▶ Number of nodes (64 to 196)
  - ▶ Number of arcs (116 to 316)
- ❖ Performed tests for 2, 3, 4, and 5 plows



# Computational Results

- ❖ Our heuristic performs very well
  - ▶ 0.09% average deviation from lower bound for 2 plows
  - ▶ 0.49% average deviation for 3 plows
  - ▶ 0.74% average deviation for 4 plows
  - ▶ 1.92% average deviation for 5 plows
  - ▶ Max deviation over all instances is 4.67%
- ❖ Optimal solution for at least 14 out of 80 total instances



# Conclusions

- ❖ Introduced the Min-Max  $k$ -MDPP variant of the WPP
- ❖ Our heuristic generates high-quality solutions
- ❖ Managerial implications
  - ▶ Lower bound, obtained by splitting a single optimal tour into  $k$  equal-length routes, is often tight
  - ▶ Route length and route balancing are *not* competing objectives
- ❖ Future work
  - ▶ Incorporate turn penalties
  - ▶ Incorporate precedence, where an unplowed street must be plowed before it can be deadheaded