

Statically Determinate Structures

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Part 3

Introduction

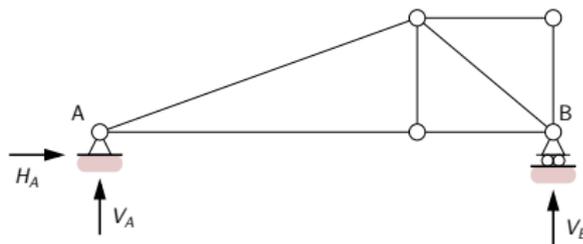
Need for Mathematical Test

Three cases to consider:

Test Structure A: Determinate.

Can compute:

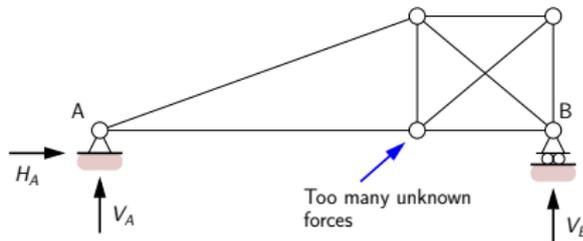
- Support reactions. ✓
- Member forces. ✓



Test Structure B: Indeterminate.

Can compute:

- Support reactions. ✓
- Member forces. ✗

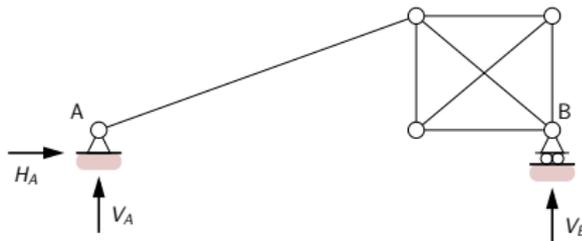


Need for Mathematical Test

Test Structure C: Unstable.

Can compute:

- Support reactions. **X**
- Member forces. **X**



Key Points:

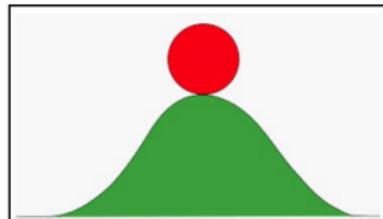
- Intuition on notions of determinacy **will not scale**. We need a mathematical test to classify structures.
- Initial inclination is to design for A and avoid B – it's complicated and probably won't work. **Unless, there are benefits** to B?

Stability

Stability

Stability of Dynamical Systems

Instability occurs when some of the system outputs (e.g., displacement) can increase without bounds. In structural analysis, **equilibrium of displacements** corresponds to a **minimum energy state**.

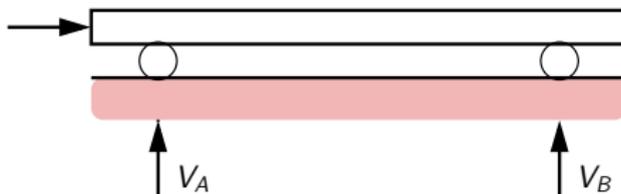


Instability of Structures:

- **External Instability.** When **support reactions** are either **concurrent forces about a point** or **parallel**.
- **Internal Instability.** When a mechanism exists.

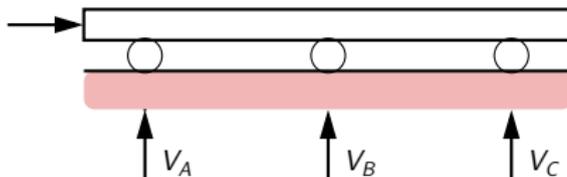
External Instability

Example 1: Reaction forces are parallel.



Three equations of equilibrium but only two reactions ($r < 3n$).

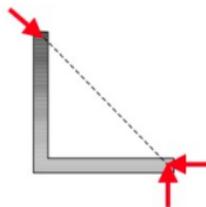
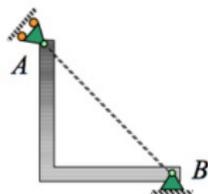
Example 2: Three parallel reaction forces



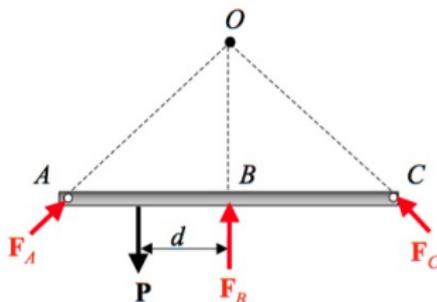
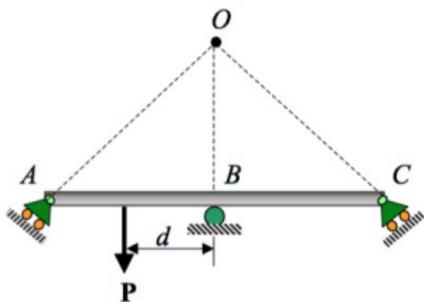
Three equations of equilibrium and three reactions ($r = 3n$). Still unstable.

External Instability

Example 3. Reaction forces are concurrent about point B.

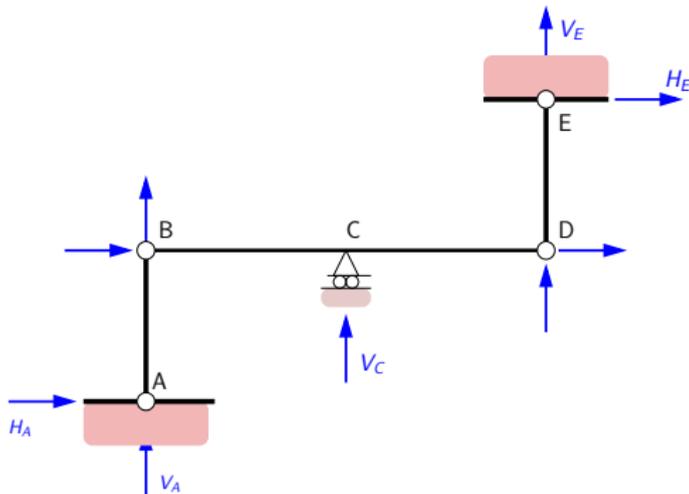


Example 4. Reaction forces are concurrent.



Internal Instability

Example 5. Structural configuration forms a pendulum mechanism.

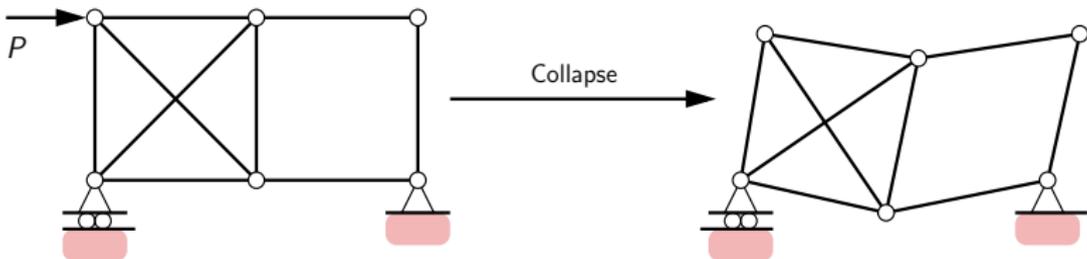


Three members: $n = 3$. No reactions $r = \{H_A, V_A, \dots, H_E\} = 9$.

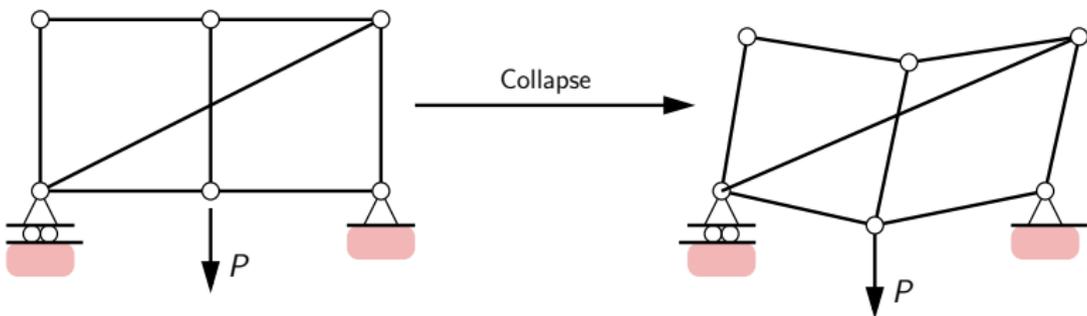
Test: $r - 3n = 0 \rightarrow$ **statically determinate**.

Internal Instability

Example 6: Internal Mechanism.



Example 7: Sometime internal mechanism are hard to identify.



Relating Stability to Linear Matrix Equations

Aside: If we compute the reactions and then systematically write the equations of equilibrium for each joint $\rightarrow 2j$ equations, which can be put in matrix form:

$$[A][X] = [B]. \quad (2)$$

Here,

- X is a vector of truss element forces.
- A is a matrix of geometry and boundary conditions.
- B is a vector of applied loads.

When the system is **statically determinate** we can write:

$$[A][X] = [B] \rightarrow [X] = [A^{-1}][B]. \quad (3)$$

Relating Stability to Linear Matrix Equations

Equations 3 only exist when $[A^{-1}]$ exists.

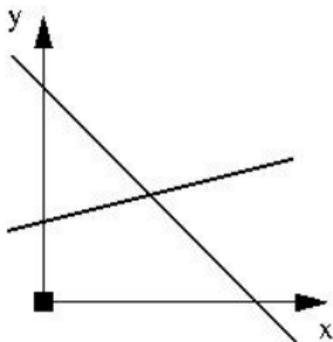
And this requires that the individual equations be **linearly independent**.

In Example 2, $[A^{-1}]$ does not exist because the reactions are co-linear, meaning that V_A can be written as a linear combination of V_B and V_C , i.e.,

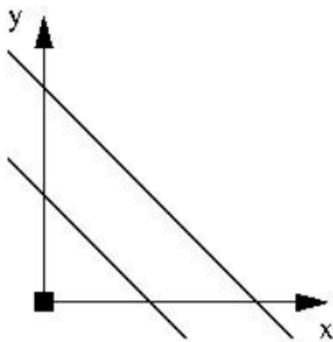
$$\sum F_y = 0 \rightarrow V_A + V_B + V_C = 0. \quad (4)$$

Equations in Two Dimensions

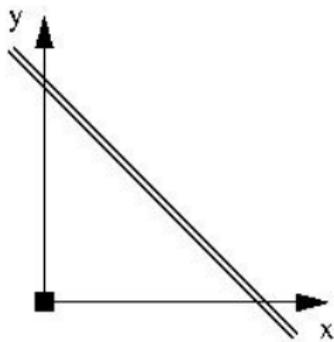
Three Types of Solutions:



Unique Solution



Inconsistent



Multiple Solutions

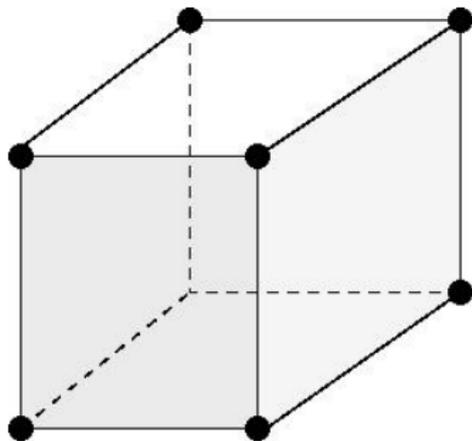
- **Unique solution** when two lines **meet at a point**.
- **No solutions** when two lines are **parallel but not overlapping**.
- **Multiple solutions** when two lines are **parallel and overlap**.

Equations in Three Dimensions

Also Three Types of Solutions:

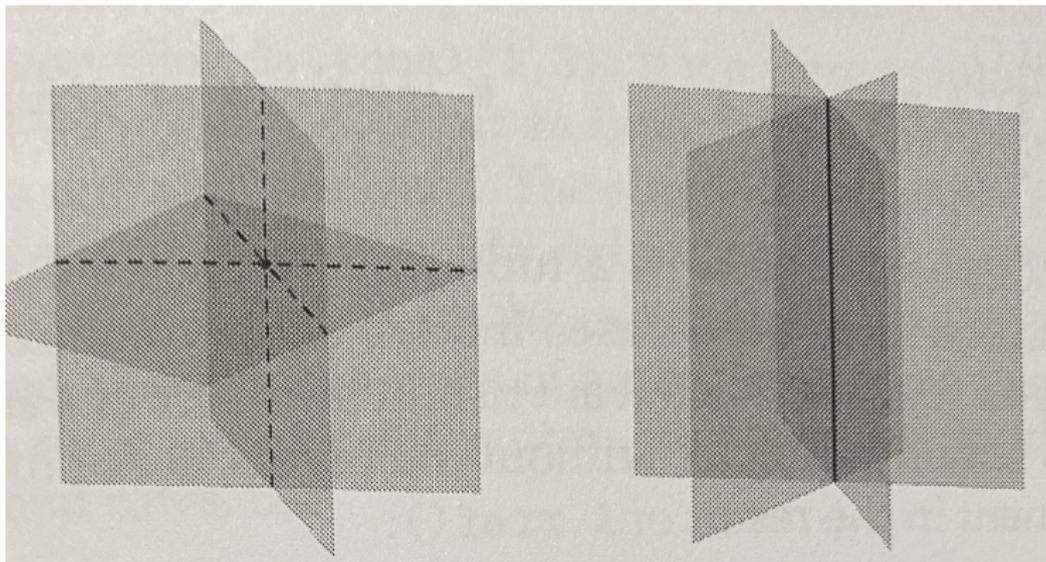
Each equation corresponds to a plane in three dimensions (e.g., think walls, floor and ceiling in a room).

- **Unique solution** when three planes intersect at a corner point.
- **Multiple solutions** where three planes overlap or meet along a common line.
- **No solutions** when three planes are parallel, but distinct, or pairs of planes that intersect along a line (or lines).



Equations in Three Dimensions

One Solution/Infinite Solutions:



Equations in Three Dimensions

No Solutions:

